

# Big Data Analysis of Ionosphere Disturbances using Deep Autoencoder and Dense Network

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**Abstract:** The ionosphere plays a critical role in the functioning of the atmosphere and the planet. Fluctuations and some anomalies in the ionosphere occur as a result of solar flares caused by coronal mass ejections, seismic motions, and geomagnetic activity. The Total electron content (TEC) of the ionosphere is the most important metric for studying its morphology. The purpose of this article is to examine the relationships that exist between earthquakes and TEC data. In order to accomplish this, we present a classification method for the ionosphere's TEC data that is based on earthquakes. Deep autoencoder techniques are used for the feature extraction from TEC data. The features that were obtained were fed into dense neural networks, which are used to perform classification. In order to assess the suggested classification model, the results of the classification model are compared to the results of the LDA (Linear Discriminant Analysis) classifier model. The research results show that the suggested model enhances the accuracy of differentiating earthquakes by around 0.94, making it a useful tool for identifying ionospheric disturbances in terms of earthquakes.

## 1 INTRODUCTION


As it slowly rises above the ground, it encounters an atmospheric taxonomy in terms of height, and some of the atmospheric layers have several key properties. The ionosphere layer is one of the most significant layers in the atmosphere, with numerous unique properties. These characteristics help to identify a wide range of events, such as solar flares and earthquakes. The ionosphere layer, which extends from 48 km to 960 km and is ionized into a plasma phase.


Total Electron Content is a primary quantifiable statistic that identifies an ionosphere property (TEC). TEC is a powerful tool for studying the ionosphere's morphology. TEC is described as the line integral of electron density along a ray path or a metric of total electrons across a ray path in the literature. TEC is measured in TECUs (TEC Units), with 1 TECU equaling 1016 *electron/m*<sup>2</sup> as described by (Arikan et al., 2003)(Nayir et al., 2007). Measuring and monitoring TEC Values can describe the ionosphere layer's


variations and turbulences effectively and efficiently.


According to (Nayir et al., 2007), the Global Positioning System (GPS) has provided a cost-effective approach in estimating and analyzing TEC and monitoring the ionospheric layer disruptions across a significant fraction of the global continent during the last several decades. The temporal and geographical variability of the ionosphere layer is closely related to the earth's daily (every day) and yearly rotation, as well as the pattern of magnetic field lines of the geomagnetic dipole. Even when there are no geomagnetic events, the earth's magnetic field is not silent, as (Rishbeth and Garriott, 1969) describes. Fluctuations in geomagnetic and solar activity, as well as seismicity, affect the ionosphere's quiet circumstances. As a result, these repercussions may produce changes in parameters such as earthquakes.

In summation, this paper offers a model based on deep learning approaches for interpreting the link between earthquakes and ionosphere perturbations, with two sub-tasks of feature extraction and classification. The model's initial phase focuses on using Deep Autoencoders and unsupervised learning approaches to extract features from TEC data. The suggested classification using deep dense neural networks based on the supervised learning approach is the second step.

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The following is the rest of the story. The related works on Total Electron Content variation produced by magnetic and earthquake disruptions in the ionosphere layer are discussed in Section 2. The ionospheric dataset and preprocessing stages for the proposed models are presented in section 3. In Section 4, we show our classification model for ionospheric data. Sections 5 and 6, respectively, cover the evaluation technique and outcomes. The final comments and future studies are found in section 7.

## 2 RELATED WORK

The relevant studies for observing ionospheric perturbations are presented in this section. Geomagnetic events such as storms and earthquakes may cause severe disruptions in the electron density distribution. The seismo-ionospheric anomalies as stated by (Pulinets et al., 2018; Tao et al., 2017) have been investigated using satellite-based observations from GPS stations.

The ionospheric disruption and storms may cause severe turbulence in the ionosphere's TEC values was explored by (Biqiang et al., 2007; Trigunait et al., 2004). Furthermore, earthquakes and seismic activity, according to (Pulinets et al., 2003), might produce changes in electromagnetic signals and the chemical properties of the atmosphere in the troposphere, and ionosphere.

Many studies, such as those cited in (Liu et al., 2004; Le et al., 2011; Liu et al., 2006; Liu et al., 2010), concentrate on statistical evaluations of the empirical association between ionospheric based abnormalities and earthquakes. For example, in (Liu et al., 2004), the authors looked at the TEC associated with 20 strong (Magnitude  $\geq 6.0$ ) earthquakes in Taiwan over the course of four years (1999–2002). During the other quiet days, they discover irregularities that show the TEC value is decreasing five days before the earthquakes. Furthermore, (Le et al., 2011) shows the relationship among TEC-based ionospheric abnormalities and severe earthquakes (Magnitude  $\geq 6.0$ ) throughout a nine-year period (2002–2010). They also verified that earthquakes with a strength of  $\geq 7.0$  and a depth of  $\leq 20$  km cause a high percentage of anomalies in the ionosphere.

(Ulukavak and Yalcinkaya, 2017; Pundhir et al., 2017; Oikonomou et al., 2016) have recently observed aberrant ionospheric layer changes based on TEC values measured days and hours before severe or large earthquakes. The data for the TEC was collected from a GPS station in the earthquake zone. There are some questions concerning how to create such

anomalies near the epicenter of powerful earthquakes. According to (Tariq et al., 2019), and (Shah and Jin, 2015), there are direct links between ionosphere variety and earthquakes. TEC values acquired from the GPS receiver varied and rose before Magnitude  $\geq 6.0$  earthquakes occurred throughout the period 1998–2014. According to the authors of (Le et al., 2011), ionospheric TEC abnormalities were used to categorize severe and strong earthquakes based on their magnitudes.

We plan to extract significant aspects of earthquakes using TEC values in the ionosphere layer, and then identify earthquake days in the target station zone, based on previous research in this area. Our main emphasis is on extracting characteristics from earthquakes and classifying them using TEC data from the ionospheric. We are not focusing on forecasting earthquakes in previous days at this time, and our study is focused on TEC changes during moderate and severe earthquakes.

## 3 DATASET AND DATA PREPARATION

The dataset relating to earthquakes and GPS station TEC values was introduced in this part. The procedures for preparing the dataset are also described.

### 3.1 Dataset

TEC values derived from GPS stations, as described in Section 2, are a valuable approach to assessing the ionospheric reaction to earthquakes and solar storms. The ionospheric variability is investigated using TEC data collected from GPS stations (Dual-Frequency GPS receiver). TEC data was acquired from two GPS sites for this study. This information was gathered from the IONOLAB group (Hacettepe University of IONOLAB is an organization of electrical engineers to investigate hurdles of the ionosphere.)<sup>1</sup> The first station is placed at coordinates ( $Lat : -20.15, Lon : -70.13$ ) Figure 1 shows the city of Iquique in Chile. The second station is located at coordinates ( $Lat : -20.85, Lon : 117.1$ ) Figure 1 depicts Karratha, a town in Western Australia's Pilbara area. The earthquake data is gathered by the (United States Geological Survey of Earthquakes)<sup>2</sup>.

This research examines ionospheric fluctuation across moderate and severe earthquake occurrences of varied magnitudes from 2012 to 2019. The data

<sup>1</sup> Available at <http://ionolab.org/>

<sup>2</sup> Available at <https://earthquake.usgs.gov/>

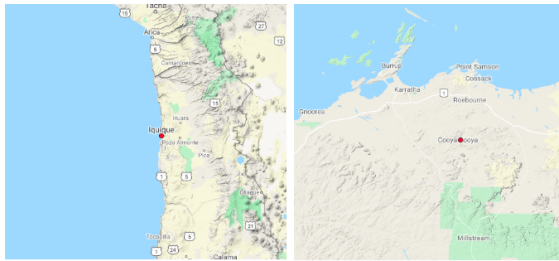


Figure 1: The Iquique (Chile) and station and the Karratha (Western Australia) station.



Figure 2: The Iquique and Karratha stations located in the same latitude from the two hemispheres of the east and west of the earth.

for each station was gathered between 2012 and 2019. The data was divided day by day with 2880 TEC samples in a day. The stations are positioned in the same latitude from the east and west hemispheres of the earth, as shown in Figure 2. The Chile area is known to powerful and severe earthquakes, however the Karratha region is rather earthquake-free.

### 3.2 Data Preparation

The reliability of the input dataset is crucial in deep learning ideas because there is a direct link between the reliability of the input data and the effectiveness of the trained model. Data preprocessing includes data tuning procedures that transform raw input data into a usable format. Ionospheric TEC data is often inadequate, inconsistent, and prone to many inaccuracies. In this study data preprocessing is divided into three stages: cleaning, transformation, and reduction.

The cleaning stage aims to delete missing values and perform regressions using previous and later observations samples to smooth noisy values since raw TEC data on certain days has missing and noisy values. Furthermore, the gathered data is transformed into suitable mining formats. TEC data are scaled to a specific defined range to accomplish the normalization (0,1.0). A day’s value of TEC data contains of 2800 samples. Learning enormous volumes of input data with various characteristics in data mining makes analysis problematic or impossible, and the training process might take a long period of time. Data Reduction is a collection of approaches for reducing the number of input samples in a dataset without harming the integrity of the original data. A single day’s

data is reduced from 2800 to 95 by sampling TEC values every fifteen minutes. The ionospheric and EQs(earthquakes) datasets are detailedly described in Table 1. All of the earthquakes were recorded at stations within a 250-kilometer radius.

The gathered data is shown in the table as well as information such as the ratio of the train and test sets.

Table 1: Detailed information of the dataset.

Dataset Characteristics	Value
Day count in uncleaned Dataset	2922
Day count in cleaned Dataset	2571
Train-Test Ratio	80%-20%
Total EQs $\geq 4.5$	141
Total EQs $\geq 5.0$	91
Day count in Trainset	2057
Day count in Testset	514
EQs $\geq 4.5$ in Trainset	113
EQs $\geq 5.0$ in Trainset	73
EQs $\geq 4.5$ in Testset	28
EQs $\geq 5.0$ in Testset	18

Solar flares and other cosmological event components have been shown to influence the ionosphere in early research. Xray fluxes are increased during solar flares, and this has been recognized as the source of increased ionization in the ionosphere. Although, this research focuses on ionospheric changes and TEC fluctuations during various earthquakes, it is necessary to diminish the impact of solar flares and other cosmological events in order to identify earthquakes and geomagnetic activity more accurately.

As previously stated, the stations are placed at the same latitude as the earth’s east and west hemispheres. Because solar flares and other comparable cosmic occurrences influence both the east and west hemispheres of the planet, the similarity between two places may be estimated. Solar flares and other such cosmic occurrences are shown by anomalies on the same day in both the stations. It is possible that the related stations contain the same irregularities as a result of solar flares and other cosmic phenomena. To reduce the impact of these abnormalities, it is necessary to compute the similarity between the stations.

The similarity among coincident days at each region in the dataset is calculated for this objective. Because of the structure of the dataset, the similarity between coinciding days at each station is estimated using cosine similarity. Cosine similarity is a measure that compares two non-zero vectors and is defined by the cosine of their angles. Equation 1 is used to compute the cosine similarity.

$$\cos(x,y) = \frac{x \cdot y}{\|x\| \|y\|} = \frac{\sum_{i=1}^n x_i y_i}{\sqrt{\sum_{i=1}^n x_i^2} \sqrt{\sum_{i=1}^n y_i^2}} \quad (1)$$

Where  $x$  and  $y$  are the TEC data vectors for each day in the stations.

## 4 METHOD

The framework of the suggested model is given in this section. A broad overview of the suggested model is shown in Figure reffig:model. Deep neural networks are utilized because of the vast quantity of TEC data associated with each station. Because Deep Learning's core benefit is the study and learning of huge volumes of supervised and unsupervised data, it's particularly useful for Big Data Analytics, where data is mostly unlabeled. Unsupervised learning methods such as Deep Autoencoders and deep dense networks are employed in the proposed model.

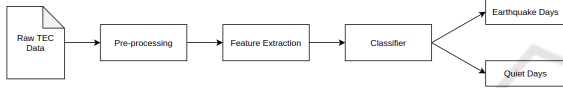


Figure 3: Overview of the proposed model.

### 4.1 Feature Extraction

The main feature extraction techniques presented by (Khalid et al., 2014) are based on projection and data mapping from a complicated input space with many dimensions while minimizing data loss. (Demšara et al., 2013; Sharma and Paliwal, 2015) discuss two prominent projection methods: Principal Component Analysis (PCA) and Linear Discriminant Analysis (LDA). The PCA technique projects the input data into its primary directions by maximizing variance. This technique is classified as an unsupervised technique. The LDA, on the other hand, optimizes discriminating data from input classes in order to produce a linear output space. The LDA technique is characterized as a supervised learning technique. The fundamental difficulty with the techniques outlined is linear projection. (Lopez-Paz et al., 2014) propose non-linear kernel functions as a solution to this problem.

Due to the large dimensionality of ionospheric TEC data, lowering dimensionality to create a compressed feature set is considered an important step in the feature extraction process. Traditional machine learning algorithms should theoretically be capable of operating on any number of characteristics. These models with large-dimensional datasets are exposed to issues like as over-fitting of the training set, excessive computational cost, and the dimensionality curse. Autoencoders use neural networks to reduce the input dimensions, with the goal of minimizing reconstruc-

tion loss. As a result, adding hidden layers to the autoencoders causes the dimension reduction process to work properly. Deep Autoencoders have been shown to be successful in detecting non-linear features in a variety of scenarios.

Deep Autoencoders are multi-layer neural networks that produce the desired output from the input. Within a pair of encoding and decoding steps, an autoencoder learns a map from the input to itself. For feature learning, autoencoders have recently directed to unsupervised approaches. It attempts to learn a condensed description of the input while maintaining the most critical data.

$$\bar{X} = Dcr(Enc(X)) \quad (2)$$

Where  $X$  represents the input TEC data,  $Enc$  represents an encoding map from the TEC data to the hidden layer,  $Dcr$  represents a decoding map function from the code layer to the output layer, and  $\bar{X}$  represents the recovered a similar version of the TEC data in Equation 2. The goal is to teach  $Enc$  and  $Dcr$  to reduce the difference between  $X$  and  $\bar{X}$  as much as possible. To reduce the error of reconstruction of input from hidden code nodes, the encoder and decoder functions ( $Enc$  and  $Dcr$ ) are trained concurrently. An autoencoder might be seen as a possible reason for the optimization issues.

$$\min_{Dcr, Enc} \| X - Dcr(Enc(X)) \| \quad (3)$$

In Equation 3,  $\| \cdot \|$  is commonly considered to be the  $\ell_2$ -norm.

The input, encoder, decoder, and output layers are shown in Figure 4. The autoencoder may output a more compact vector as input vector if the reconstruction error is reduced. Sigmoid and ReLU, as defined in Equations 4 and 5, are employed in this study.

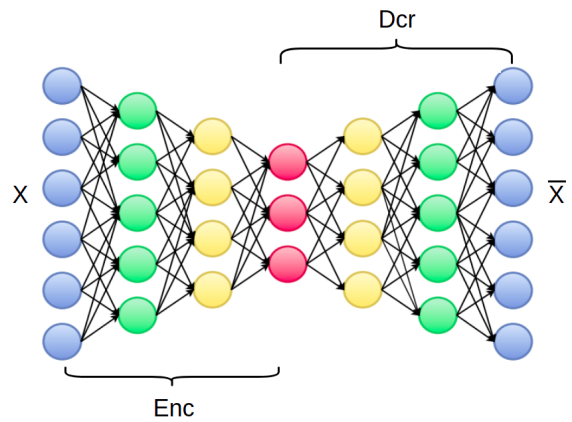


Figure 4: A Deep Autoencoder with five layers.



$$\varphi(z) = \frac{1}{1 + e^{-z}} \quad (4)$$

$$R(z) = \max(0, z) \quad (5)$$

The output of the  $x^{th}$  node in the  $i^{th}$  layer is obtained sequentially from the output of the prior nodes in the previous layer as Equation 6 where  $bias_x^i$  is bias scalar and  $N_i$  represents the number of nodes in the  $i^{th}$  layer,  $w_{x,n}^i$  is the weights which connect the  $x^{th}$  node in the  $i^{th}$  layer to the  $n^{th}$  node in previous layer.

$$O_x^i = \varphi(net_x^i) = \varphi\left(\sum_{n=1}^{N_{i-1}} w_{x,n}^i O_n^{(i-1)} + bias_x^i\right) \quad (6)$$

Increasing the number of layers improves the capacity to learn more complex patterns. The matrix of all weights  $W$  is changed to minimize the mean square error over the training set, as shown in Equation.

$$\varepsilon = \sum_{i=1}^N \|X - Dcr(Enc(X))\|^2 \quad (7)$$

## 4.2 Classification Method

After the feature extraction, these features must be classified. Several different classification methods have been used in the literature. Deep neural networks are often used in combination with softmax regression. It is possible to combine the classifier and encoder functions for this purpose. Logistic regression is induced by softmax (multinomial logistic) regression. It uses Equation 8 to calculate the probability of the  $i^{th}$  class.

$$Prob_i = Prob(i|I) = \frac{e^{w_i I}}{\sum_{n=1}^N e^{w_n I}} \quad i = 1, \dots, N \quad (8)$$

Where  $w_i$  are the training weights for the  $i^{th}$  class and  $I$  is the classifier's input. The classification is carried out by comparing  $Prob_i$ 's. The softmax may simply be used with the encoder function to form the network's deep structure.

Figure 5 shows a block diagram of the suggested autoencoders. It's a combined model that includes both unsupervised and supervised learning. The encoder that was learned in the feature extraction step is used for unsupervised learning, while the supervised model is a dense softmax classifier.

By decreasing the error rate and employing Equation 7, features at hidden layer two are reduced and compressed. These characteristics are then supplied

to the next autoencoder layer, and the features from layer three (code layer) are fed to the softmax classifier, which uses labeled data to do classification. During the feature extraction step, the layers of the Deep Autoencoder are trained individually. As a result, the features are learnt unsupervised, whereas classification is done supervised.

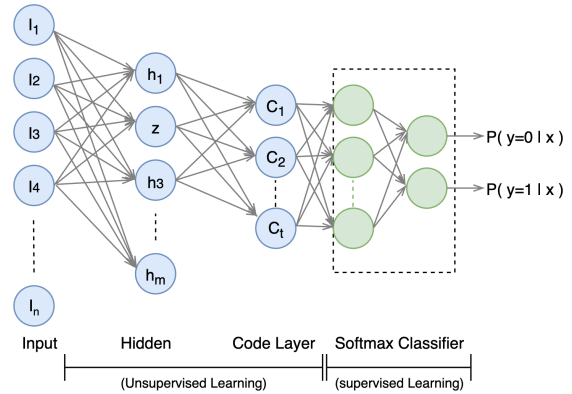


Figure 5: The structure of the proposed model.

## 5 EVALUATION METHODOLOGY

By using learning parameters and evaluation metrics discussed in this section, you will be able to better grasp the metrics necessary to conduct a quality assessment.

As previously noted in Section 4; the TEC values are split by days and classified using the suggested model in the technique section, as previously described. The suggested model is broken into two sub-models, which are described below. The Deep Autoencoder is used to extract the features from TEC values in terms of days in the first sub-model. When the feature extraction phase is trained, it provides a low-dimensional form that encodes a meaningful topological structure of TEC characteristics in order to reconstruct the high-dimensional input. The second kind of dense network is a softmax dense network, which is pinned to the encoder and is used to do classification jobs. The hidden layers of the classifier are bound by the earthquake labels in the data. By combining the autoencoder with the classifier, the networks are trained.

When evaluating the performance of a model, it is necessary to use model assessment measures. The model determines which evaluation measures are used and which ones are not. As a result of the nature of the data and the suggested model, we employ the accuracy, precision, and recall of the model as perfor-

mance indicators. The accuracy of classification models is a frequent assessment parameter in this context. It is defined as the ratio of the number of correctly identified earthquakes to the total number of correctly classified days. Precision defined as the ratio of accurately identified earthquake days to the total number of days labeled as earthquake days in a year. The recall is a measure of how well our model performs in properly detecting earthquake days when compared to the total number of earthquake days. Depending on the data and requirements of the classification model, it may be necessary to prioritize precision and recall over the other. The nature of this study is the categorization of ionosphere disturbances based on earthquakes. In addition to earthquakes, ionospheric disturbances may influence other types of phenomena. Therefore, the number of false positives may be acceptable in the classification model.

A relationship or trade-off exists between precision and recall values in conventional classification models. The term "F1-score" refers to a measure of test set efficiency that takes into account both precision and recall while calculating the score. The F1-score is the harmonic average of precision and recall in Equation 9.

$$F1\text{-score} = 2 * \frac{\text{precision} * \text{recall}}{\text{precision} + \text{recall}} \quad (9)$$

It is possible to forecast the performance of machine learning algorithms by dividing a dataset into two parts: the train set and the test set. As shown in Table 1, the dataset has been divided into two groups: train sets and test sets, with an 80-20 split ratio between the two groups. It seems that there is no appropriate ratio between the number of quiet days and the number of earthquake days in the dataset.

As a consequence, there are only 141 earthquakes with magnitudes greater than or equal to 4.5 between 2012 and 2019. A limited number of earthquake classes are provided in the classification model. With just a limited number of earthquake classes included in the classification model, this results in an issue known as imbalanced classification, which is a difficulty in the model. When a class is relatively rare in comparison to other classes, the class imbalance issue emerges. There have been several approaches developed for unbalanced classification by (Makki et al., 2019; Lin et al., 2020), and some beneficial findings have been published in the literature.

In order to deal with the issue of unbalanced classes, K-fold cross-validation has been used. In the k-fold cross-validation approach, model performance is evaluated by splitting the data into  $n$  equal folds and then measuring the performance of the model on each

fold. This technique is similar to that of the repeated random sampling technique. In an unbalanced class distribution situation, the proper use of k-fold cross-validation needs the usage of stratified k-fold cross-validation, which is described below. In particular, it has the ability to divide arbitrarily in such a manner that the same class distribution is maintained in each subset. Testing is carried out using a ten-fold cross-validation strategy for the purpose of analyzing the days. In order to make each fold a suitable sample of the original dataset, 10 equal folds are randomly split into the original dataset.

To determine the significance of the suggested combination model, we employed an LDA (Linear Discriminant Analysis) classifier based on the compression of the features, similar to the work done by the authors (Kim et al., 2011; Tharwat et al., 2017). Linear discriminant analysis is implemented with the aid of a max function  $M$ , which serves as a classification rule.

$$f_i(X) = \frac{1}{(2p)^{\frac{1}{2}} |\Sigma|^{\frac{1}{2}}} \exp \left[ -\frac{1}{2} (X - \mu_i)^T \Sigma^{-1} (X - \mu_i) \right] \quad (10)$$

$$M(X) = X^T \sum \mu_i - \frac{1}{2} \mu_i^T \sum \mu_i + \log(p_i) \quad (11)$$

$f_i(X)$  represents the conditional density of  $X$  in class  $i$ , where  $p_i$  is the probability of class  $i$ . If the vector of features  $X$  is variable and distributed with a mean vector  $\mu_i$  and a shared covariance matrix  $\Sigma$ , then the solution is as follows: Once  $f_i(X)$  has been determined, as indicated in Equation 10,  $f_i(X)$  may be calculated. Calculation of the discriminant function  $M(X)$  is done using the Bayes rule, which results in Equation 11.

## 6 EVALUATION RESULTS

The performance of our suggested model, DAEclass (Deep Autoencoder Classifier), as well as the LDA classifier model, is assessed using the evaluation approach stated in Section 5. Specifically, the purpose of this section is to evaluate and analyze the performance metrics of both the suggested classification model and the LDA classifier.

Table 2 gives the percentage of performance measures such as accuracy, recall, precision, and F1-score for the proposed DAEclass model and LDA classifier based on two datasets. On the first and second

Table 2: Comparison of DAEclass and LDA classification models using performance metrics.

Model	Accuracy	Precision	Recall	F1-Score
DAEclass-EQs $\geq$ 4.5	0.93	0.56	0.75	0.64
LDA-EQs $\geq$ 4.5	0.89	0.30	0.63	0.40
DAEclass-EQs $\geq$ 5.0	0.96	0.61	0.83	0.70
LDA-EQs $\geq$ 5.0	0.94	0.35	0.71	0.47

rows, you can see a comparison between the proposed model and the LDA classifier model, which is based on all earthquakes with a magnetite  $\geq 4.5$  value in their dataset. It is undeniable that the suggested model outperforms the LDA classifier across the board in all criteria. The suggested model improved its precision and recall over the LDA classifier. The fluctuations in the ionosphere layer are a reflection of all cosmic and seismic activity. Precision is lower than recall and accuracy because the false positive count is high owing to the unbalanced classes in the dataset. The final two rows compare the proposed model to the LDA model, which is based on more powerful earthquakes (magnetite-EQs  $\geq 5.0$ ) than those in the first two rows. Because severe earthquakes have a greater impact on the ionosphere than mild earthquakes, they are more clearly characterized. The performance difference between the two models is lower than the performance gap between the two models on the EQs  $\geq 4.5$  dataset.

EQs  $\geq 4.5$  and EQs  $\geq 5.0$  datasets are represented by the bar chart in Figure 6, which shows the comparison of performance measures between two models. It can be observed in Figure 6 (A) that the accuracy of the DAEclass increases marginally in the two datasets that have been described. Precision and recall measures are helpful indicators of classification performance when the classes are unequally distributed over the dataset. As a consequence of earthquakes and false alarms, precision is a measure of classification result relevance, while recall is the classifier’s capacity to locate all of the earthquake days. The performance of the DAEclass classifier is more stable when compared to the LDA classifier, as shown by the comparison of the two databases. Overall, the DAEclass technique significantly improves precision, recall, and F1-score, as shown in Figure 6 (B)(C)(D). This results in a greater extent of better performance in the dataset EQs  $\geq 4.5$  than the dataset EQs  $\geq 5.0$ , and the DAEclass is more trustworthy in all earthquakes as a result of this.

For the purpose of comparing multiple classifiers, it might be advantageous to summarize the performance of each classifier into a single metric. The Receiver Operating Characteristic (ROC) curve is a commonly used and standard metric for comparing various classification models. It is calculated by com-

puting the area under the curve. The relationship between the true-positive rate and the false-positive rate was shown by the receiver operating characteristic curve (ROC curve).

Classifiers that produce curves that are closer to the top-left corner of the screen demonstrate more dependable performance. The ROC curves for the DAEclass and LDA classifier models, which were constructed using two datasets, are shown in Figure 7. Because the ROC curves associated with the DAEclass are positioned increasingly closer to the upper left angle in ROC space, the DAEclass has a gradually more significant discriminant ability for earthquake classification as time goes on. As shown in the image, the DAEclass and the LDA classifier may be visually compared at the same time, with the results indicating that the DAEclass is more efficient than the LDA classifier in this case.

In order to evaluate the intrinsic performance of classification models, the AUC (area under the curve) is an effective and integrated measure of the true-positive and false-positive rates. In other words, the bigger AUC indicates that the diagnostic test is ideal for distinguishing between earthquake and quiet days. The outputs are shown in Table 3, which shows the AUC values of the model for each of the datasets. The AUC in the DAEclass-EQs  $\geq 4.5$  classifier is 0.89, while the AUC in the LDA-EQs  $\geq 4.5$  classifier is 0.79, indicating a significant increase in the ROC metric in both classifiers. On the dataset EQs  $\geq 5.0$ , the AUC values for the DAEclass technique are somewhat higher than those for the LDA classifier, ranging from 0.85 to 0.91.

Table 3: AUC values for the DAEclass and the LDA classifier.

Model	ROC AUC
DAEclass-EQs $\geq$ 4.5	0.892
LDA-EQs $\geq$ 4.5	0.794
DAEclass-EQs $\geq$ 5.0	0.914
LDA-EQs $\geq$ 5.0	0.856

A statistical test is used to examine the suggested model in further detail, in order to determine its degree of significance and potential for improvement. In the test, the null hypothesis assumes that there is no difference between the categorized earthquake days

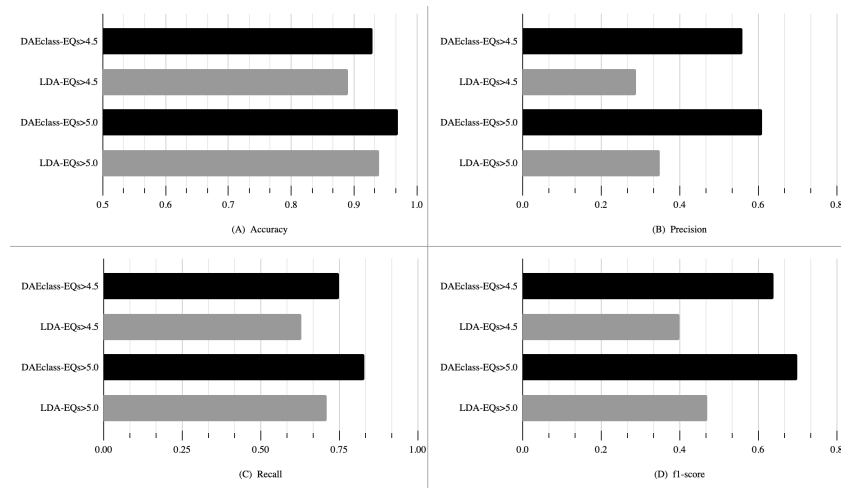


Figure 6: Performance metrics of the DAEclass and the LDA models based on two datasets ( $EQs \geq 4.5$  and  $EQs \geq 5.0$ ).

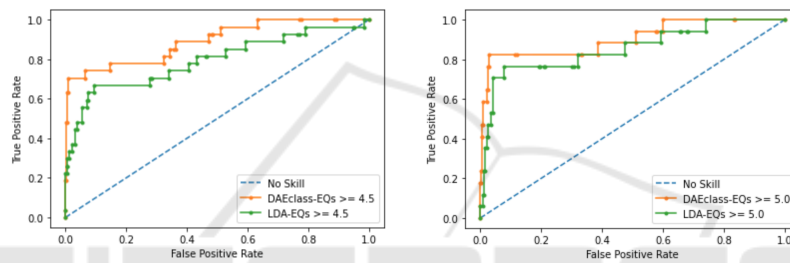


Figure 7: ROC curve of the DAEclass and the LDA classifier models based on two datasets ( $EQs \geq 4.5$  and  $EQs \geq 5.0$ ).

and the quiet days. In order to determine whether or not the null hypothesis under consideration can be rejected, the p-value test is done. The probability of detecting the effect(E) when the null hypothesis is true is represented by the P-Value. As shown by the test results of the DAEclass model, the difference in performance across all measures is statistically significant ( $p - value \ll 0.01$ ).

## 7 CONCLUSION

This study presents a method for interpreting earthquakes based on TEC values in the ionospheric layer. Data on ionospheric TEC was gathered from two GPS sites. The Chilean area is prone to powerful and severe earthquakes, however the Karratha region is rather earthquake-free. The primary goal of this study is to establish a link between earthquakes and ionosphere disturbances using deep learning methods to accomplish two sub-tasks: feature extraction and classification. Deep learning techniques are used to accomplish this goal. In the first stage, we concentrate on feature extraction from the TEC data, which is accomplished via the use of an unsupervised learn-

ing algorithm. To extract relevant information about the earthquake and quiet days, we create a Deep Autoencoder. Then, in the following stage, we use a supervised learning approach to do classification using a dense neural network, which is followed by a final step. The LDA classifier was used to examine the contribution of the proposed combination model to the overall contribution. Our findings show that the two test sets of earthquakes, which included mild and severe earthquakes, performed roughly 90-94 percent accurately based on the correctness of the data. In terms of accuracy, recall, precision, F1-score, and ROC curve metrics, the proposed DAEclass outperforms the LDA in a more trustworthy and dependable manner.

Because the primary purpose of this study is to extract important aspects of earthquakes from the ionosphere layer using TEC values and to identify earthquake days in the target station zone, earthquake prediction is not within the scope and priority of this research. In our other work (Abri and Artuner, 2022), we planed to work on a predictive system to predict earthquake using TEC data related to the earlier days of earthquakes by LSTM based deep learning models.



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