

CSPJade: Architectural Driven Development of Complex Embedded System Software Using a CSP Paradigm Based Generation Tool Code

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Abstract: A code generation tool for the development of control system software based on an architectural view of distributed real-time systems as a set of communicating parallel processes is presented. Firstly, we obtain a complete system specification by using the CSP+T process algebra. Secondly, an architectural design of the entire system under modeling is performed using the CSPJade graphical tool; once a model of the system is achieved in the CSPJade framework, an implementation in Java can be automatically generated by using the JSCP library. CSPJade defines a graphical abstract model of processes similar to the semantic of CSP+T, so a translation of modeling entities into CSP+T processes and vice-versa is easy to achieve and becomes less error prone. CSPJade allows the designer to deploy a set of reusable software components which are stored in two XML structures, the java project model (JPM) and the java container model (JCM).

1 Introduction

The specification of user requirements is considered a key phase of the development cycle of software systems. To achieve the system specification task goals, a comprehensive and accurate description of functional and non-functional requirements must be provided. A new framework together with a structured graphical language is proposed here to obtain a specification of behavioral and temporal requirements of real-time systems. In addition, the modeling entities can be translated into correct syntactical terms of a process algebra derived from CSP+T [1].

Many semi-formal system requirement specification and analysis notations, (SA/RT, CPN, CTPN, UML/RT, etc.) lack of predictable analysis entities when they are applied to the development of real-time systems; whereby these modeling languages make impossible to perform any verification or temporal analysis of the system model. As consequence, timing and dependability requirement analysis of real-time distributed control systems is usually performed by the development team after completely developing a system prototype in the industry. As a consequence, many prototypes result discarded, especially first prototypes, before obtaining an acceptable version of the final system. In addition, system validation only based on testing prototypes is not a good Software Engineering practice, since several of these

usually need to be built and discarded before obtaining a *correct* implementation of the *final* system, which increases development costs and delays its delivery date.

A Process Algebra (*PA*) is an algebraic approach for studying concurrent systems made of parallel communicating or synchronizing processes. Differently from other formal design languages, *PA*s are compositional. In this work we investigate how to carry out the development of a graphical framework for supporting a *PA* formal specification language, by providing a hierarchical, visually oriented, representation of processes and channels, which allows us: (a) to abstract a group of processes into a structured one, (b) to zoom inside a structured process in order to declare and (c) to manage channel connection definition between component processes in a comprehensive way. Our claim is that this tool can be used by analysts and developers without a deep knowledge of mathematics and logics to derive a provably correct system model.

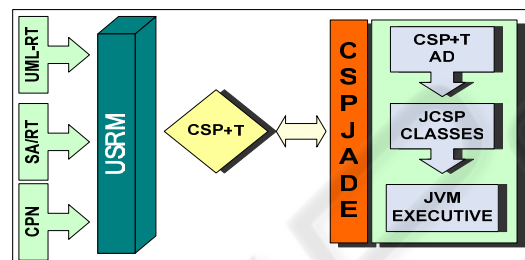


Fig. 1. Methodology proposed by [2] Capel et al.

The complete roadmap to obtain a complete system specification following our method is given in Fig.1. Starting from an initial user requirement specification model (*USRM*), a detailed system design by using *CSP+T PA* notation is obtained by following a systematic transformation [2]. The procedure allows us to model real-time processes including the specification of their timing requirements. Finally, by employing the graphical software tool *CSPJade*, we can perform a design automation of distributed embedded real-time control systems and the complete development process can be fully implemented in Java with the support of *CTJ* [3] or *JCSP* [4] libraries.

2 Background

Graphical notations for modelling and building software systems have been used in different stages of the development process of software, in special notations based on *UML* [5,6]. Some of them are capable of a “formal” reasoning of a *USRM*, as to mention *Statecharts*, with its formal official [7] semantics supported by the *Statemate* tool, the Unified Modelling Language (*UML*), a semi-formal language for visualising different systems from different perspectives, and which possesses different profiles [8] that can be used for developing some kind of specific systems as embedded or real-time systems in specific languages.

Pezzè et al. [9] has focused on providing a formal semantics for *Structured Analysis* style diagrams. Their work revealed that the numerous different interpretations of data flow diagrams can be structured and classified.

Dong et al. [10] considered visualising Timed Communicating Object-Z (TCOZ) specifications on the web by using XML/XML and UML diagrams as projected views. The automated reasoning of system properties within the design phase of these systems can be facilitated by using the proposed graphical tool.

3 CSPJade Definition

CSPJade is a graphical tool implemented in Java that allows us to perform a structured analysis of complex systems described as $CSP+T$ specifications assisted by a graphical language.

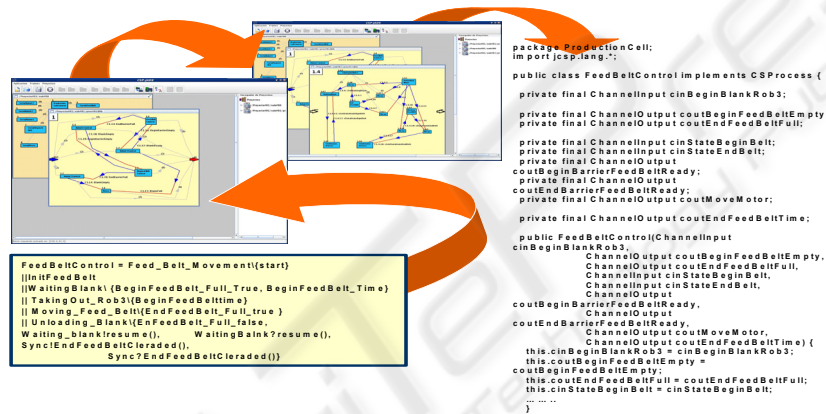


Fig. 2. Stages to achieve code generation.

An implementation of the system can be automatically generated in Java with the aid of the *JCSP* library as we presented recently in [11].

A model in CSPJade, i.e. Figure 3 is an n-tree hierarchical structure of graphs constituted by two main modelling elements: Processes and Channels. A process represents an independent self-contained entity which interacts with its environment through the channels. A channel is the entity that represents the connection of two processes in one specific direction. With these elements a static architectural model of the system can be built as a set of nested “views”. Each of these contains the information relevant to the processes inside the view.

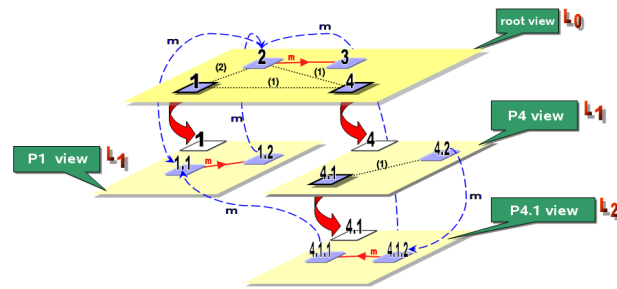


Fig. 3. Hierarchical abstract representation of a system in CSPJade.

The Channel entity creation is straightforward, but the global establishment of a Process entity implies the consecution of two objectives: firstly, the graphical connections of the Process through the channels must be done, obtaining by composition of these the static architectural diagram of the system. Secondly the behavioral part of the Process must be defined, as a function of the data that receives through its input channels and sends through its output ones. In Figure 2 we show a schematic view of a nested set of Processes and Channels..

3.1 Analysing Reusability Aspects

Our graphical tool makes use of XML technologies [12,13] to gain interoperability in a near future with other formal tools for real-time systems, i.e. FDR, and reusability is guaranteed by means of the deployment of the XML structures, namely JPM and JCM, with the aid of the JDOM library [14]. JPM stands for Java Project Model, which is a repository usually consisting of one file and a specific structure to store the information model. The JPM structure contains the graphical and executive aspects of a project, which encapsulate the underlying logical structure of the model. JCM stands for Java Component Model, its structure is based on a specific *Process* and it is a reusable unit of a system with a precise static and functional description of the nested elements that it contains.

4 Case of Study: Stages to Achieve Code Generation in the FeedBelt Control

The Feed Belt Control is a main part of the production cell, which is a well-known realistic manufacturing industry oriented problem [15], where safety requirements regarding the fulfilment of timing-constraints by the different concurrent movements of the cell components (robot arms, conveyor belts, press, etc.) are of paramount importance in order to have a useful design of the target system. The proposed configuration of the production cell as well as the CSP+T specification that can be seen in the lower left corner of Figure 2 is well detailed in [11].

We can summarize the steps, graphically represented in Fig. 2 as follows:

1. A CSP+T specification of the system must be obtained
2. The static architectural design of the system is done, by creating the nested set of processes and channels, and specifying the behavioral part of the processes as a function of the input/output data carried by the channels
3. Each executive part of a Process entity analyze its graphical structure, the data that carries its channels and performs the necessary computations to deliver the executable Java code

5 Conclusions and Future Work

Up to now a first version of our graphical editor has been built which allows obtaining an architectural diagram of the system, and the code generation module will be available in a short term, as well as other features that are discussed next.

Because we share a common interest with the work conducted by Jovanovic et al [16], and Hilderink [17] much of the following features planned to be added to our graphical tool in future releases are common to those presented by them:

- A coherent, complete and syntactically correct notation needs to be included in our tool, Brooke, Jovanovic and Hilderink notations are been carefully examined for this purpose.
- The temporal aspects of a communication line must be implemented to allow the design and analysis of real-time systems of a consistent way with the CSP+T process algebra.
- A GUI for allowing the implementation of new functionality of a process is, at this time, being developed. The functionality of the process will be saved in a XML structure through an adequate DTD or XML Schema.
- A temporal analysis module must be developed to perform scheduling analysis of complex designs of real-time systems, so that we can derive a provably correct and complete design previously to the implementation of any system prototype.

Finally, we hope that our graphical tool will help to expand the use of CSP by helping designers and developers in the task of concurrent system design and application programming, mainly in the development of real-time and embedded system.

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