

# Transductive Support Vector Machines for Risk Recognition of Sustained Ventricular Tachycardia and Flicker after Myocardial Infarction

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**Abstract.** This paper presents the improved recognition of patients with sustained ventricular tachycardia and flicker after myocardial infarction based on signal averaged electrocardiography. The novel approach includes: new filtering technique, extended signal description by a set of 9 parameters and the application of transductive support vector machine classifier. The dataset consists of 376 patients selected and commented by cardiologists of the Warsaw Medical University. The best score 94% of successful recognition on the test set was obtained for signals filtered by FIR method, described by 9 parameters.

## 1 Introduction

Ventricular tachycardia is a difficult clinical problem for the physician [4], [5], [9], [14], [15], [16], [17], [18]. Patients with sustained ventricular tachycardia and ventricular fibrillation have a potential for sudden death. After myocardial infarction the chance to get sustained ventricular tachycardia or ventricular fibrillation increases, thus reduction in number of sudden death requires advanced predictive procedures. The ability to identify properly arrhythmias from signal-averaged ECG (SAECG)[20] recordings is important for clinical diagnosis and treatment. This paper presents a novel approach to efficiently and accurately identify normal patients and sustained ventricular arrhythmias through the SAECG parameters by using the Transductive Support Vector Machines [6], [15], [21].

Signal-averaged electrocardiography is a technique involving computerized analysis of segments of a standard surface electrocardiogram. [3], [20] Signal-averaging

techniques, which reduce the noise (low-frequency, high-amplitude signals) interfering with the surface ECG, have been used since the 1970s, and it is used for detecting small electrical impulses, termed ventricular late potentials (VLP), that follow the QRS segment. Ventricular late potentials in patients with cardiac abnormalities, especially coronary artery disease or following an acute myocardial infarction, are associated with an increased risk of ventricular tachyarrhythmias and sudden cardiac death.

The application of support vector machine to the classification of electrocardiographic signals gave excellent results [10], [11]. However, the severe problem deals with the requirement of labelling the training set examples by cardiologists. Usually the data set consists of few commented examples and a large set of unlabeled signals. This fact strongly motivated us to use the transductive approach to medical data recognition.

## 2 Transductive Support Vector Machine

Transductive support vector machine (TSVM) is a statistical learning system that explores the information from the labelled data as well as unlabelled data distribution in the input space. It is the extension of supervised support vector machine.

The idea of transductive learning was postulated by Vapnik [21] who stated that transduction – labelling a test set is easier than induction – learning a general rule.

The objective is the classification of unlabelled data by a separating hypersurface in the Hilbert space between classes with the maximum margin with respect to labelled as well as unlabelled data points. The unlabelled points can be assigned to the class suggested by this solution, named the transductive support vector machine.

Intuitively, we expect that the separating hypersurface is located in the low density region of unlabelled data points between two classes.

Although the transductive support vector machine defines many new theoretical and numerical problems (it is NP.-completed problem) the idea is attractive due to following reasons:

1. The problem is perfectly suited for the applications in medicine [15], bioinformatics [13], text categorization [12] etc., as the data labelling of large data sets is practically impossible;
2. It is expected that the consideration of unlabelled data distribution can significantly improve the classifier generalisation with respect to supervised classification, especially if the number of labelled points is small as compared to the number of unlabelled points;
3. Semi-supervised classifier has well-defined statistical properties (margin width, separating border, generalisation), thus it is superior of unsupervised classifiers obtained by some heuristics (e.g. self-organising maps).

There exist some solutions for efficient transductive support vector machines, as the semi-supervised support vector machine  $S^3VM$  by K. Bennett and Demiriz [2] that enabled to perform up to several hundreds unlabelled points, SVM-light implementation of Joachims [12] and large-scale TSVM by Collobert et al. [7] that use iterative concave-convex procedure (CCCP).

The data set consists of  $l$  labelled training pairs  $\{(\mathbf{x}_{l1}, y_{l1}), \dots, (\mathbf{x}_{ll}, y_{ll})\}$ ,  $\mathbf{x} \in \mathbf{R}^n$ ,  $y \in \{1, -1\}$  denoted as L set and  $u$  unlabelled vectors  $\{\mathbf{x}_{u1}, \dots, \mathbf{x}_{uu}\}$  denoted as U set.

The problem of transductive support vector machine can be performed as an extension of supervised soft-margin support vector machine by adding 2 constraints to every point of the working set: One constraint enables to calculate the cost to classification error if a given point belongs to the positive class and the second one – the error cost if a given point belongs to the negative class. The objective function for 2 cases of classification errors is calculated. The minimum cost suggests the labelling decision of a given unlabelled point. Hence, we deal with the hard combinatorial task.

The primal form of the objective function of linear transductive support vector machine is as follows:

$$\min W(y_{u1}^*, \dots, y_{um}^*, \mathbf{w}, b, \xi_1, \dots, \xi_l, \xi_1^*, \dots, \xi_u^*) = \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^l \xi_i + C^* \sum_{j=1}^u \xi_j^* \quad (1)$$

under constraints:

$$\begin{aligned} \forall i \in L: & \quad y_{li}(\mathbf{w} \cdot \mathbf{x}_{li} + b) \geq 1 - \xi_i \\ \forall j \in U: & \quad y_{uj}^*(\mathbf{w} \cdot \mathbf{x}_{uj}^* - b) \geq 1 - \xi_j^* \\ \forall j \in U: & \quad y_{uj}^* \in \{-1, +1\} \\ \forall i \in L: & \quad \xi_i \geq 0 \\ \forall j \in U: & \quad \xi_j^* \geq 0 \end{aligned}$$

where:  $\mathbf{w}$ ,  $b$  – parameters of the optimal separating hyperplane,  $\xi$ ,  $\xi^*$  - slack variables.

The parameters  $C$  and  $C^*$  express the trade-off between the margin width and the number of classification errors on the labelled set data or exclusion of unlabelled data points. The labels are numbers: +1, -1.

In general, we can introduce a non-linear kernel in order to generalize the transductive support vector machine. We applied the radial basis function (RBF) kernel [19]

$$K(\mathbf{x}, \mathbf{x}') = \exp(-\gamma \|\mathbf{x} - \mathbf{x}'\|^2) \quad (2)$$

The quality of TSVM classifier strongly depends on the proper choice of the parameters  $C$  and  $C^*$  and on the kernel function parameter  $\gamma$ .

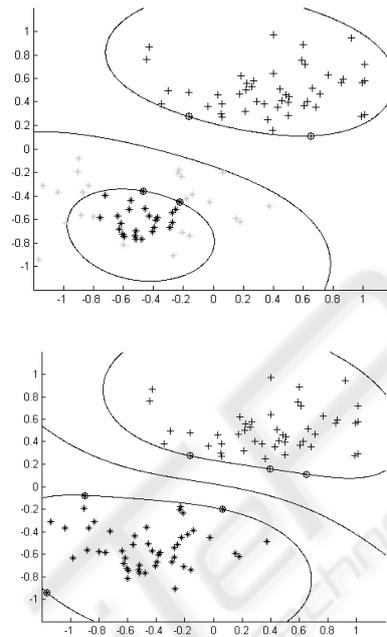
Our calculations are based on the SVM-light algorithm that operates in the following way. The input information consists of labelled data set L and unlabeled set data U. The parameters set up by the user are:  $C$ ,  $C^*$  and  $num+$ , the predicted cardinal number of points from positive class of entire set L+U. The algorithm starts from solving the problem of supervised support vector machine for labelled data set L. The unlabelled data U are given the labels resulting from the obtained classifier.

The first  $num+$  data points of the largest values of discriminative function:

$$f(\mathbf{x}) = \sum_{i=1}^l \alpha_i K(\mathbf{x}_i, \mathbf{x}) + b \quad (3)$$

where  $\alpha_i$  are the Lagrange multipliers of each data point, are assigned to the positive class and the remaining points to the negative class.

The initially small value of parameter  $C^*$  ( $10^{-5}$ ) is multiplied by 1.5 on each iteration up to the value  $C$  set by the user, hence the influence of unlabelled data  $U$  on the position of separating hypersurface grows up. The next loop performs the label switching caused by some data points and verifies their influence on the objective function.



**Fig. 1.** a) Decision boundary based on small number of labelled examples. b) The decision boundary is moved to place with low local density: \* class +1 examples, + class -1 examples, ○ support vectors, light grey – unlabeled data, black – labelled data.

Therefore the solution is improved by modifying the initial labels of data set points  $U$  in the direction of decreasing objective function. The output of TSVM procedure is a set of predicted labels of the data set  $U$ .

The algorithm is convergent in finite number of label changes due to finite number of permutations of  $U$  points.

The idea of transductive support vector machine is shown in Fig. 1 for a case of two-dimensional data sets.

### 3 Signal-averaged ECG Analysis

The Agency for Health Care Policy and Research [1] published a Health Technology Assessment of SAECG in 1998, concluding that clinical studies of SAECG consis-

tently demonstrated a very high negative predictive value (76-100%), variable sensitivity (35-83%) and specificity (47-91%), and poor positive predictive value (8-48%) when performed on patients with cardiomyopathy or following a myocardial infarction.

The ability to properly identify arrhythmias from SAECG recordings is important for clinical diagnosis and treatment, also predictive procedure can reduce the number of sudden cardiac death.

The method of recording and analysis of SAECG is recommended by the AHA/ACC/ESC Policy Statement on SAECG Standards, as well as the ACC Expert Consensus Document on SAECG [5]. After recording  $x, y, z$  signals (recommended Frank leads) the signals are averaged, then filtered using the Bidirectional Butterworth Filter. [3] After filtering each lead,  $x(t), y(t), z(t)$ , the resulting vector magnitude (VM) is calculated as  $(x^2 + y^2 + z^2)^{1/2}$ .

Three time domain parameters were calculated:

1. the total duration of the filtered QRS complex (hfQRS),
2. the root mean square voltage of the last 40 ms of the filtered QRS complex (RMS40)
3. the duration of the low amplitude (LAS<40  $\mu$ V) signals at the terminal portion of the QRS complex.

It was shown that this method has several limitations, as the differences in the algorithms for defining the end and the beginning of QRS, the normal values of mentioned parameters and others. [1, 3, 8].

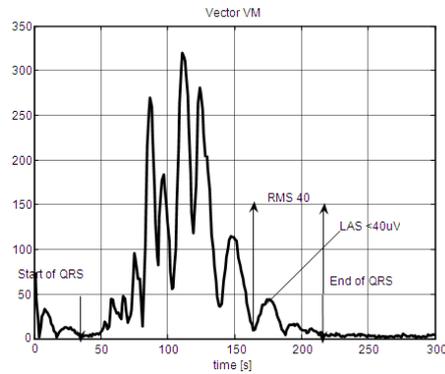
This problem can be solved by using statistical classification method and testing if we can better extract patients with high risk of ventricular tachyarrhythmia and sudden cardiac death. [9] The aim of our study was to improve the method of signal-averaged ECG for extraction of patients after myocardial infarction with the risk of sustained ventricular tachycardia by applying different type of filtration and 6 new parameters. Our study is based on a data set performed at the Chair and Clinic of Internal Medicine and Cardiology, Warsaw University of Medicine. It consists of 376 patients underwent the signal-averaged ECG recordings. Upon the medical diagnosis, these patients are divided into 3 groups:

1. patients with sustained ventricular tachycardia (sVT+) after myocardial infarction - 100 patients;
2. patients without sustained ventricular tachycardia (sVT-) after myocardial infarction - 199 patients;
3. healthy persons – 77 patients.

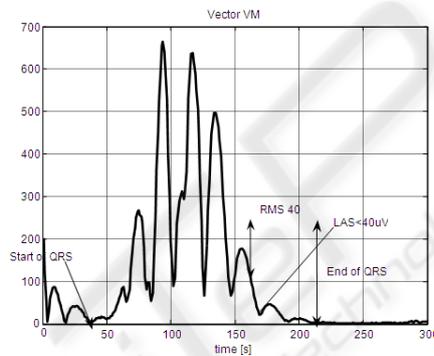
Only 76 patients from the first group satisfied the common criteria of existence of late potentials.

#### 4 Time Domain Parameters

The QRS complex of three bipolar leads were combined into the vector magnitude (Figure 2 and 3). For each of 2 types of filtration (a four-pole IIR Butterworth filter, FIR filter with Kaiser window) we calculated 9 signal parameters: 3 commonly used and 6 additional ones, as defined in Table 1.



**Fig. 2.** Example of vector magnitude of filtered QRS complex for patient with sVT+ (four-pole IIR Butterworth filter).



**Fig. 3.** Example of vector magnitude of filtered QRS complex for patient with sVT- (four-pole IIR Butterworth filter).

**Table 1.** Signal-averaged ECG parameters.

	<b>Parameter</b>	<b>Definition</b>
1	hfQRS (msec)	the total duration of the filtered QRS complex
2	RMS40 ( $\mu$ V)	rms voltage of the last 40 ms of the filtered QRS complex
3	LAS<40 $\mu$ V (ms)	the duration of the low amplitude < 40 $\mu$ V signals at the terminal portion of the QRS complex
4	LAS<25 $\mu$ V (ms)	the duration of the low amplitude < 25 $\mu$ V signals at the terminal portion of the QRS complex
5	RMS QRS ( $\mu$ V)	rms voltage of the filtered QRS complex
6	pRMS ( $\mu$ V)	rms voltage of the first 40ms of filtered QRS complex
7	pLAS (ms)	the duration of the low amplitude < 40 $\mu$ V signals within QRS complex
8	RMS t1( $\mu$ V)	rms voltage of the last 10 ms the filtered QRS complex
9	RMS t2 ( $\mu$ V)	rms voltage of the last 20 ms the filtered QRS complex

rms – root mean square

## 5 Results

Based on signal-averaged ECG recordings nine data sets described in Table 2 were created.

**Table 2.** Description of the data sets.

Data set	Number of parameters	Filtration type
WS3-1,2,t	3	40Hz high-pass and 250Hz low pass four-pole IIR Butterworth filter
WS9-1,2,t	9	40Hz high-pass and 250Hz low pass four-pole IIR Butterworth filter
WK9-1,2,t	9	FIR filter with Kaiser window 45-150 Hz

Data sets WS3-t, WS9-t and WK9-t contained 188 cases and were used for testing of obtained classifiers. Data sets WS3-1, WS9-1 and WK9-1 contained 188 cases and were used for creation of three supervised SVM models (all data were labelled). Data sets WS3-2, WS9-2 and WK9-2 contained the same 188 cases as Wxx-1 sets but only 50% of them were labelled. They were used for creation of three TSVM models.

The application runs in Windows system environment. No additional libraries are required. The input data for the models creation are read from files. The results are send to standard output of the application. It enables redirection to file for further analysis or viewing on the screen. The calculations required for the transductive support vector classifier are much more time consuming than those for the supervised SVM method due to iterative nature of the TSVM algorithm.

Table 3 contains model properties for the supervised SVM method.

**Table 3.** Model properties – supervised SVM method.

Data set	No. of support vectors	No. of support vectors at C	C, gamma	Estimation of VC dimension
WS3-1	25	20	100, 0,5	358,94
WS9-1	26	11	100, 0,5	770,79
WK9-1	24	9	100, 0,5	1010,37

Table 4 contains model properties for the TSVM method. TSVM model contains fewer support vectors and has higher estimation of VC dimension than equivalent SVM model.

**Table 4.** Model properties – TSVM method.

Data set	No. of support vectors	No. of support vectors at C	C, gamma	Estimation of VC dimension
WS3-2	16	12	100, 0,5	423,34
WS9-2	21	8	100, 0,5	664,41
WK9-2	24	6	100, 1	1642,40

The results of classification are listed in Table 5. Each test data set (different from learning set) was classified by means of regular SVM classifier as well as TSVM classifier. The results confirm good generalization of obtained models. It is worth to note that results of SVM and TSVM classification are similar, although only 50% of data in the second case was labelled. In data set WK-9 the TSVM method achieved better results.

**Table 5.** Results of SVM and TSVM classification.

Data set	Correct classifications [%]		No. of correct classifications		No. of misclassifications	
	SVM	TSVM	SVM	TSVM	SVM	TSVM
WS3-1,2	92,51	92,51	173	173	15	15
WS9-1,2	92,55	90,43	174	170	14	18
WK9-1,2	93,09	94,15	175	177	13	11

## 6 Conclusions

This paper reports the study of risk recognition of sustained ventricular tachycardia and flicker in patients after myocardial infarction based on high-resolution electrocardiography. We considered 3 data sets consisting of the signal averaged ECG:

1. filtered by 40Hz high-pass and 250Hz low pass four-pole IIR Butterworth filter described by three standard parameters,
2. filtered by 40Hz high-pass and 250Hz low pass four-pole IIR Butterworth filter described by 9 parameters,
3. filtered by FIR filter with Kaiser window 45-150 Hz described by 9 parameters.

We compared the results obtained by the supervised and the transductive SVM classifier. In all considered cases we obtained very high score of successful recognition (90-94%). This result is significantly better than 76% obtained by the commonly used criteria. The best recognition score is obtained for the signal-averaged ECG recordings filtered by the FIR filter with Kaiser window 45-150 Hz described by 9 parameters. In this case the transductive SVM (TSVM) classifier is superior over the supervised SVM classifier. All studied support vector classifiers exhibit also excellent

statistical properties expressed by small number of support vectors and high value of estimated VC dimension.

The system is fast enough. The TSVM solution for a data set of several hundreds points is of order 20-30 seconds, the recognition time is about 0.1 s.

It can be concluded that the transductive support vector machine is an efficient tool of computer-aided medical data recognition. It enables the improvement of results for labelled data by exploring much larger set of unlabelled data.

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