SOFTWARE EFFORT ESTIMATION AS A CLASSIFICATION PROBLEM

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Abstract: Software cost estimation is still an open challenge. Many researchers have proposed various methods that usually focus on point estimates. Software cost estimation, up to now, has been treated as a regression problem. However, in order to prevent over/under estimates, it is more practical to predict the interval of estimations instead of the exact values. In this paper, we propose an approach that converts cost estimation into a classification problem and classifies new software projects in one of the effort classes each corresponding to an effort interval. Our approach integrates cluster analysis with classification methods. Cluster analysis is used to determine effort intervals while different classification algorithms are used to find the corresponding effort classes. The proposed approach is applied to seven public data sets. Our experimental results show that hit rates obtained for effort estimation are around 90%-100%s. For point estimation, the results are also comparable to those in the literature.

1 INTRODUCTION

Software cost estimation is one of the critical steps in software development lifecycle (Leung and Fan, 2002; Boehm, 1981). It is the process of predicting the effort required to develop a software project. Such predictions assist project managers when they make important decisions such as bidding, etc.

Although most methods proposed in literature produce point estimates, Stamelos and Angelis states that producing interval estimates is safer (Stamelos and Angelis, 2001). Up to now, interval estimation is composed of finding either the confidence intervals for point estimates or the posterior probabilities of predefined intervals (Angelis and Stamelos, 2000; Jorgensen, M., 2003; Sentas et al. 2004; Sentas et al. 2003) and then fitting regression-based methods to these intervals. However, none of these approaches address cost estimation problem as a pure classification problem. In this paper, by using interval estimation as a tool, we aim to convert cost estimation into a classification problem. By using cluster analysis, effort classes are determined dynamically instead of using manually-predefined intervals. Then, classification methods are applied on clustered data in order to find the estimated effort interval.

2 RELATED WORK

Previous work on software cost estimation mostly produces point estimates by using regression methods. There is less number of studies that focus on interval estimation. These studies can be grouped into two main categories: (1) those which produce confidence intervals for point estimates and (2) those which produce the probabilities of predefined intervals. In (1), interval estimates are generated during the estimation process (Angelis and Stamelos, 2000; Jorgensen, M., 2003). In (2) the intervals are predefined before the estimation process (Sentas et al. 2004; Sentas et al. 2003). In contrast to these studies, in this paper, firstly, effort intervals are not predefined manually; rather, they are determined by clustering analysis. Secondly, instead of using regression-based methods, we use classification algorithms that originate from machine learning area. Thirdly, point estimates can still be derived from these intervals; this will be shown in the following sections.

We also use cluster analysis for grouping similar projects in this paper as in (Lee et al. 1998; Gallego et al. 2007). The difference of our research with these studies is that we combine clustering with classification methods for effort estimation.

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3 THE APPROACH

There are three main steps in our approach: (1) grouping similar projects together by cluster analysis, (2) determining the effort intervals for each cluster and specifying the effort classes, and (3) classifying new projects into one of the effort classes. The resulting class shows the effort interval that contains the new project's effort value.

In step (1), we use an incremental clustering algorithm called Leader Cluster (Alpaydin, 2004). In this algorithm, the number of the clusters is not predefined; instead, the clusters are generated incrementally and Euclidean distance is used as similarity measure (Bakar et al. 2005; Lee et al. 1998).

In step (2), firstly, the minimum and maximum of the efforts of the projects that reside in the same cluster are found. Secondly, these minimum and maximum values are chosen as the upper and lower bounds of the interval that will represent that cluster. Finally, each cluster is given a class label which will be used to classify the new projects into.

In step (3), we use three different classification algorithms with different complexities. Linear Discrimination is the simplest one whereas Decision Tree is the most complex one. K-Nearest Neighbor has a moderate complexity depending on the training set size (Alpaydin, 2004; Quinlan, 1993).

4 EXPERIMENTAL STUDY

MATLAB is used for the implementation of the approach.

4.1 Data Set Description

In our experiments, data from two different sources are used: Promise Data Repository and Software Engineering Research Laboratory (SoftLab) Repository (Boetticher et al., 2007; SoftLab). An overview of all the datasets used is given in Table 1.

Data Source	Dataset Name	# of Projects
	cocomonasa_v1	60
	coc81	63
Promise	desharnais_1_1 (updated version)	77
	nasa93	93
	sdr05	25
SoftLab	sdr06	24
	sdr07	40

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4.2 Model

Our proposed model is shown in Figure 1. Before applying any method, all of the datasets are normalized in order to remove scaling effects in different dimensions by using Min-max normalization.

Firstly, clustering algorithm is applied to the normalized data to obtain project groups. Secondly, with Principal Component Analysis (PCA), each cluster's dimensions are reduced individually by using their own covariance matrices (Alpaydin, 2004). The aim here is to prevent data loss within clusters while extracting relevant features. Thirdly, each cluster is assigned a class label and the effort intervals for each of them are determined. Then, the effort data containing projects with corresponding class labels is given to each of the classification algorithms described in Section 3. Since there are not separate training and test sets, the classification process is done in a 10x10 cross-validation loop. In the cross-validation loop, data is 10 times shuffled into random order and then divided into 10 bins. Training set is built from nine of the bins, and the



Figure 1: Our proposed model.



remaining bin is used as validation set. Classification algorithms are firstly trained on the training set and then error calculations are made by using the validation set. The errors are collected during 100 cross-validation iterations.

In order to make a comparison with other studies, at the classification step, point estimates are calculated for each classification method. For this process, both mean and median of the effort values of the projects that belong to the class found by each classifier are taken (Sentas et al., 2003).

4.3 Accuracy Measures

In our experimental study, there are two types of accuracy measures: (a) misclassification rate for classification and (b) MMRE, MedianMRE, and PRED (25) for point estimates. Misclassification rate can be thought as the complement of the *hit rate* that has been mentioned in interval prediction studies. In order to say that a model performs well, MdMRE and MMRE values should be low and PRED (25) values should be high.

5 RESULTS AND DISCUSSION

The effort clusters created for each dataset and the minimum and maximum numbers of projects assigned to a cluster are given in Table 2.

The classification results for effort interval estimation are given in Figure 2. K-NN and LD performs similar for coc81, desharnais_1_1, nasa93, and sdr05. They both give 0% misclassification rate for coc81 and sdr05. For cocomonasa_v1 and sdr06, K-NN outperforms the others whereas for sdr07, LD is the best one. In general, considering classifiers, K-NN is the best performing one; LD follows it with a slight difference whereas DT is the worst performing one. The misclassification rates are 0% for most cases and around 17% in the worst case.

The most recent study on effort interval classification is Sentas et al.'s study. In Table 3 we

compare our results with that of Sentas et.al. Note that the intervals in their study are manually predefined intervals.

Table 2: Effort	clusters	for	each	dataset.
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Deteret	# of	# of Projects		
Dataset	Clusters	Min	Max	
coc81	4	2	44	
cocomonasa_v1	5	3	36	
desharnais_1_1	9	2	21	
nasa93	6	3	44	
sdr05	3	3	16	
sdr06	3	2	12	
sdr07	4	6	16	

In order to show how our results can be easily converted to point estimates, in Table 4, we present the point estimation results found by either taking the mean or median of the projects' effort values. K-NN and LD perform nearly the same and better than DT for all datasets. All classifiers' performances improve for all measures when median is used for point estimation. MMRE and MdMRE results decrease down to 13% and PRED results increase up to 86% for some datasets. Note that an 86 % PRED value means that 86% of all estimations are within 25% confidence interval, which shows the stability and robustness of our proposed model.

Table 3: Comparison of the results.

	Hit rate (%)			
	Min Max			
Sentas et al.	60.38	79.24		
Our model	97	100		

6 CONCLUSIONS AND FUTURE WORK

In this paper, we handle cost estimation as a classification problem rather than a regression

Detect	Classifier	Using the mean of projects			Using the median of projects		
Dataset	Classifier	MMRE	MdMRE	PRED	MMRE	MdMRE	PRED
	LD	189	183	33	131	131	33.6
coc81	K-NN	189	183	33	131	131	33.6
	DT	192	190	29.6	134	131	30.2
	LD	69	45	42.2	51	32	54.8
cocomonasa v1	K-NN	69	45	42	51	32	54.6
_	DT	76	50	26.8	58	40	39.4
	LD	13	12	84.14	13	12	86.42
desharnais 1 1	K-NN	13	12	84.14	13	12	86.71
	DT	16	15	79	15	15	81.85
	LD	70	52	55.5	52	40	57.7
nasa93	K-NN	69	52	55.5	52	40	57.7
	DT	72	52	51.2	55	41	53.4
sdr05	LD	45	28	45.5	37	26	52
	K-NN	45	28	45.5	37	26	52
	DT	59	44	28.5	52	38	35
sdr06	LD	31	31	50.5	25	23	67
	K-NN	30	31	50.5	24	23	67
	DT	34	36	44.5	27	25	61
	LD	14	14	84.66	14	14	79.6
sdr07	K-NN	14	13	81.33	14	14	76.3
	DT	14	13	81.33	14	14	76.3

Table 4: Point estimation results (%).

problem and propose an approach that classifies new software projects in one of the dynamically created effort classes each corresponding to an effort interval. In the experiments done, we obtain higher hit rates than other studies in the literature. For point estimation results, we can see that MdMRE, MMRE, and PRED (25) values are comparable to those in the literature for most of the datasets although we use simple methods like mean and median regression.

Future work includes using different clustering techniques to find effort classes and to apply regression-based models for point estimation.

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