

A MULTIVARIATE STATISTICAL ANALYSIS OF MUSCULAR BIOPOTENCIAL FOR HUMAN ARM MOVEMENT CHARACTERIZATION

Giuliano Alves da Silva, Maria Cláudia Ferrari de Castro and Carlos Eduardo Thomaz

*Department of Electrical Engineering, Centro Universitário da FEI
Av. Humberto A.C. Branco, 3972, São Bernardo do Campo, São Paulo, CEP 09850-901, Brazil*

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Abstract: Pattern recognition of electromyographic signals consists of a hard task due to the high dimensionality of the data and noise presence on the acquired signals. This work intends to study the data set as a multivariate pattern recognition problem by applying linear transformations to reduce the data dimensionality. Five volunteers contributed in a previous experiment that acquired the myoelectrical signals using surface electrodes. Attempts to analyse the groups of acquired data by means of descriptive statistics have shown to be inconclusive. This work shows that the use of multivariate statistical techniques such as Principal Components Analysis (PCA) and Maximum uncertainty Linear Discriminant Analysis (MLDA) to characterize the acquired set of signals through low dimensional scatter plots provides a new understanding of the data spread, making easier its analysis. Considering the arm horizontal movement and the acquired set of data used in this research, a multivariate linear separation between the patterns of interest quantified by the distance of Bhattacharyya suggests that it's possible not only to characterize the angular joint position, but also to confirm that different movements recruit similar amounts of energy to be executed.

1 INTRODUCTION

The human movement characterization represents a great challenge and a relatively new field in the scientific investigation. Several techniques have been used in the attempt to describe and classify these movements (Kleissen et al., 1998; Bittar and Castro, 2008).

The study of muscular bio-potentials has been developed impelled by the diagnosis of neuromuscular disturbances and by the development of mechanical prostheses for amputees. The myoelectric signal, through the electromyography, helps to describe, standardize and define the operation of the muscular movement. The electromyography consists of acquiring and registering the electric signals emitted by the muscular cells.

Electric signals, generated by motor units in the skeleton muscles, control the position and the movements of the limbs, while traveling between the muscles and the peripheral/central nervous system (Henneberg, 2000). By acquiring and studying these

signals through the electromyography, it's possible to determine patterns of interest and use such discriminative information to control a wide variety of devices. Unfortunately this information is not totally reliable due to a great susceptibility to noise, redundancy, and the small sample size inherent to the acquired data set.

This paper introduces some techniques that aim to improve the understanding and reliability of the acquired data set by applying multivariate linear transformations such as Principal Components Analysis (PCA) (Fukunaga, 1990) and Maximum uncertainty Linear Discriminant Analysis (MLDA) (Thomaz et al., 2005). Experiments mixing the signals provided by the biceps and triceps, in an experience that intends to identify the angular position of the arm, have shown that it's possible to have a good and reliable separation of myoelectric signals for further classification.

2 EXPERIMENTS AND METHODS

2.1 Experiments

For the extraction and analysis of myoelectric signals used in this experiment, five volunteers were submitted to tests in a previous research that evaluated the contribution of the muscles biceps and triceps during voluntary flexion and extension elbow movements (Bittar and Castro, 2008).

Figure 1 illustrates the device used in the experiment, developed to minimize the interferences in the movement performed by the volunteer and guarantee the angular position of the arm, making easier the control over the acquired data.

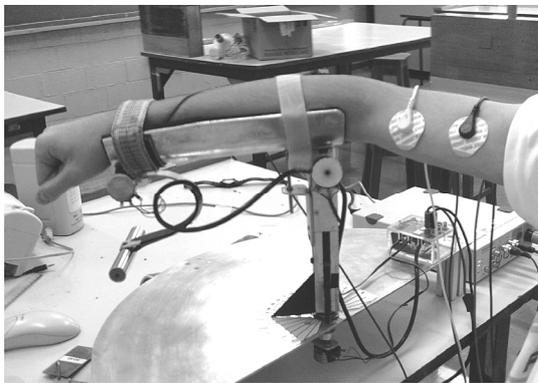


Figure 1: Horizontal myographic signals acquisition.

Each volunteer was submitted to 3 types of tests repeated 3 times in the vertical and horizontal plans. In this work, we only consider the tests in the horizontal plan, according to the following description:

- Test 1 (BT1): The first test consists of moving the arm in a 10° shift on every 3 seconds going to 90° and returning to the extension position by the same way. This test generated a subset of data, here called BT1, which have been labeled as 3 different groups of signals: 0° to 10°, 40° to 50° and 80° to 90°;

- Test 2 (BT2): In the second test, the volunteer repeated the movement from 0° to 90°, but this time without pauses, in a continuous way and in the space of ten seconds. This test generated the BT2 subset of data, which have been labeled accordingly to the following 3 groups of signals: 0° to 10°, 40° to 50° and 80° to 90°;

- Test 3 (BT3): In the third test, the movement should be done moving the arm from the initial point in a 10° shift and returning to the origin and

repeating again from the origin to 20° and back, so forth until achieving 90°. This test generated the BT3 subset data, which have been labeled accordingly to the following 3 groups of signals: 0° to 10°, 0° to 50° and 0 to 90°.

The myoelectric signals were tabulated to simplify the data set manipulation. A data set BTG (BT1+BT2+BT3) was created considering the simultaneous analysis of biceps and triceps signals to characterize the arm angular position. Figure 2 shows a representation of the BTG group, obtained from the combined signals of triceps and biceps muscles in movements from 0° to 10°, 40° to 50° and 80° to 90° (BT1+BT2) and 0° to 10°, 0° to 50° and 0° to 90° (BT3), through a dispersion graph. It can be seen that due to the high dimensionality of the data and noise presence on the acquired signals, the characterization of the patterns of interest is a challenging multivariate data analysis task.

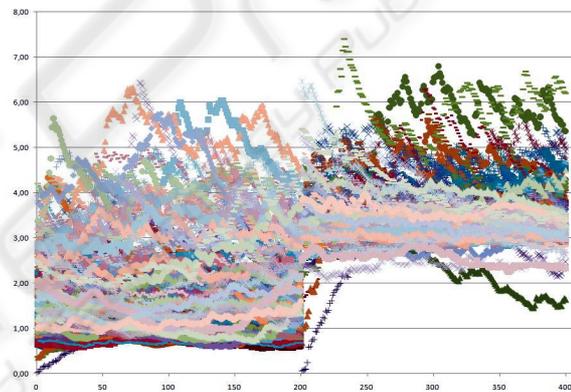


Figure 2: BTG biceps (left) and triceps (right) signals.

2.2 Methods

In statistical pattern recognition, a myographic signal with n variables or parameters can be treated as a point in an n -dimensional space called the original space. The coordinates of this point represent the values of each variable of the signal and form a high dimensional vector $x^T = [x_1, x_2, \dots, x_n]$, where $n \gg 1$. Since n -dimensional myographic signals are highly redundant, we can project such multivariate data onto a lower dimensional space without significant loss of information. In this section, we describe the multivariate statistical techniques used in this work to analyze and characterize the acquired set of signals through low dimensional linear transformations.

2.2.1 Principal Components Analysis (PCA)

PCA is a feature extraction procedure concerned with explaining the covariance structure of a set of variables through a small number of linear combinations of these variables. It is a well-known statistical technique that has been used in several pattern recognition problems, especially for dimensionality reduction. A comprehensive description of this multivariate statistical analysis method can be found in (Fukunaga, 1990).

Let an $N \times n$ training set matrix X be composed of N input signals with n variables. This means that each column of matrix X represents the values of a particular variable observed all over the N signals. Let this data matrix X have covariance matrix S with respectively Φ and Λ eigenvector and eigenvalue matrices, that is,

$$P^T S P = \Lambda. \quad (1)$$

It is a proven result that the set of m ($m \leq n$) eigenvectors of S , which corresponds to the m largest eigenvalues, minimizes the mean square reconstruction error over all choices of m orthonormal basis vectors (Fukunaga, 1990). Such a set of eigenvectors that defines a new uncorrelated coordinate system for the training set matrix X is known as the principal components.

Therefore, although n variables are required to reproduce the total variability (or information) of the sample X , much of this variability can be accounted for by a smaller number m of principal components. That is, the m principal components can then replace the initial n variables and the original data set, consisting of N measurements on n variables, is reduced to a data set consisting of N measurements on m principal components. Figure 3 shows the representation of the BTG data set focusing on the analysis of the biceps and triceps signals on the first two principal components ($m=2$).

However, since PCA explains the covariance structure of all the data its most expressive components, that is, the first principal components with the largest eigenvalues, do not necessarily represent important discriminant directions to separate groups of patterns.

2.2.2 Maximum Uncertainty LDA (MLDA)

A common practice to identify the important linear directions for separating groups of patterns is to use Fisher's Linear Discriminant Analysis (LDA) rather than PCA. The primary purpose of LDA is to sepa-

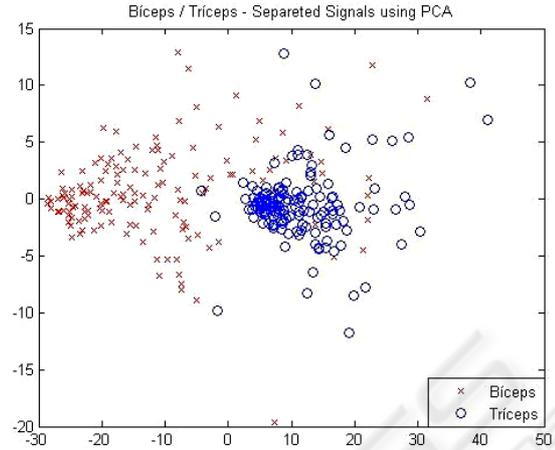


Figure 3: BTG biceps and triceps signals on the first two principal components.

rate samples of distinct groups by maximizing their between-class separability while minimizing their within-class variability.

Let the between-class scatter matrix S_b be defined as

$$S_b = \sum_{i=1}^g N_i (\bar{x}_i - \bar{x})(\bar{x}_i - \bar{x})^T \quad (2)$$

and the within-class scatter matrix S_w be defined as

$$S_w = \sum_{i=1}^g \sum_{j=1}^{N_i} (x_{i,j} - \bar{x}_i)(x_{i,j} - \bar{x}_i)^T, \quad (3)$$

where $x_{i,j}$ is the m -dimensional pattern j from class π_i , N_i is the number of training patterns from class π_i , and g is the total number of classes or groups. The vector \bar{x}_i and matrix S_i are respectively the unbiased sample mean and sample covariance matrix of class π_i (Fukunaga, 1990). The grand mean vector \bar{x} is given by

$$\bar{x} = \frac{1}{N} \sum_{i=1}^g N_i \bar{x}_i = \frac{1}{N} \sum_{i=1}^g \sum_{j=1}^{N_i} x_{i,j}, \quad (4)$$

where N is the total number of samples, that is, $N = N_1 + N_2 + \dots + N_g$.

The main objective of LDA is to find a projection matrix P_{lda} that maximizes the ratio of the determinant of the between-class scatter matrix to the determinant of the within-class scatter matrix (Fisher's criterion), that is,

$$P_{lda} = \arg \max_P \frac{|P^T S_b P|}{|P^T S_w P|}. \quad (5)$$

However, the performance of the standard LDA can be seriously degraded if there is only a limited number of total training observations N compared to the dimension of the feature space m . Since the

within-class scatter matrix S_w is a function of $(N - g)$ or less linearly independent vectors, its rank is $(N - g)$ or less. Therefore, S_w is a singular matrix if N is less than $(m + g)$, or, analogously, might be unstable if N is not at least five to ten times $(m + g)$ (Jain and Chandrasekaran, 1982).

To avoid the aforementioned critical issues of the standard LDA in the limited sample and high dimensional problem investigated here, we have calculated P_{lda} by using a maximum uncertainty LDA-based approach (MLDA) that considers the issue of stabilising the S_w estimate with a multiple of the identity matrix (Thomaz et al., 2004; Thomaz and Gillies, 2005).

The maximum uncertainty LDA is constructed by replacing S_w with its regularization version in the Fisher's criterion formula described in equation (5). A comprehensive description of this multivariate statistical analysis method can be found in (Thomaz and Gillies, 2005).

3 RESULTS

Figure 4 shows the PCA+MLDA transformation of biceps and triceps signals treated together in tests 1, 2 and 3.

The two-stage PCA+MLDA multivariate linear transformation reduces the dimensionality of the original data and extracts the most discriminant information from the patterns of interest. We have retained all the PCA eigenvectors with non-zero eigenvalues, that is, $m = N - 1$, to reproduce the total variability of the samples with no loss of information.

BTG group was then analyzed, intending to investigate the possibility of characterizing the groups of movements based only on the executed angular position instead of the muscle and the related movement. Thus, by naming the classes with the corresponding angular position and group labels and considering three main groups as follows:

- (M1) all the movements aiming 10° ,
- (M2) all the movements aiming 50° ,
- (M3) all the movements aiming 90° ,

Figure 5 shows that even when analyzing the different data set groups BT1, BT2 and BT3 on the same 2D scatter plot it is still possible to see the 3 classes of data, which represent the final joint position of the arm.

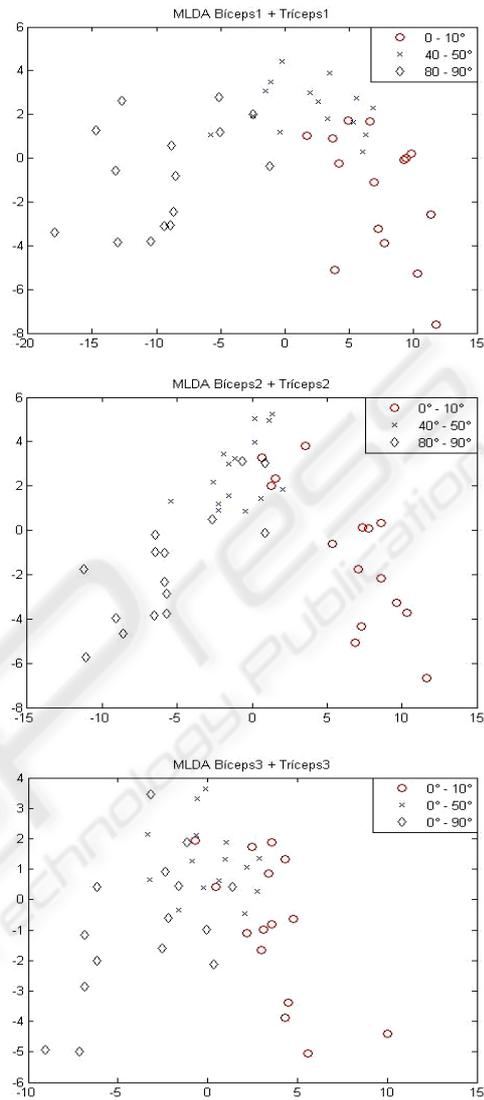


Figure 4: BT1 (top), BT2 (middle) and BT3 (bottom) signals on the two PCA+MLDA most discriminant components.

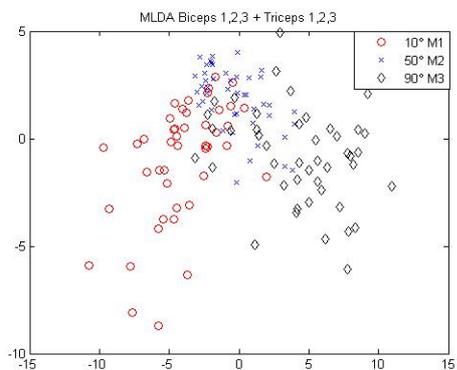


Figure 5: BTG biceps and triceps signals on the first two PCA+MLDA most discriminant components.

To quantify the PCA+MLDA linear separation between the groups visually inspected in Figure 4, we have used the Bhattacharyya distance (Fukunaga, 1990). The Bhattacharyya distance between two groups of patterns can be defined as

$$d = \frac{1}{8}(\bar{x}_1 - \bar{x}_2)^T \left(\frac{S_1 + S_2}{2} \right)^{-1} (\bar{x}_1 - \bar{x}_2) + \frac{1}{2} \ln \frac{\frac{|S_1 + S_2|}{2}}{\sqrt{|S_1| |S_2|}} \quad (6)$$

where the notation “|.” denotes the determinant of a matrix. As described previously, the vector \bar{x}_i and matrix S_i are respectively the unbiased sample mean and covariance matrix of class π_i ($i = 1,2,3$).

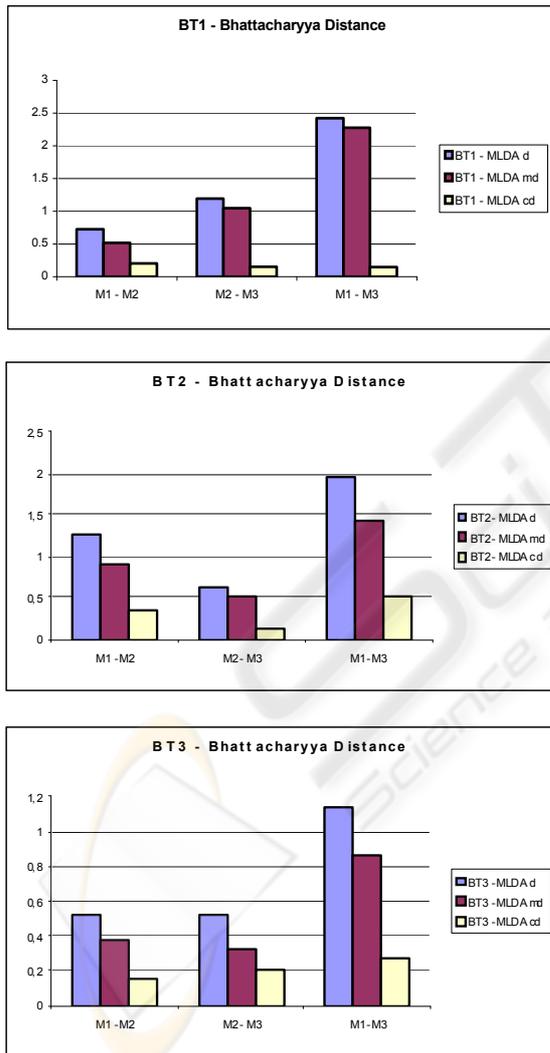


Figure 6: Quantification of the BTG biceps and triceps signals separation on the PCA+MLDA linear transformation using the Bhattacharyya distance.

Figure 6 illustrates the Bhattacharyya distance calculated pairwise between classes M1, M2 and M3. For each group BT1 (top), BT2 (middle) and BT3 (bottom), there is a measure of the total Bhattacharyya distance (d), the Bhattacharyya distance considering only its component related to the mean differences (md), and the one related to covariance differences (cd) only.

4 DISCUSSION

Initially, the acquired data was plotted in a dispersion graph, as previously illustrated in Figure 2. As it can be seen, it was not possible to extract any useful discriminant information from these graphs because there was a lot of redundancy on it, due to noise and the nature of the data itself. This picture becomes more confused as the number of samples increases.

To simplify and make possible this analysis, it was used a two-stage linear transformation to reduce the data set dimensionality and extract discriminant information between the patterns of interest. First, PCA was used making much easier the understanding of the data group representation by using a bi-dimensional space to represent the groups of data on the first two principal components. Afterwards, MLDA was used to improve the results through the data discriminant analysis. Then, we analyzed the biceps and triceps muscles to investigate whether the signals could be roughly separated. The signals provided by both muscles could be linearly separated, as shown in Figure 3, motivating the use of a combination of these signals to discriminate the sets to determine the angular joint arm position.

Figure 4 shows a clear separation of the studied groups $0^\circ-10^\circ$, $40^\circ-50^\circ$ and $80^\circ-90^\circ$, which had been very difficult to detect before using such two-stage linear transformation. As it can be seen, there is a little spot concentration in some points of the BT3 multivariate data analysis. This happens because, in this case, the movement performed by the volunteers started always at the same point, that is, $0^\circ-10^\circ$, $0^\circ-50^\circ$ and $0^\circ-90^\circ$, and such experiment can make harder to differentiate one movement from the other. By applying all groups BT1, BT2 and BT3 in a new bigger group BTG, whose aiming was to condense the data and verify their class-separability, it was still possible to determine the concentration regions of the studied classes. However, there has been still a slight overlap on these regions, as it was observed on the separated groups BT1, BT2 and BT3.

The Bhattacharyya distance was then calculated to quantify the data group separation visually inspected. The results on Figure 6 show that the separation between groups M1 and M3 are bigger, while the overlap is more evident between groups M1- M2 and M2-M3. Therefore, as the movements involved are more distant or different from each other, more the set of signals become separated in its own group or intra-class. This result was expected but the experiment, especially with BTG group, has showed the possibility of discriminating different sets of data from different tests and obtaining a reasonably understandable set of data, where classes and groups could be linearly separated.

5 CONCLUSIONS

Our experimental results have suggested that analyzing a given myoelectrical set of signals by descriptive statistical tools is a hard task due to a high data dimensionality and noise presence. Acquiring myoelectrical signals with superficial electrodes means to deal with a highly noisy susceptible set of data due to electrical variances of the skin and electrodes displacements during muscle movements. The use of linear transformation can make the multivariate data set analysis easier.

Considering the arm horizontal movement and the acquired set of data used in this research, a discriminant linear analysis showed that it is possible not only to characterize the angular joint position, but also to infer that different movements recruit similar amounts of energy to be executed.

Our experimental results confirm that using multivariate statistical analysis, myoelectric signal recognition can be significantly improved after linear transformations, which are practical and feasible methods to analyze such multivariate high dimension and small sample size data for further classification.

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