

A METRIC FOR RANKING HIGH DIMENSIONAL SKYLINE QUERIES

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Abstract: Skyline queries have been proposed to express user's preferences. Since the size of Skyline set increases as the number of criteria augments, it is necessary to rank high dimensional Skyline queries. In this work, we propose a new metric to rank high dimensional Skylines which allows to identify the k most interesting objects from the Skyline set (Top-k Skyline). We have empirically studied the variability and performance of our metric. Our initial experimental results show that the metric is able to speed up the computation of the Top-k Skyline in up to two orders of magnitude w.r.t. the state-of-the-art metric: Skyline Frequency.

1 INTRODUCTION

Currently, large amounts of data are made available using novel technologies in databases and computer networks such as Semantic Web, Grid, Semantic Search, and Cloud and Peer-to-Peer computing. For example, by the time this paper has been written at least 24.07 billion pages are indexed by the Web (De Kunder, 2010). The enormous growth in the size of data has a direct impact on the performance of tasks that process very large datasets and whose complexity depends on the size of the input. Even a very large subset from the input dataset may be irrelevant for the answer.

Skyline queries enable user's preferences to be expressed naturally and may identify useful data from datasets (Börzsönyi et al., 2001). Even though, Skyline may be a good choice for huge data sets, its cardinality may become very large as the number of criteria or dimensions increases (Bentley et al., 1978). Thus, the users have to be aware that a possibly large subset of the Skyline can be irrelevant and useless data must be manually discarded. Nevertheless, the size of the answer for high dimensional Skyline queries may be decreased. Users could limit the number of dimensions but this would require a domain knowledge expert. A better

solution is to efficiently identify which Skyline tuples are the k most interesting. Thus, a function to score the Skyline interestingness needs to be applied. This function may be defined by the user as a score function (Balke et al., 2004; Goncalves and Vidal, 2005, 2009; Brando et al., 2007) or may be a predefined ranking metric (Chan et al., 2006a; Chan et al., 2006b; Lin et al., 2007).

We focus on ranking metrics based on subspaces, such as Skyline Frequency metric (SFM) (Chan et al., 2006a). In this work, we propose a less expensive metric called Top-k Skyline Frequency Metric (TKSFM). TKSFM can be very useful in decision making applications that require a quick and efficient ranking metric. With the help of TKSFM, Skyline can be ranked according to interestingness of the user's criteria.

Finally, the remainder of this paper is organized as follows. Section 2 introduces the basic preliminary background information. Section 3 illustrates the SFM and the definition and explanation of the TKSFM. In Section 4, we report the results of our experimental study where the SFM and TKSFM metrics are compared. Section 5 points out conclusions and future work.

2 PRELIMINARIES

In this section we present five formal definitions of the basic concepts required to understand the foundations of Skyline and Skyline metrics. For these definitions we are assuming a space S on a set of n dimensions $\{d_1, \dots, d_n\}$, a subspace S' or non-empty subset of the space S , and a dataset DS on S . Also, we suppose a tuple $t \in DS$ is represented as $t = (t_1, \dots, t_n)$ where t_i is a real number on dimension d_i . For simplicity, we suppose all dimension will be preferred if they have the highest values (maximization).

Definition 1 (Dominance). A tuple $t = (t_1, \dots, t_n) \in DS$ dominates another tuple $u = (u_1, \dots, u_n) \in DS$ if $(\forall i \mid 1 \leq i \leq n : t_i \leq u_i \wedge (\exists j \mid 1 \leq j \leq n : t_j < u_j))$.

Definition 2 (Skyline). The Skyline of a space S , denoted as SKY_S , is the set of the non-dominated tuples on S .

Definition 3 (Skycube). The Skycube or lattice is the set of the all Skylines for any subspace S' of S , i.e., $Skycube = \{\cup SKY_{S'} \mid S' \subseteq S\}$.

Definition 4 (Skyline Frequency). The Skyline Frequency of a tuple $t \in DS$, denoted by $sf(t)$, is the number of subspaces S' of S in which t is a Skyline tuple, this is, $sf(t) = (\sum S' \mid S' \in S \wedge t \in SKY_{S'} : 1)$.

Since the Skyline can be huge (Chan et al., 2006a), the Skyline needs to be ranked by a score function to distinguish the top-k tuples in a set of incomparable ones. A score function of a tuple t , denoted as $f(t)$, is a function that ranks the tuple t inducing a totally ordered of the input dataset DS .

Definition 5 (Top-k Skyline). The Top-k Skyline tuples of a space S , denoted by TKS_S , are the k Skyline tuples on S that no other Skyline tuple on S may have higher score function value than them:

$TKS_S = \{t \mid t \in SKY_S \wedge \neg(\exists^{k-|SKY_S|} u \mid u \in SKY_S : f(u) > f(t))\}$, where, \exists^x means that exists at most x elements in the set.

The Skyline Frequency may be used as score function to rank the Skyline. In (Chan et al., 2006a), the Top-k Frequent Skyline tuples, denoted here by $TKFS$, are defined as the k tuples in DS that no other tuple in DS can have larger Skyline Frequency than them: $TKFS = \{t \mid t \in SKY_S \wedge \neg(\exists^{k-|SKY_S|} u \mid u \in SKY_S : sf(u) > sf(t))\}$.

3 SKYLINE METRICS

The three steps to compute the SFM metric are: 1) The Skyline for each subspace of the multi-dimensional criteria is computed; 2) The SFM of each tuple t is calculated by summing up the number of subspaces for which t is a Skyline tuple; 3) The Skyline is sorted by SFM values and the best k tuples are returned.

Unfortunately, Skyline Frequency has two disadvantages. On one hand, it may require to build a lattice of skylines for each non-empty subset of a multi-dimensional criteria, this is, $2^d - 1$ skylines (Chan et al., 2006a). In this sense, several solutions have been introduced to reduce cost of the lattice computation. In (Chan et al., 2006a), the authors proposed to estimate the Skyline Frequency values with efficient approximated algorithms. (Yuan et al., 2005; Pei et al., 2006) define algorithms to efficiently calculate the Skycube or the lattice of skylines by sharing computation of multiple related Skyline subspaces.

On the other hand, Skyline Frequency benefits those tuples that have the best value in at least one dimension. Any tuple with this characteristic will have a lower bound of $1 + \sum_{i=1}^{d-1} \binom{d-1}{i}$ when data are not duplicated. According to Corollary 1 in (Yuan et al, 2005), a tuple in a subspace s will be in all subspaces for which subspace s is a subset. For this reason, all of these tuples could have the same Skyline Frequency value (little variability).

To introduce variability into SFM, we propose a new metric called Top-k Skyline Frequency Metric (TKSFM). The basis of the lattice for TKSFM is the two-dimensional Skylines. Therefore, it does not benefit those tuples with the best value in at least one dimension as SFM does. Additionally, our experimental study shows that our metric is less expensive than SFM because it does not need to build the whole Skyline for each subspace.

To exemplify the difference between TKSFM and SFM, suppose a lattice for 4 dimensions: A , B , C , and D , as shown in Figure 1. SFM value of a tuple t is the number of times in which t is in a subspace of the lattice. Since the Skyline for each subspace must be calculated, the Skyline Frequency computation is very costly (Chan et al., 2006a).

Instead of the skylines for each subspace of the lattice, the lattice of the TKSFM is based on Top-k Skyline subspaces. Thus, the evaluation cost of the metric may be reduced because the Top-k Skyline is computed instead of the whole Skyline set (Goncalves and Vidal, 2009).

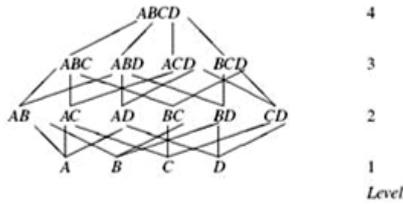


Figure 1: Lattice.

However, the Top-k Skyline subspaces require a score function to rank the Skyline (Goncalves and Vidal, 2009) in each subspace. We define this function as the number of times in which a tuple appears in any inferior subspace. Because the tuples that have the best value in at least one dimension could have the same Skyline Frequency value; we decide that infimum of the lattice will be composed of two-dimensional skylines to introduce variability in our metric. Therefore, the basis of TKSFM is the two-dimensional skylines at the lowest bound of the lattice and Top-k Skyline for superior levels.

3.1 Formal Definition and Computation

Given a space S defined by a set of n dimensions $\{d_1, \dots, d_n\}$, we define the Top-k Skyline Frequency Metric, denoted by $TKSFM$, through the recurrence given in the following definition.

Definition 6 (Top-k Skyline Frequency Metric).
(Base Case)

$$TKSFM_1(t) = (\sum S' \mid S' \in S \wedge |S'| = 2 \wedge t \in SKY_{S'} : 1)$$

(Inductive Case)

$$TKSFM_i(t) = (\sum S' \mid S' \in S \wedge |S'| = i+1 \wedge t \in SKY_{S'} \wedge \neg(\exists^{k-1} SKY_{S'} u \mid u \in SKY_{S'} : \sum_{m=1}^{i-1} TKSFM_m(u) > \sum_{m=1}^{i-1} TKSFM_m(t)) : 1) \text{ where } 2 < i \leq n-1.$$

The three steps to compute the TKSFM metric are: First, the Skyline for each two-dimensional subspace is calculated (Base Case). Second, the Top-k Skyline for each i -dimensional subspace is calculated based on the frequency or the number of times in which a tuple t appears in all m -dimensional subspaces, where $0 < m < i$, and $2 < i < n$ (Inductive Case). Third, the best k tuples that have the highest frequency will be returned.

4 EXPERIMENTAL STUDY

We conducted an experimental study to empirically analyze the variability of the TKSFM with respect to

SFM, and we study performance of lattice construction using each metric. The study was performed on a table of 10,000 randomly generated tuples. Each table contained an identifier and ten real values ranged from 0.0 to 1.0. The attribute values were generated following a uniform distribution.

We randomly generated 30 queries characterized by the following properties: (a) only one table in the FROM clause; (b) the attributes in the multi-dimensional function were chosen randomly among the attributes of the table; (c) the MAX directive was selected; (d) the number of attributes of the multi-dimensional function was between 7 and 10; (e) k value was chose to be 10 and 50.

We show the number of tuples in common between the two Top-k Skyline results obtained from applying TSFM and SFM metrics (variability) and time for constructing the lattice using both metrics. Time was measured using the time Solaris command.

The Bottom-Up Skycube (BUS) algorithm was implemented in Java (64-bit JDK version 1.5.0 12). BUS was proposed in (Yuan et al., 2005) to compute Skyline Frequency values by building the Skycube. We adapt BUS to calculate the TKSFM including the recurrence given in Definition 5. On the other hand, data were stored in relational tables using Oracle 9i. The experiments were evaluated on a SunFire V440 machine equipped with 2 processors Sparcv9 of 1.281 MHZ, 16 GB of memory and 4 disks Ultra320 SCSI of 73 GB running on SunOS 5.10 (Solaris 10).

We studied the common results that are matched by both metrics. Thus, we intersect the results sets obtained from both metrics and are shown in Figure 2 and Figure 3. The graphics illustrated in the figures show the number of common tuples retrieved using both metrics for Top-10 Skyline and Top-50 Skyline queries, respectively. In general, the number of common results using both metrics is between 40% and 80%. Thus, TKSFM introduces a difference between 20% and 60% with respect to SFM. This difference is because of SFM benefits tuples characterized by the best value in at least one dimension while the basis of TKSFM is two-dimensional Skylines.

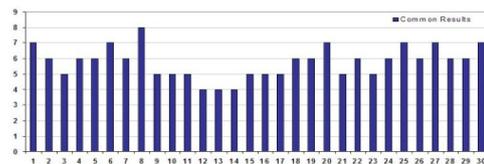


Figure 2: Number of Common Results for Top-10 Skyline Queries.

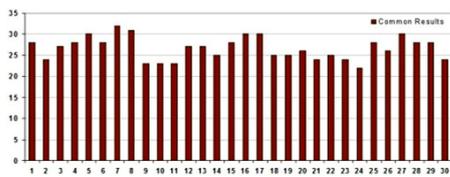


Figure 3: Number of Common Results for Top-50 Skyline Queries.

Also, we studied the performance associated with the lattice construction. Figure 4 and Figure 5 show the time required to build the lattice when TKSFM and SFM are applied. We can observe that time for TKSFM is up to two orders of magnitude higher than SFM. This overhead for SFM is because the algorithm computes the Skyline for each subspace completely. Furthermore, between 40% and 80% of the results obtained from TKSFM match the results obtained from SFM in less time.

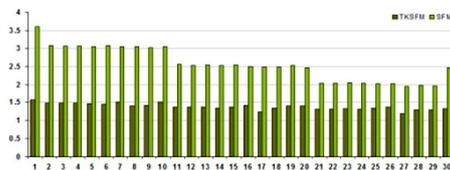


Figure 4: Time (seconds) for Top-10 Skyline Queries.

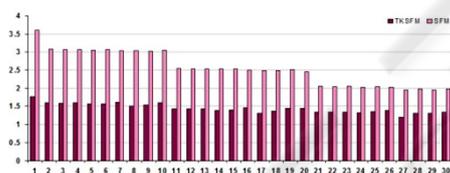


Figure 5: Time (seconds) for Top-50 Skyline Queries.

Finally, Table 1 shows the results for the t-test in terms of time. As the analysis of the t-test shows, the difference for time is highly significant (more than 99% level).

Table 1: t-test for time.

Average	k = 10		k = 50	
	TKSFM	SFM	TKSFM	SFM
	24.39	616.84	28.53	611.03
t-test(one-tailed, paired)	p-value=0.000091		p-value=0.000113	

5 CONCLUSIONS

In this work, the Top-k Skyline Frequency Metric has been proposed in order to rank high dimensional Skylines and its performance and variability has been empirically compared to the Skyline Frequency

Metric. Both metrics are based on subspaces, but TKSFM is less expensive and it has been thought to not benefit tuples that have only the best value in one of the dimensions. Experimental results show that TKSFM identify at least 40% and varies at least 20% of the results obtained from SFM. In the future, we plan to study the quality of our metric making a study in a real scenario using real data gathered from real users.

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