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Abstract: We succinctly summarise the various current approaches encountered in Policy-Based Control of Functional Networking within Cloud Structures by integrating these concepts with those of Profile generation, and generic environment representation, based on Entity-Relationship (ER) and Class-Based Modelling. The subsequent problems that this integration gives rise to are identified and discussed. We present a generic solution to these problems, which has been partially implemented, and show how this work is being extended using the concept of Abstraction Classes. We indicate further work to be undertaken in this area.

1 INTRODUCTION

In this paper we will initially outline current approaches by which policies and profiles are implemented in a network-based environment. This is followed by a description of the way in which policy/profile-based control systems are used to address specific types of problem in cloud process management in the context of Functional Domain (FD) design, together with abstracted system modelling. The current approaches give rise to various problems that to date are unresolved. This problem area is identified and discussed. To this end we describe a generic approach that has been used to implement a unified solution to these problems by way of a partial implementation. We conclude by outlining the future work currently in progress.

The organisation of this paper is as follows: in section 2 we identify current problems and present an overall approach to addressing these problems. In section 3 we present a generic design for the solution of the said problems, and finally we give a critique and conclusions in sections 4 and 5, respectively.

2 PRELIMINARIES

2.1 Current Approaches

A *domain* can simply be defined as a set of entities of a particular class within the controlling database structure representing a specific network operating system. For example, within the Windows 2008 Active Directory (Desmond and Richardson, 2009), a domain is simply a partition of the namespace that forms a security boundary (Neilsen, 1999). This is hosted within the Organisational Unit (OU), serving as the local domain container object. Conventional operating system domain membership normally applies to workstations and server classes of network nodes, where each such node may be a member of only one specified domain. This introduces an inherent limitation in the sense that domain membership cannot be fluid, and the properties of the node are therefore required to be rigid. For example.

Operating_System_Domain(x) = { Network Node(i) | (Network_Node(i).[VLAN] ∈ Domain(x).[VLAN])

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Figure 1: ER diagram from the main ER/Class cloud model introducing the FD concept.

$(1 \le i \le Max(Domain(x).[VLAN])) \land$ $(Domain(x).[OS] = Network_Node(i).[OS])$

Next we briefly look at a business system in the context of existing compute models (e.g. clientserver) and then within a cloud environment. A business system is loosely defined as a set of one or more processes which, when combined, address the requirements of a specific business problem. In the traditional client-server model such systems were implemented as one or more servers that were dedicated to hosting the required business system processes (Microsoft, 2001e). These were accessed over one or more networks by individual sets of workstations, whose functionality may have been mutually exclusive with respect to each other. Where the business process invoked requires heterogeneous systems access, then there is a problem with the current definition of the term domain, referred to earlier, with respect to policybased control (0 et al., 2002, Stegmann, 1997), and therefore the term functional policy domain or *functional domain* should be used instead (Figure 1) (Tezuka et al., 2000).

Throughout the paper the abbreviation *Abs* stands for Abstraction / Abstracted, *IPM* for Inter-Process Message and *FK* for Foreign Key.

This means that one dimension of the inheritance of policy-based data may be controlled through the specific business system being invoked by the client. One of the key problems that is encountered in the design and configuration of large-scale open enterprise systems (Sutherland and Van den Heuvel, 2002, Murray, 2009, Nezlek et al., 1999, Pereira and Sousa, 2004, Gorton and Liu, 2004, Arsanjani, 20020) is the lack of flexibility in the inherent

domain-mapping properties associated with the operating systems of the network nodes (Figure 2). This is combined with the properties relating to the concept of ownership that are inherent within the control structure of a domain; the domain is also in turn normally tightly-coupled to either the operating system or the network operating system of each network node, such as Active Directory (Desmond and Richardson, 2009) in the case of the Windows operating system or X.500 (Chadwick, 1994) in the case of Unix. This situation leads to an inherent problem in that control structures formed through the use of policies and profiles have to be repeated for each operating system domain and between each level of integration with the target network node or network group. Where the design of a network domain follows a strict, yet standard, hierarchy in accordance with a relatively simple and repeatable QMS (Quality Management System) requirement model, there is a 1:M relationship between the operating system/control system (e.g. Active Directory) and the network node. There is also a $1 \cdot M$ relationship between the operating system/control system and the associated business systems. Both of these relationships do not lend any significant degree of flexibility to their environment, and as such are not specifically suited to fulfilling the role of a control system within a cloud.

2.2 New Approach

To date the modelling which has been proposed for the basic inter-communication management structural methods, within the structure of a cloud, uses the concept of abstraction classes (Eccles and Loizou, 2010a, b) within the context of large-scale



Figure 2: ER subschema showing the relationship between the FD concept and a conventional domain structure.

CIENCE AND TECHNOLOGY PUBLICATIONS enterprise design structures. The next level of structure that we propose is termed the Functional Domain (Figure 1), and constitutes a logical area within an Enterprise Domain (ED) that is defined by the constraints of that domain or as a consequence of the design policies that together define the properties of that FD

The class of ED that is proposed to utilise a set of related component structures, such as FDs, is that of a cloud (Figure 1). The set of application components linked to an enterprise function is called the FD of that enterprise function (Wendt et al., 2005). The elements of an FD require functional integration with regard to the enterprise function given. The given set of enterprise functions correlates with the set of abstraction classes referred to above. These may be integrated with respect to their joint class of function by association with one or more individual FDs (Figure 3, Figure 4). As such, the resultant properties of the abstraction class may vary as a consequence of belonging to a specific FD, and the variation of these properties is expressed via the policy or policies associated with that specific FD. The FD may be enabled as part of the design structure for the virtualised cloud environment, and the methodology and design structure for this are the subject of a future paper. Such a policy may be modified by being part of an operational policy class (Figure 3), which therefore enables what is being invoked as opposed to how such an invocation process is taking place.

A key operational requirement within an environment, such as a cloud, is to be able to have a control system that can take advantage of the dynamic nature of such an operational scenario. One of the key attributes of the concept of the FD, referred to in this paper, involves the M:M relationship to a business system (Figure 2). This gives the required degree of flexibility necessary to enable multiple business systems functions (e.g. services) to relate to multiple degrees of control structure on a peer-to-peer basis in conjunction with hierarchies within a cloud. This naturally leads to the following formalism for the logical representation of the properties of a generic FD; namely,

 \forall Network Node(x_i) \exists { Functional Domain(y) | Network Node(x_i) \in {Functional Domain(y)} \land ((1 \leq y \leq Max(Functional_Domain(y))) $\wedge (1 \leq x_i \leq Max(Network Node(x_i))))$ \wedge ((Network Node(x_i)) \in {Business System.Node(a_i)}) \land (1 \leq a_i \leq Max(Business System.Node(a_i)))) \land ((Business_System.Node(a_i)) \in {Functional Domain(y).BusSys(z)}) $\wedge (1 \leq z \leq$ Max(Functional_Domain(y).BusSys(z)))) }

The concept of the FD, as it is herein presented, enables the requirement that a node may belong either to different domains within an operational session, depending on the set of abstracted processes



Figure 3: Abstraction Classes (VMs) in a cloud structure realised within the context of FDs and associated operational policies. The metadata contains the definition of the operational policies, the location of the classes of operational functions and the application of each such function within each host FD. These functions are accessed directly by the IPM modules, using local policies specific to each IPM or IPM Class ID within an FD, Operational Policy (OP) area.

being invoked; or alternatively, it may be a member of more than one domain simultaneously. By abstracting the concept of the network node (Figure 5) within a cloud, each Network_Node object can be associated with different subclasses of abstracted cloud classes, such as those of users, user groups or workstations (Figure 9)

3 DESIGN OF A GENERIC APPROACH

There is a great degree of overlap in the structure and the basic design of a cloud when compared to a large-scale open enterprise system.

Many current definitions, and in some cases working models of systems, described as clouds, essentially comply with this basic characteristic (Traore and Ye, 2003). The additional characteristics of sets of services are presented as accessible utility functions. However, it is also reasonable to assert that a cloud differs from a large-scale open enterprise system in that the internal structure may vary in both its apparent architecture and in the presentation over time on a dynamic basis. Therefore, the points of reference used for internal processing, and which may be available to external events, may also vary in their nature and in their location, leading to variations in the complexity of cloud systems. Such variations may depend on the interaction between other clouds and external events. This is further complemented by the goal of making all functional attributes of a cloud abstracted with reference to the means by which they are accessed or referred to.

En passant we note that the initial focus for the concept of FDs originates from an analogous concept that is used in the field of protein structure research (Bajaj et al., 2011). In this area rather than using the amino acid composition to represent a protein sample, the FD composition is introduced to incorporate the sequence order-related features (Vlahovicek, 2001, Chou and Cai, 2004). Therefore, a protein is now represented in terms of the FD composition in a lower-order memory space, incorporating not only some sequence order-related features within the representation.



Figure 4: ER diagram for the control policy attributes within the cloud metadata that is responsible for governing the operation of the FDs and the associated classes of NNs.

When a cloud is modelled by using a subset of methods used for modelling other analogous systems, the resultant artifact exhibits some interesting properties.

One of the properties of the concept of an FD is that of using it as an integral part of the generic control structure, described later in this paper (Figure 7, Figure 8), involving the use of policy combined with event trapping in the context of one or more sets of FDs, in order to produce an input event command profile. Thus in order to achieve this in a manner most applicable to each class of event, it is required that the most appropriate class of control policy be applied at the most relevant point within the cloud. This is made possible through the use of the layered metadata used to co-ordinate the control management mechanisms within the cloud. The sets of ER diagrams included in this paper are subschemas taken from the overall metadata model of the cloud and its associated management structures.

Some parts of the metadata database refer to the nature and function of the said policies with reference to their respective FDs (Figure 3), whilst other parts form subschemas that relate to the different aspects of the cloud and the control structures (Figure 2) that are formulated for its management through the use of integrated frameworks (Traore and Ye, 2003). An example of these are abstraction classes (Eccles and Loizou, 2010a, b). Within these ER diagrams can be seen many instances of policy as they are applied to a specific target entity (e.g. NN_AC_Policy_ID applied to a specific Network_Node abstraction (see Figure 4), where NN stands for Network Node).

Thus, using the metadata ER design model (see Figure 3), it becomes possible to finely tune the policies with respect to both their content and their direct applicability to the subject area to which they are to be applied. (Policies are software-enabled devices that enable a single instance of the declaration of one or more rules concerning the state of the environment in which they apply.)

It must be noted that the full model for the design of the cloud, referred to in the discussion, incorporates a much more complete range of techniques taken from the Unified Modelling Language (UML) (Bjorkander and Kobryn, 2003) and the Business Process Modelling Notation (BPMN) (Caetano et al., 2007). It must be observed that in order to incorporate the output artifacts from these techniques within a control metadata database that is accessed by event-driven policies, for practical realtime use, it is required to represent the artifacts emanating from these techniques in a relational manner using an ER model. The full methodology for the proper design and construction of a cloud is currently being developed, as we continue to develop the management and control structures extending and modifying through certain architectures and standards for large-scale open



Figure 5: ER diagram representing the generic abstraction of different network entities related to the common entity Network_Node.



Figure 6: ER diagram from the model of a cloud structure illustrating the abstracted nature of different classes of cloudbased conceptual structures.

enterprise systems in order that they may be applied to a cloud.

Control policies may be enabled with reference to many different classes of Network_Node entity, such as users, workstations and servers. In order for the cloud model being developed to be correct with respect to the characteristics described earlier, it becomes essential to refer to the cloud components in an abstracted sense, as shown in Figure 4 and Figure 5, where NIC stands for Network Interface Card, Con stands for Conceptual and Sw stands for Switch. This concept is extended further in Figure 6 (SW stands for Software), where the functional constructs hosted by the cloud, such as clusters, applications, different classes of service objects are also defined in an abstracted manner, each as part of an FD.

In general, policies are used within specific FDs and, for the most part, are applied to relatively simple areas within those domains, such as user and workstation configuration control. Within this context, the general use of policies is either to control the presentational level of processes, or to control how their management may be restricted with respect to their operating environment. Policies may be applied using whatever form of ruleinterpretation is best suited to the local environment, viewed in an abstracted manner. These policies may in turn be associated with Active Directory objects, such as sites, domains or OU's (Desmond and



Figure 7: An intra-cloud dataflow structure employing an input (user) event, a control policy from the relevant FD, and a resultant control profile in the selection of an abstracted (user) application.

Richardson, 2009, Allen and Lowe-Norris, 2003, Allen, 2003). System policies enable local registry values to be overridden with settings specific to the particular process being addressed. Control policies are defined in a policy file, normally located in an area that is accessible to the requesting process.

The policies enabled through the use of FDs are closer to the class of Control Policies than, for example, the class of firewall policies (Lee et al., 2003, Lee et al., 2002). As such, these are more in keeping with the class of policy that may be utilised in control structures such as those encountered in the SOA context model (Zhou and Liu, 2010).(In Figure 7 VDI stands for Virtual Desktop Interface).

An example of such a class of process is the Application Abstraction: Control Policy Determination that is shown in Figure 7. As a result of such a process, a resultant policy is formulated from the system policy settings and the user policy and/or default settings in the local registry (Microsoft, 2001a), depending on the relative security settings of each class of policy owner. Based on the appropriate control structure, the instance of this latter resultant process produced from the Control Policy Determination process results in the formulation of the system profile, which controls the target process to be accessed

(Figure 7). Figure 7 represents an example of a standard method of invoking abstraction classes within a cloud structure using events that are formulated such that the event class, the policy acquisition, the profile generation and the associated functional access are all derived at the abstract level. Initially on receipt of the initial input event class (e.g. a logon process), the local configuration information is checked for the location of the policy file (Microsoft, 2001b). The policies are then downloaded by initially checking as to whether the event profiles are enabled. If so, the policy file is searched for the relevant event and, if found, then the event-specific policy is enabled. If not then the default user policy is enabled (Posey, 2001). If group policy support (Microsoft, 2001c, d) has been enabled, then it is established as to whether the user is a member of any of the relevant set of groups. If so, then the group information is downloaded beginning with the lowest-priority group and ending with the highest, thereby enabling the data belonging to the latter group to supersede the rest. This is then copied to the registry of the abstracted host, or its equivalent. The policy file is then checked for information pertaining to the relevant abstracted host. If this exists, then the relevant policies are applied to the environment of the abstracted host.



Figure 8: A low-level view of the interaction between the FD (Functional_Domain(index_j)), Policy (Operational_Policy(index_k)) and Events to produce the control structure by way of an Operational Policy for the Functional Operation.(Cf. Application Abstraction:Control Policy Determination in Figure 7).

Network-based policies within a cloud, controlling the interpretation of event class information and the actions that are undertaken as a consequence of such events being invoked, are examples of threshold management applications. An example of this is Threshold Manager (Cisco, 1997), which allows thresholds to be set and retrieves event information. Thresholds can be set for targeted abstracted nodes using threshold policies, implemented as sets of configuration data that specify the conditions for triggering a threshold event for a particular management attribute affected across a particular node given certain constraints (Microsoft, 1997, Microsoft, 2001c, e).

An event is essentially a change of state of a system, where the quantifying of the degree of change of the system depends on both the class of the event and the environment within which it occurs. That is to say, both the nature of the event and the method of its measurement will depend on the class model of the relevant event and the class of FD within which it occurs. All captured events are related to the values of threshold-related events and then cross-referenced to the user-configured threshold policies.

In Figure 8 we have determined to clarify the explanation of the represented dataflows by labelling each of the said dataflows from 1 to 10. These are referred to in the ensuing text as, for example, (1), (2), etc.

As shown in Figure 8, an abstracted input event from a source other than an abstraction class is examined by the policy control interface (1). This uses the class-based control policy in conjunction with the determined class of event to generate the appropriate trigger for the operational profile generation (2). This operational profile is to become part of the protocol of the generated event (3), so as to enable correct operation within the context of the FD of the next abstraction class (6). This event action may also be directly input through the use of an abstraction class (4) or indirectly input through the latter set of processes, if there is a requirement for an operational profile to be generated (5). The control policy sets the thresholds (7) that are set for the class of input events (e.g. Systems Network Management Protocol (SNMP) events), generated from the local Management Information Base (MIB) database variables, which exist in the local environment controlled by the specified FD.



Figure 9: ER subschema to show how the abstraction of the Network_Node entity is conceptually related to the abstracted layer of equivalent network entities with a 1:1 relationship.



Figure 10: ER subschema of a cloud model showing the entity Abstracted_Server and how this is related to physical /virtual servers irrespective of their operational state within a dynamic cloud environment.

The profile is generated as a consequence of the specific FD (2) adapting the local control policies in accordance with its own internal policy, producing a localised profile control structure for the input event classes. The generated event calls the next abstraction class in the relevant sequence of abstraction classes derived from the controlling metadata (Figure 3). In Figure 8 this next abstraction class locates an instance of an object that will perform the functional operation required (8), which is itself influenced by the operational layer class policies (9) in conjunction with the current FD (10). This leads to the production of a set of abstracted levels of technical (business) systems within a cloud model; these systems lead to the simplification of the management of the sets of their points of control. An initial example of this is given in Figure 10, where the entity Abstracted Server is the point of control that relates to the Server technical business system. This is then related to the entity Functional_Domain by way of the entity Network_Node in Figure 9. It is thus demonstrated how the dynamic properties of a cloud, referred to earlier in this section, may be expressed by means of the entity Operational_Server_Instance via the use of the attribute Operation_State. This enables simple centralised control at an abstracted level of the different classes of server, where the current practical requirements of implementing that specific server, or set of servers, change depending on whether the servers in question be physical or virtual.

As a result of the salient concept of FDs, there is an associated class of control policy (Functional_ Domain_Policy_Set) that relates each FD and the abstraction class of each Network_Node, as shown in Figure 9. Each such policy interacts with the



Figure 11: ER subschema from a cloud model to show how the abstraction of an application can be used to control the nature of the implementation interface depending on the entity Selection_Control_Policy and the process Application Abstraction : Control Policy Determination in Figure 7.

policy for the abstracted Network_Node as shown in Figure 9 (Net_Node_Abstraction_ Class_Policy). The latter policy will inherit from the former in order to produce a resultant policy for the specific abstracted Network_Node class with respect to the FD in which it is located (De Bruijn and De Vreede, 1999). This process is more complex than it seemingly is, due to the possible M:M relationship between the entities Functional_ Domain and Network_Node, implemented as the control entity Func_Dom_Node_Membership in Figure 9.

As shown in Figure 12, this design is put into practical use by means of a generic architecture that produces a system able to operate within a cloud environment as well as a large-scale virtual/physical environment. This system is designed to utilise virtualised applications rather than install them on a target network node, typically a workstation. Utilising this mechanism within an FD- controlled cloud environment may result in the location of the virtualised applications shifting with FD policybased rules, due to the dynamic nature of the cloud. It is also the case that as the access mechanism for the virtualised applications is abstracted, there is no need to change the initial function call made to the application via the Initiator Process Node in Figure 12, nor to the target node (e.g. workstation/server), since both are abstracted (Figure 5). This gives the initial basis for a very flexible management system that is intended to serve as the basis for a control system employed for a cloud construct currently

under development. A prototype of this design construct is now under development / testing.

4 DISCUSSION

Once a virtualised environment has been properly developed as a computing resource for a specific business, or set of businesses, a new set of problems emerge which are only now being recognised and addressed. To begin with, the methodology and associated modelling structure must now become an intricate part of the active operational structure as well as the more passive system management, since the idea of the total replacement of layers of the system will no longer be applicable. Therefore, the complete set of artifacts used to model and design the full range of components contributing to a cloud control and management system must be implemented as a data model. In practice this becomes a distributed system and is the subject of impending future research.

Finally, there is a need for subsequent research concerning the integration of the concept of functional policy domains with different networkbased operating systems. This must be extended to deal with policy integration between different domains (FDs) and between different types of such domains in the context of a network environment. This is being addressed by designing policies and network-based systems in an abstracted manner.



Figure 12: Summary diagram showing a generic control-flow system for the activation of an application by either Presentation or Streaming mechanisms within the context of one or more FDs.

5 CONCLUSIONS

We have shown how formulating a set of simple extensions to the object control policy methodology by using the concept of FDs can produce the basis for a policy-based network, which governs not only how an object is initiated, but introduces seamless flexibility into specifying which class of the functional application should be invoked. This can be tested using a cloud model, which is being produced from an evolving cloud development methodology; this is the subject of an upcoming paper.

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