Analyzing UML Activity and Component Diagrams An Approach based on COSMIC Functional Size Measurement

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Abstract:

UML is a widely used modeling language that offers a set of complementary diagram types used to describe a system according to different views, such as the functional view, the dynamic view and the static view. This multi-view modeling can induce inconsistencies between UML diagrams. This paper presents a COSMIC-based approach for analyzing and checking the consistency between the activity diagram and the component diagram. First, it elaborates a set of procedures for the COSMIC Functional Size Measurement of each diagram. Secondly, it proposes a set of heuristics, based on the semantic relations between these two diagrams, to assist developers in predicting the range of the FSM values of the component diagram from those of the activity diagram. The set of measurement procedures and heuristics are illustrated through the "Rice cooker" case study.

1 INTRODUCTION

Thanks to its various diagram types, UML provides for a multi-view representation of user functional requirements, system structure, and dynamic behavior. Nonetheless, the diversity of UML diagram types can introduce inconsistencies among the various diagrams representing the same system. Evidently, these inconsistencies may lead to errors, high development costs, and potentially software failures. Thus, it is vital to have an approach for ensuring the consistency among the various UML diagrams modeling the same system.

To detect inconsistencies among UML diagrams, several approaches have been proposed either based on meta-modeling (Chong et al., 1999), or based on the adoption of formal methods (Sengupta and Bhattacharya, 2008). The first category of approaches examines only the syntactic constraints among the UML concepts; the second category relies on the semantic constraints among the UML concepts and requires a certain level of expertise in the formal method used. In addition, none of them provides for a means both to detect potential inconsistencies and to estimate functional size attributes of one diagram from another already elaborated. Such a means can be offered through a measurement method. In this paper, we illustrate the

feasibility of such an approach by using the functional size of software.

In the software measurement literature, to measure the functional size of software applications, five measurement methods have been recognized as standards: IFPUG (ISO/IEC 20926: 2009), MKII (ISO/IEC 20968: 2002), NESMA (ISO/IEC 24750: 2005), FiSMA (ISO/IEC 29881: 2008), and COSMIC (ISO/IEC 19761: 2011). The main advantage of the functional size measurement (FSM) of COSMIC is its ability to quantify software from a user's point of view independently of any quality and technical criteria. In addition, compared to other international measurement methods, COSMIC is designed to be applicable to any type of software. These advantages motivated several researchers to investigate the use of COSMIC to determine the functional size of UML-diagrams.

Current proposals to use FSM for UML focused on particular diagrams, *e.g.*, the use case diagram (Sellami and Ben-Abdallah, 2009), (Lavazza and Bianco, 2009), (Berg et al., 2005), (Azzouz and Abran, 2004), and (Bévo et al., 1999); the sequence diagram (Sellami and Ben-Abdallah, 2009), (Lavazza and Bianco, 2009), (Azzouz and Abran, 2004) and (Bévo et al., 1999); the activity diagram (Berg et al., 2005); class diagram (Sellami and Ben-Abdallah, 2009), (Lavazza and Bianco, 2009) and

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(Bévo et al., 1999), or the component diagram (Lind, 2011) and (Lavazza and Bianco, 2009). Except for (Sellami, 2009) and recently (Lind, 2011), these proposals treated UML diagrams in an isolated way. In addition, the UML-Activity Diagram (UML-AD) has not been explored in detail, despite its importance in representing behavioral aspects of software. Similarly, the UML-Component Diagram (UML-CD) has not been treated in spite of its advantage in component reuse especially for the development of complex applications.

This paper has a two-fold contribution. First, it completes our previous work (Sellami, 2009) which focused on the functional size of the UML use case diagram as a reference measurement for the FSM of the sequence and class diagrams. In this paper, we use the COSMIC method to measure the functional size of the UML-AD and UML-CD diagrams. Secondly, it proposes a set of heuristics that provide for both verifying the consistency of these diagrams in terms of functional size, and estimating a bound on the functional size of one diagram from a developed diagram. Such an estimate can be used for instance in a time/effort evaluation process.

The remainder of this paper is organized as follows: Section 2 presents an overview of the COSMIC method and existing proposals for COSMIC FSM of UML diagrams. Section 3 and 4 present, respectively, the proposed measurement procedure required for measuring the functional size of UML-AD and UML-CD with the proposed heuristics. Section 5 illustrates the application of these measurement procedures by using the "Rice Cooker" case study (COSMIC Group, 2008). Finally, Section 6 summarizes the presented work and outlines some further works.

2 RELATED WORKS

2.1 Overview of COSMIC FSM

COSMIC has been widely used in order to measure software functional size, which is derived by quantifying the Functional User Requirements (FUR) (ISO/IEC 14143-1: 2007). FUR is a sub-set of the user requirements, that explains what the software must do to satisfy user needs. COSMIC is developed to overcome limitations of initial FSM methods such as Function Point Analysis. It is designed to be used to measure functional size of real-time software, business application software, etc. It has been accepted as an international standard ISO/IEC 19761 since 2003. The COSMIC measurement procedure includes three phases: measurement strategy, mapping, and the measurement.

As illustrated in Figure 1, COSMIC covers four types of data movements (Entry, Exit, Read, and Write). The exchange of data across the boundary between users and software components causes an Entry data movement type (E: from a functional user to the functional process), or an Exit data movement type (X: from a functional process to the functional user). On the other hand, the exchange of data between storage hardware and software component causes a Read data movement type (R: from a persistent storage to the functional process), or a Write data movement type (W: from a functional process to the persistent storage).



Figure 1: Different data movement types in COSMIC.

In the COSMIC measurement phase, every data movement is assigned to 1 CFP (Cosmic Function Point). The software functional size is computed by adding all data movements identified for every functional process (ISO/IEC 19761: 2011).

2.2 COSMIC for UML

Among the researchers that studied the use of COSMIC to measure the functional size of UML, (Bévo et al., 1999) investigated the mapping between concepts of COSMIC 2.0 and those of UML 1.0. Their investigation was presented through the FSM of a building access system modeled with the use case, sequence and class diagrams. Being presented through an example, it lacked the coverage of some concepts like the triggering event which enduces one CFP. This study reports the issue of identifying the appropriate UML concepts to represent the COSMIC functional process, and then identifying the appropriate level of granularity.

(Azzouz and Abran, 2004) also treated the UML use case, sequence and class diagrams. They proposed an automated functional size measurement procedure of these diagrams when developed according to the Rational Unified Process. Their tool, COSMIC-RUP, is integrated in Rational Rose. It was used to measure the functional size of two case studies "Rice Cooker" and "Valve Control". However, the results obtained by COSMIC-RUP differ by 1 CFP from those obtained by a manual measurement for each case study. Furthermore, the proposed measurement procedure does not account for the COSMIC "system layers" concept which is important to identify the functional processes of a system under measurement.

On the other hand, (Berg et al., 2005) showed that UML can be used to present FUR at four levels of refinement: Goal-level requirements, Domainlevel requirements, Product-level requirements, Design-level requirements. In every level, they assume that particular UML diagrams are used to model the software. In addition, (Berg et al., 2005) also showed that the functional size can be determined using measurement methods such as Function Point Analysis (FPA) and COSMIC-Full Function Points (COSMIC-FFP) in the third level. In this level, they used the use case diagram, activity diagram and class diagram. The proposed measurement approach is illustrated through a case study "The Hotel Case". Despite being the only study treating UML-AD to model the behavioral view of software, the provided measurement approach did not investiage several details of UML-AD.

(Lavazza and Bianco, 2009) studied the functional size measurement of the UML use case, sequence, and component diagrams by using COSMIC. Similar to the previous works, their measurement process relies on a mapping of the COSMIC concepts onto the UML diagram concepts. It was illustrated through the FSM of the "Rice Cooker" real time software. However, the UML-AD of the "Rice Cooker" was not measured despite its usefulness in representing system details and interactions between the system and its actors.

Unlike the above works, (Sellami and Ben-Abdallah, 2009) considered that the semantic links among the various UML diagrams of a system model must be respected in any measurement process. First, they presented an approach to measure the functional size of the UML use case diagrams. Then, they propose to use the functional size of the use case diagram as a reference measurement for the sequence and class diagrams. To overcome the high level of abstraction of the use case diagrams, the authors used an intuitive documentation of the use cases proposed by (Ali and Abdallah, 2006). The produced measurement can thus be used to verify the consistency of the the use case diagram with the the functional size of the sequence diagrams. The proposed approach was verified using a business application "ALLOC" (Gabay and Gabay, 2008).

Also exploring the semantic links among UML diagrams, (Lind et al., 2011) developed a tool "CompSize" to provide the functional size of the component diagram (UML-CD). For this, they extended UML-CD to represent necessary information. However, their measurement process defines data movements independently of the software boundary, which may lead to incorrect results.

In summary, as shown in Table 1, most of the researches proposed mappings between COSMIC concepts and some UML diagrams. None of these studies considered *all* COSMIC concepts. In addition, further work is needed to explore the semantic links among UML diagrams types to provide for a confrontation/estimation/consistency verification among the different diagrams modeling a given system.

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COSMIC concepts	(Lind,	(Sellami,	(Lavazza,	(Berg,	(Azzouz,	(Bévo, 1999)
-	2011)	2009)	2009)	2005)	2004)	
Application border	Component	Use Cases				
boundary		Sequence	Component			
System layers	Component	None	None	None	None	None
Functional User	Component	Use Cases				
		Sequence	Component			
Triggering event	None	Use Cases	Component	Activity	Sequence	Scenario
Data group	None	None	Component	Class	Class	Class
			Class			
Data attribute	None	None	None	None	Class	Class
Functional Process	Component	Use Cases	Sequence	Activity	Use Cases	Use Cases
		Sequence	Use Cases			
	Component	Use Cases	Sequence	Activity	Sequence	None
Data Movement		Sequence				
		Class				

Table 1: Summary of the proposals mapping COSMIC on UML.

3 MEASURING UML-AD

3.1 Modeling Rules

To model an UML-AD that can be measured using COSMIC, we propose 12 modeling rules. These rules are inspired from "good design practices" and are intended to eliminate certain inconstancies. Modeling rules are defined to make the application of COSMIC concepts easier. The first three rules (R1, R2 and R3) are required at the functional level whereas the remaining rules (R4 to R12) are used at the dynamic level.

- R1: Represent all system processes and the relationship between them at the functional-level.
- R2: Any component or user that interacts in the realization of a process is considered as an actor in the UML-AD.
- R3: If the activity requires incoming information or a condition that must be satisfied, it is considered as a pre-condition.
- R4: Each functional process will be represented by an activity diagram.
- R5: Each external actor (system user) is represented by a partition.
- R6: Any internal actor is represented by a partition.
- R7: All actions performed by the same actor are grouped in the same partition.
- R8: Any action requires retrieved or written data from/to a persistent storage; it must be associated to an object node that contains the data to be used.
- R9: Avoid the transitions between the actors and the system when they are intended to indicate a possible end of the functional process (failure or success).
- R10:Every guard condition is considered as a trigger event of its corresponding action.
- R11:Action data recovery and action of writing data are differentiated by the direction of the transition.
- R12:If the action requires incoming information that must be satisfied, it is considered as a precondition.

Note that it is required to distinguish between external actor's partition and system's partition (internal actor). This distinction can be indicated by a description of the actor's attribute.

3.2 Mapping COSMIC on UML-AD

Measuring the functional size of an UML-AD

needs to define the mapping between the COSMIC concepts and those of UML-AD. As listed in Table 2, the mapping deals with the identification of functional users, boundary, functional processes, etc.

Table 2: Mapping of COSMIC on UML-AD.

COSMIC	UML-AD concepts
V.3.0.1	
Functional	Actor who interacts with the system
User	
Boundary	Conceptual line between the system
	partition and actor partition
Functional	An executable activity node
Process	presented in the first level
Triggering	Pre-condition of an activity
Event	Guard condition in a decision or a
	fusion node
/	Pre-condition of an action
Persistent	Object node: Storage
Storage	
Transient data	Object node: Pins
group	
Entry	An incoming data (from actor
	partition to system partition)
Exit	An outgoing data (from system
	partition to actor partition)
Read	Read access from an object node
Write	Write access to an object node

3.3 FSM Measurement Formulas

At the functional level, an UML-AD A consists of a set of activities. Each activity is a functional process. Thus

$$FSM(A) = \sum_{i=1}^{n} FSM(a_i)$$
(1)

where:

- FSM (A): functional size of the UML-AD A.
- *n*: the number of activities in $A(1^{st} \text{ level})$.
- FSM (**a**_i): functional size of the activity **a**_i (2nd level).

At the dynamic level, an activity \mathbf{a}_i consists of a set of actions **act** $_{ij}$. According to (Knieke et al., 2008) in this level, an activity is made by at least one action, an end node, and an initial node.

Thus, the functional size of an activity \mathbf{a}_i is given by:

$$FSM(a_i) = FSMcond (Precond a_i) + \sum_{j=1}^{m} FSM (act_{ij})$$
⁽²⁾

where:

• FSM (a_i): functional size of the activity a_i.

- *m*: is the number of actions act_{ij} of the activity a_i (2nd level).
- FSM (act_{ij}): functional size of the action act_{ij} of the activity a_i (2nd level). (3).
- FSMcond (Precond a_i): functional size of the precondition of the activity a_i. (4).

The functional size of an action **act**_{ii} is given by:

FSMcond (Precond act)

$$FSM(act_{ij}) = FSMcond (Precond act_{ij}) + FSMparam (Param act_{ij})$$
(3)

where:

$$\begin{cases} 1 \ CFP & if \ act_{ij} \ has \ a \ pre-condition \end{cases} (4) \\ 0 & otherwise \end{cases}$$

FSMparam(Paramact_{ij})= {1 CFP if act_{ij} has input/output parameters (0 otherwise

If an action is preceded by a decision or a fusion node, then the guard condition is considered as a trigger event. It is necessary to add 1 CFP to action's size.

$$FSMcond \ (Condgarde) = \begin{cases} 1 \ CFP & if \ act_{ij} \ has \ a \ guard \ condition \\ 0 & otherwise \end{cases}$$
(6)

When the end of an action in an Actor partition causes the execution of an action in a System partition, then the control flow corresponds to an Entry data movement. However, if the end of an action in a System partition causes the execution of an action in an Actor partition, then the control flow corresponds to an Exit data movement. Hence,

$$FSMactTyp(actTyp) = \begin{cases} 1CFP & if the actTyp corresponds to the \\ particular case of actions \\ 0 & otherwise \end{cases}$$
(7)

4 MEASURING UML-CD

4.1 Mapping COSMIC on UML-CD

Establishing a mapping between the COSMIC concepts and those of UML-CD is needed to

facilitate the measurement of the UML-CD functional size. Our mapping is inspired from the proposition of (Lavazza, 2009). Table 3 shows the mapping between concepts of COSMIC and those of UML-CD.

Table 3: Mapping of COSMIC on UML-CD.

UML-CD concepts
External entity directly connected with the
system components
Frontier between external components and system components
Operation in a system interface invoked
directly by an external entity
Classes: physical components
Data across the system boundary,
interface's operations or parameter's
operations
Set of operations, in one or more interfaces,
carrying out a process
Operations in a required interface directly
connected to the system
Operations in a provided interface directly
connected to the system
Get type operation in a system component
Set type operation in a system component

4.2 FSM Measurement Formulas

Data movements in an UML-CD are represented by interface's operations across the boundary, and operations in a system component. The functional size of the UML-CD (C) is given by:

$$FSM(C) = \sum_{i=1}^{n} FSM(S_i) + \sum_{j=1}^{m} FSM(I_j)$$
(8)

where:

- FSM (C): functional size of the UML-CD (C).
- FSM (S_i): functional size of operations in a system component.
- *n*: number of the system components.
- FSM (Ij): functional size of required and provided interfaces.
- *m*: number of the interfaces required and provided in (C).

The functional size of operations in a system component is given by:

$$FSM(S_i) = \sum_{j=1}^{y} FSM_{op}(Op_{ij})$$
(9)

where:

• FSM (S_i): functional size of operations in a system component.

- y: number of operations in a component system.
 (i=1,...n)
- FSMop (Op_{ij}): functional size of the operation Op_{ij}. (1CFP)

The functional size of required and provided interfaces is given by:

$$FSM(I_j) = \sum_{k=1}^{z} FSMop(Op_{jk})$$
(10)

where:

- FSM (I_j): functional size of required and provided interfaces.
- z: number of operations in the interface I_j . (*j*=1,...*m*)
- FSMop (Op_{jk}): functional size of the operation Op_{jk}.

4.3 Correspondence between UML-AD and UML-CD

Equation (11) can be used to verify the conformity between an UML-AD A and an UML-CD C in terms of COSMIC FSM:

$$2 \le FSM(C) \le FSM(A) \tag{11}$$

The UML-AD is composed of at least one actor and a system, an initial node, an end node, and a set of actions. In the second level of abstraction, a UML-AD represents a functional process. Based on COSMIC concepts, a functional process is composed of two data movement (Entry and Exit or Write). Therefore, the FSM of a UML-AD is at least equal to 2 CFP, i.e. (FSM (A) \geq 2 CFP). On the other hand, the FSM of an UML-CD is always less than the FSM of an UML-AD. Hence, FSM of an UML-CD is at least equal to 2 CFP. The maximum size of an UML-CD depends on the size of the UML-AD.

Equation (11) gives a confrontation means of both diagrams in terms of COSMIC FSM. Besides this high-level FSM boundary confrontation, we propose the following five heuristics to ensure the consistency in terms of COSMIC FSM between UML-AD and UML-CD:

ConsR1: Any partition representing an actor in UML-AD is a component in the UML-CD.

ConsR2: Any action in a partition is represented by a method in an interface.

ConsR3: Input/output pins in the UML-AD correspond to the input/output parameter's operations in the UML-CD.

ConsR4: Object nodes in UML-AD are represented by class's components in UML-CD.

ConsR5: Pre and post-conditions of an action in UML-AD correspond to pre and post-conditions of an operation in UML-CD.

5 EXAMPLE: THE RICE COOKER

To illustrate the application of the proposed FSM formula, we use the real time software application "Rice Cooker" case study. The FURs of this case study are described in (COSMIC Group, 2008). The question is how to determine the functional size of the three functional processes (FP1: *Set Target Temperature*, FP2: *Adjust Temperature* and FP3: *Lamp Control*) as described in (COSMIC Group, 2008). These processes are triggered by three events which are respectively:

- Signal 30s: Every 30s software controller selects a new target temperature.
- Signal 5s: Every 5s software controller must compare between the target temperature and actual temperature to control the heater.
- Tick (elapsed): Every 1s the timer must issue the elapsed time since button START is turned on.

Figure 2 shows the activity diagram of the "Rice Cooker" application at a high level of abstraction.







Figure 3: UML-AD of the "Set Target Temperature".

Figure 3 illustrate the UML-AD of the functional process "Set Target Temperature".

Table 3 presents in detail the measurement results of the UML-AD for the functional process (FP1). Due to space limitation, we will present only the measurement results for the two other processes (FP2, FP3). In addition, based on the component

diagram of the "Rice Cooker" in (Lavazza and Bianco, 2009), which includes three components and five interfaces; we will present the FSM results of the related UML-CD in Table 4.

According to equation (11), it can be ensured that the UML-AD design is conformed to the UML-CD design. In addition, assuming that the

Functional Process	Application of measurement formulas (UML-AD)	Measurement results in CFP	
	$FSM (FP1) = FSMcond(Signal 30s) + \sum_{j=1}^{6} FSM(act_{1j})$		6
	FSMcond(Signal 30s)	(4)	1
	$FSM act1j = FSM cond (Precond act_{1j}) + FSM param (Param act_{1j})$	(3)	0+3
	$FSMcond (Precond act_{1j}) = \begin{cases} 1 \ CFP & \text{if } act_{1j} \text{ has a pre-condition} \\ 0 & \text{otherwise} \end{cases}$	(4)	0
	FSMparam (Param act_{1j}) = $\begin{cases} 1 CFP \text{ if } act_{1j} \text{ has input/output parameters} \\ 0 \text{ otherwise} \end{cases}$	(5)	3
	FSMactTyp (actTyp) = $\begin{cases} 1 \text{ CFP} & \text{if actTyp is a particular case} \\ 0 & \text{otherwise} \end{cases}$	(7)	ATIO ² NS
	$\sum_{j=1}^{6} \text{FSM}(\text{act}_{1j}) = \text{FSM}(\text{Receive signal 30s}) + \text{FSM}(\text{Get cooking mode})$ FSM(Get elapsed time) + FSM(Provide elapsed time) + FSM(Get cooking ten FSM(Set target temperature))	0+1+0+ 0+1+1	
FP2	$FSM (FP2) = FSMcond(Signal 5s) + \sum_{j=1}^{7} FSM(act_{2j})$	(2)	6
FP3	$FSM (FP3) = FSMcond(Signal 1s) + \sum_{j=1}^{3} FSM(act_{3j})$	(2)	2
Total	$FSM(A) = \sum_{i=1}^{3} FSM(a_i)$	(1)	14

Table 3: Measurement results (Activity diagram of the "Rice Cooker").

Table 4 : Measurements	results (UML-CD	of the "Rice Cooker").
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Application of measurement formulas (UML-CD)	CFP
$FSM (C) = \sum_{i=1}^{3} FSM (S_i) + \sum_{j=1}^{5} FSM (I_j) $ (8)) 12
$FSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $ $PSM (S_1: CookingModeC) = \sum_{j=1}^{2} FSM_{op} (Op_{1j}) = $) 1+1
FSM (GetMode(): Cooking_mode) + FSM (SetMode(mode:Cooking_mode))	
FSM (S ₂ : CookingSpecsC) = $\sum_{j=1}^{1}$ FSM _{op} (Op _{2j}) = FSM (GetCookingTemp (time: (9)) 1
Integer, mode: Looking_mode): Integer)	
$FSM (S_3: CookingStateC) = \sum_{j=1}^{2} FSM_{op} (Op_{3j}) = FSM (SetTargetTemp(temp)) + (9)$) 1+1
$FSM (I_1: TimedEvents) = \sum_{j=1}^{3} FSM_{op} (Op_{1i}) = FSM (Signal 30s ()) + (10)$)
FSM (Signal 5s())+ FSM (Tick(elapsed))	1 1 1
$FSM (I_2: TempSensorCommands) = \sum_{j=1}^{1} FSM_{op} (Op_{2i}) $ (10)) 1
= FSM (ReadTemp (): Integer)	1
$FSM (I_3: HeaterOnInterface) = \sum_{j=1}^{1} FSM_{op} (Op_{3i}) = FSM (HeaterOn()) $ (10)) 1
$FSM (I_4: HeaterOffInterface) = \sum_{j=1}^{1} FSM_{op} (Op_{4i}) = FSM (HeaterOff()) $ (10)) 1
$FSM (I_5: LampCommands) = \sum_{j=1}^{1} FSM_{op} (Op_{5i}) = FSM (On()) $ (10)) 1

consistency heuristics are satisfied, the FSM difference between the UML-CD (12 CFP) and the UML-AD (14 CFP) can be justified by the difference in the levels of abstraction. Since UML-AD represents software at a more detailed level and UML-CD represents software at a high-level of abstraction, UML-CD does not represent all software details as well as UML-AD. Looking closely, in the UML-AD FP2, the extra CFP is due to the guard conditions which are not represented in the UML-CD.Table 3: Measurement results (Activity diagram of the "Rice Cooker")

Compared to existing works, our measurement results are consistent with those of (Lavazza and Bianco, 2009) and they ensure the correctness of our measurement procedures. Albeit, it can appear that there are some distinctions in the FSM results. For instance, we measured 14 CFP for UML-AD and 12 CFP for UML-CD of the "Rice Cooker" case study, while the FSM of the same case study calculated by (Lavazza and Bianco, 2009) is equal to 11 CFP. Their value is provided according to the identification of data movement involved in functional processes. It is independent of the UML diagrams. It can be observed that, for UML-AD, there is an extra of 3 CFP for three "Exits". Because of FP1 contains the transition "Get elapsed time", it should be considered as a data movement type "Exit". However, (Lavazza and Bianco, 2009) ignored this data movement. In FP2, the extra 2 CFP are due to: (i) the guard conditions which were not treated by (Lavazza and Bianco, 2009) for both actions "Start heater" and "Stop heater". They considered the command "HeaterOn and HeaterOff" as 1 data movement "Exit"; and (ii) the action "Get Actual Temperature" was not identified by (Lavazza and Bianco, 2009) since they considered the "Actual Temperature" to be returned by "Temperature Sensor" following the demand of "Software Controller".

Furthermore, for the UML-CD, the extra 1 CFP is due to the operation "SetMode(mod:Cooking_mode)". Indeed, this operation corresponds to another functional process (stop cooking). If we take into account the 'scope' according to COSMIC method, this operation will not be considered. In addition, our measuring scope is limited by the three FP (Set Target Temperature, Adjust Temperature and Lamp Control).

6 CONCLUSIONS

Applying COSMIC FSM method in the design phase

for checking consistency between activity diagram (UML-AD) and components diagram (UML-CD) is the main purpose of this paper. To meet this purpose, functional size measurement procedures for UML-AD and UML-CD were presented. These procedures were defined based on the mapping between COSMIC concepts and those of UML diagrams concepts. We have proposed а measurement interval that it can be used as a guideline by designers and developers to verify consistency between UML-AD and UML-CD and to identify modeling errors. We have also proposed a set of modeling rules to ensure the consistency between those diagrams. Finally, we have illustrated the proposed measurement procedures by using the "Rice Cooker" case study, and confronted our measurement results with those of (Lavazza and Bianco, 2009).

Further works including the use of measurement results of UML-AD and UML-CD should be investigated. These measures can also be helpful to software managers and leaders to complete their project within the scheduled dates. The proposed formulas need to be applied on larger case studies to ensure the quality of measurement results. Finally, implementation is also required not only to find faster the FSM of each UML diagram, but also alert users (developers, designers, etc.) with the presence of any modeling errors in the design phase.

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