Towards a Standard Approach for Optimization in Science and Engineering

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Abstract: Optimization plays a fundamental role in engineering design and in many other fields in applied science. An optimization process allows obtaining the best designs which maximize and/or minimize a number of objectives, satisfying at the same time certain constraints. Nowadays, design activities require a large use of computational models to simulate experiments, which are usually automated through the execution of the so-called scientific workflows. Even if there is a general agreement in both academy and industry on the use of scientific workflows for the representation of optimization processes, no single standard has arisen as a valid model to fully characterize it. A standard will facilitate collaboration between scientific and engineering publications. This paper proposes the use of BPMN 2.0, a well-defined standard from the area of business processes, as a formal representation for both the abstract and execution models for scientific workflows in the context of process optimization. Aspects like semantic expressiveness, representation efficiency and extensibility, as required by optimization in industrial applications, have been carefully considered in this research. Practical results of the implementation of an industrial-quality optimization workflow engine defined in terms of the BPMN 2.0 standard are also presented in the paper.

1 INTRODUCTION

Optimization is the process of finding the best solution for a problem given a set of restrictions or constraints. Typical problems faced nowadays in engineering and applied sciences, both in research and industry, are defined with multiple and possibly conflicting objectives. This class of problems, known as **Multi-Objective Optimization** (MOO) problems, usually do not have a single solution, but a set of trade-off solutions where no objective can be enhanced without a deterioration of at least one of the others. This set of compromise solutions, known as **Pareto front**, represents the output of an MOO process (Branke et al., 2008).

Formally, an MOO problem is defined as follows:

$$\begin{aligned} Minimize_x \ F(x) &= [F_1(x), F_2(x), \dots, F_k(x)]^T \\ subjet \ to \ g_j(x) &\leq 0, j = 1, 2, \dots, m \\ h_l(x) &= 0, l = 1, 2, \dots, e \end{aligned}$$

where k is the number of objective functions, m is the number of inequality constraints and e is the number of equality constraints. The vector $x \in E^n$ is the vector of design variables while F corresponds to the objective vector function.

In most engineering and applied sciences problems, the objective vector function *F* represents a physical problem, which is usually evaluated by a so-called solver defined in terms of simulated processes running on computer systems. This computational process can be rather complex, involving a large number of simulation steps, which need to exchange data between themselves and can require execution on distributed systems like a Grid or Cloud Computing system. The simulated process is usually represented with a formalism known as a scientific workflow (Lin et al., 2009), which provides both a representation for the abstract view (used by the engineer to represent the process) and the associated execution model (used for the real simulation). The abstract view is usually a humanunderstandable graphic representation, while the execution model is usually represented with XML. This last model is used by a workflow engine in order to execute the workflow and perform the simulation.

However, even if scientific workflows have been

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used successfully since many years, most of the tools used for their definition and execution are not based on standard technologies. A large number of different graphic and execution formats are currently in use, and there is no clear signs of convergence till now. However, things are different in the area of business processes, where many standards have been defined for both the graphical and the execution representation of business process workflows. It is definitely true that most of the business process standards cannot be used to represent scientific workflows since they lack enough expressive power to support specific scientific workflow requirements. However, the recent BPMN 2.0 (OMG, 2011) standard allows the support of required characteristic for scientific workflows at both levels, particularly due to its powerful extension scheme, which can be used to define the missing features. From now on, all references with the acronym BPMN are intended as references to version 2.0 of the standard.

While it is mostly accepted that BPMN can be used to represent scientific workflows, this paper will go one step forward. It will show that BPMN can be used to represent a complete **optimization workflow**, which includes not only the scientific workflow used to represent the physical problem, but also the optimization cycle supporting the multiple patterns required by current optimization problems. In this way, BPMN is opening the path for the use of a single standard in optimization workflows for engineering and applied science applications, both in research and industrial fields.

The paper is structured as follows: Section 2 presents a short review of the state of the art, Section 3 describes optimization problems and the most common optimization patterns in use today, Section 4 presents our proposal for the use of a standard notations for optimization workflows and Section 5 presents results on a standard implementation by considering specific requirements like execution efficiency. The paper ends with conclusion and references.

2 STATE OF THE ART

The use of **scientific workflows** for process automation has been widely analyzed in the literature (Lin et al., 2009). Many commercial and open source implementations do exist. The most widely used are Kepler (Ludascher et al., 2009), Triana (Taylor et al., 2007), Taverna (Missier et al., 2010), Pegasus (Sonntag et al., 2010) and KNime (Berthold et al, 2008), with many new frameworks appearing continually. However, all these scientific workflow frameworks are based in proprietary nonstandard formats. Attempts have been made to represent scientific workflows by using standards; for example, BPEL was proposed as the execution representation for workflows using other models for graphical representation, like BPMN or Pegasus (Sonntag et al., 2010). However, the need to use two different models, one for the abstract or graphical representation, and the other for the execution representation, prevented its widespread use in industry.

Standards coming from the business process area, like BPEL and the first version of BPMN had some strong limitations to support all required features. The latest release of the BPMN standard, however, has open the possibility to use a single standard in the context of scientific workflows due to its powerful extension mechanism (Abdelahad et al., 2012), even if in some cases the development efforts can be important (Sonntag et al., 2010).

Concerning **optimization workflows**, there are specific workflow systems defined for optimization and also extensions of the previously mentioned frameworks which can include optimization components in them. As an example from the open source community, Kepler through its module Nimrod/OK, provides the possibility of defining optimization cycles (Abramson, 2010). In the area of commercial tools, there exists many options like for example modeFRONTIER (ESTECO, 2012), widely used in CAD/CAE engineering optimization. However, again, all of them are based in proprietary formats.

To the best of our knowledge, no current tool, open source or commercial, can define optimization workflows by using a standard workflow notation.

3 OPTIMIZATION PROBLEMS

An optimization session is defined through what is usually know as an **optimization plan** (OP), which consists at least in the specification of the design of experiments strategy and the selection of the optimization algorithm. Other elements, like robust sampling or response surface models are usually required in industrial applications (Branke et al., 2008). The following subsections provide a short description of these elements, together with an specification of the most common optimization patterns in use today.



Figure 1: The most common optimization patterns: (a) simple, (b) sequential, (c) nested, (d) robust and (e) mixed robust.

3.1 Design of Experiments

A **Design of Experiments** (DoE) session usually precedes the optimization stage. The aim of a DoE is to test specific configurations regardless of the objectives of the optimization run, but rather considering their pattern in the input parameters space. It provides an *a-priori* exploration and analysis which is of primary importance when a statistical analysis has to be performed later on. Moreover, most optimization algorithms require a starting population of designs to be considered initially, eventually generating random input values if no other preference has emerged yet.

3.2 Optimization Algorithms

The **Optimization Algorithm** (OA) implements the mathematical strategies, or heuristics, which are designed to obtain a good approximation of the actual Pareto front. It is important to stress that real-world optimization problems are solved through rigorously proven converging methodologies only in a very few cases, since the high number of input parameters and the low smoothness of objective functions involved limit the possible usage of classical mathematical algorithms.

In many cases, the most widely used optimization techniques tend to "over-optimize", producing solutions that perform well at the design point but may have poor off-design characteristics. It is important, therefore, that the designer ensures robustness of the solution, defined as the system insensitivity to any variation of the design parameters. This effect is achieved through the use of **Robust Sampling** (RS), which searches for the optima of the mean and standard deviation of a stochastic response rather than the optima of the deterministic response (Bertsimas et al, 2010).

3.3 Response Surface Models

In real applications, the required simulation process is usually computationally expensive since every single execution can require hours if not days. Therefore, multi objective optimization algorithms are required to face the demanding issue of finding a satisfactory set of optimal solutions within a reduced number of evaluations. **Response Surface Models** (RSM), can help in tackling this situation by speeding up the optimization process (Voutchkov and Keane, 2010). Previously evaluated designs can be used as a training set for building surrogate models, allowing a subsequent inexpensive virtual optimization to be performed over these metamodels of the original problem.

3.4 Optimization Patterns

The specification of an optimization problem in terms of the interaction between the solver and the optimization algorithm can follow different patterns. The **Optimization Patterns** (OP) most widely used nowadays in industrial and research applications are presented in Figure 1 and described below:

- 1. **Simple Optimization:** The simplest pattern which consists on a single optimization loop (see Figure 1.a). The optimization algorithm (OA) sends design patterns to the solver (S) for evaluation, which in turn returns the computed values for the objectives.
- 2. Sequential optimization: A sequence of two simple Optimizations (see Figure 1.b). Usually, the second optimization starts by considering the best designs obtained by the first optimization. In many cases, both solvers are the same, i.e. S'=S, corresponding to a situation where two different optimization strategies are applied to the same physical problem. A typical use case is when the first algorithm performs a rough and fast optimization step, reducing the search space for a second more precise but slower optimization.

- 3. Nested Optimization: The optimization cycle includes two optimization algorithms (see Figure 1.c). A typical use case consists in a main optimization algorithm (OA) generating designs, which are evaluated by using a solver and a secondary optimization algorithm (NOA). This last optimization cycle performs a kind of local optimization in a fixed context defined by the design provided by the first algorithm. The design evaluation results are sent back to the main algorithm only after this secondary optimization has finished.
- 4. **Robust Optimization:** In this pattern, the designs generated from the external optimization loop are not sent directly to the solver (see Figure 1.d). Instead, an internal loop performs robust sampling (RS) by sending for evaluation a fixed number of designs for each original design submitted from the external loop, randomly perturbed by following a probability distribution.
- 5. Mixed Robust Optimization: The designs generated by the optimizer and perturbed by a robust sampling algorithm, are evaluated with the real solver or with a synthetic response surface model (RSM) depending on a probabilistic distribution. The objective is to use an approximation of the real solver which can help to reduce the computation time, without losing precision (see Figure 1.e).

Note that there are no restrictions on the number of designs to be evaluated concurrently if the optimization algorithm allows it.

4 STANDARD OPTIMIZATION WORKFLOWS

This section will show that BPMN can be used to represent optimization workflows, supporting the multiple patterns required nowadays by current applications in engineering and applied sciences.

4.1 Requirements

Required features that are not directly supported by BPMN can be defined through the standard extension mechanism. Therefore, this section will consider only the aspects that are required to fully support optimization workflows. These specific features are the following:

1. **Optimization Data handling:** The workflow notation needs to support data objects that can adequately represent the DoE, optimization plan,

design database, and subsets of it (like the Pareto front for example). Also, suitable support for data transformations must be provided (for example, in order to filter a set of designs or select the Pareto front).

- 2. Asynchronous Communication: Optimization algorithms and related components like robust optimization activities, require the evaluation of designs in asynchronous terms, in such a way that evaluation of a number of designs can be requested without blocking the execution of the algorithms.
- 3. **Concurrent Execution:** mechanisms must be provided to support parallel execution of the solver and other components, like response surface models and robust optimization.
- 4. **Instance Routing:** Since there will be many instances of the same process running concurrently, the messaging system has to deliver the messages to the particular instance to which is addressed. This can be handled through an adequate correlation model which can ensure that data will flow between the components as required.

Complete support for all these required features, however, is not enough, since a standard workflow model used for optimization needs to address also **execution efficiency** both in terms of memory and processing time. Next sections will show that BPMN supports not only the required features, but also allows specifying elements to guarantee efficiency through its extension mechanism.

4.2 BPMN Support

The BPMN standard provides elements which can support the requirements identified in previous section. In particular:

- 1. **Data Objects:** The construction used to represent data within the process, which can also represent a collection of objects, as required for a DoE or design databases. Transformation expressions are allowed in data associations, which are used to transfer data between data objects and inputs/outputs of activities and processes.
- 2. **Messages:** BPMN coordinates process interaction by using the so-called conversations and choreography processes. Coordination is reached through asynchronous message exchange between activities defined in different pools.
- 3. Message-triggered Start event: A process with a message start event will start its execution as

soon as a message of the appropriate type will be received. In this way, the optimization algorithm task can start many instances of the solver by sending the appropriate number of messages to the solver process.

4. Correlation keys: BPMN supports instance routing by associating a particular message to an ongoing conversation between two particular process instances by using a correlation mechanism defined in terms of correlation keys.

4.3 **Optimization Patterns Support**

With the appropriate elements identified in the previous section, BPMN can support the most widely used optimization patterns, as it will be shown below.



Figure 2: Simple optimization pattern in BPMN.

A BPMN diagram with two pools representing two participants, the optimization algorithm and the solver respectively, can be used to model the **simple** optimization pattern, as shown in Figure 2. The optimization algorithm is defined with a process with three nodes: a start event, a task that implements the optimization algorithm itself, and an end event that are executed in sequence. The optimization task (labeled as OA) gets the initial set of designs to evaluate from a data object (DoE) and produce the final Pareto front in a second data object (Pareto). The solver is implemented also by a three nodes process: a message triggered start event, a task that implements the solver itself and an end event that generates a message. When the OA task generates a message with the design to be evaluated as payload, an instance of the second process is started. The solver (S) evaluates the design and generates a message with the corresponding metrics as payload, which is sent to the optimization task (OA) through the conversation defined between the two participants. Multiple instances of the solver can

be run in parallel, each one of them started when triggered by the message from the optimization task.

A **sequential optimization** pattern can be represented by adding a second optimization algorithm task in the first process, as shown in Figure 3. The first optimization task (labeled as



Figure 3: Sequential optimization pattern in BPMN.

 OA_1) gets the initial set of designs to evaluate from a data object (DoE), performs the evaluation using the first solver (S), producing as output a set of designs which are assigned to a data object (Best designs). The second optimization algorithm (OA₂) uses this data object as the initial population for the second optimization loop, which in turn produces the final Pareto front in a third data object (Pareto) by repeatedly evaluating designs by using the second solver (S'). Note that multiple instances of the solver can be run in parallel for each optimization cycle.

Figure 4 presents the **nested optimization** pattern represented in BPMN. The two optimization



Figure 4: Nested optimization pattern in BPMN.

loops are implemented in different processes. The first process (OA) implements the outer optimization loop in the same terms as the loop in the simple optimization pattern, sending designs for evaluation to the inner optimization loop (NOA). An instance of this process is started for every message



Figure 5: Robust optimization pattern in BPMN.

received, meaning that multiple inner optimizations can be evaluated concurrently. The internal optimization executes a solver (S), and based on their output and the design sent from the external optimizer, performs a local optimization by using the nested algorithm (NOA). The nested algorithm evaluates designs by using the second solver defined in the third process (S'). Note that evaluations of the this process can also be run concurrently.

Figure 5 shows **the robust optimization** pattern in BPMN, which represents a very usual pattern in industrial design. There is an optimization algorithm task (OA) which sends through messages the designs for evaluation to the second process. One instance of this process is started for each design that is received.

The robust sampling task (RS) generates a number of messages for each design received from the top level, which are in turn sent as messages to the third process for evaluation by using the solver (S). Note that if the first process generates n messages for concurrent evaluation, n process for robust sampling will be started concurrently, and if the RS processes send each one m messages for concurrent evaluation, a total of $n \times m$ solver instances could eventually be run concurrently.

The **mixed robust optimization** pattern in BPMN is shown in Figure 6. In this patter there is an external optimization loop which send designs for evaluation to the robust sampling process as in the previous pattern (see Figure 5). This process performs evaluations by using the real solver (S) or a synthetic model of it (RSM) depending on a probabilistic distribution, a decision that is represented with the decision exclusive gateway node in the second process.

4.4 Efficiency Considerations

The previous section has shown that BPMN can be used to represent the most widely used patterns in optimization. However, in order to use it effectively in a real environment, execution efficiency has also to be considered. Many aspects in the BPMN specification can introduce execution difficulties for optimization workflows. Nevertheless, the BPMN extension mechanisms allows defining new elements to effectively handle them. Since it is not possible to describe all situations that have been considered, this section presents a **representative example** that shows how a typical problem with efficiency can be handled with appropriate extensions. The next section will present experimental results by using the extension proposed.

As shown before, optimization patterns are



Figure 6: Mixed robust optimization pattern in BPMN.

heavily based on asynchronous communication. This puts a strong pressure on the messaging system,

since optimization processes typically run for a long time, with days or weeks being a common duration, involving also a large number of task evaluations. Hundreds of thousands of messages could be exchanged in a single run. In a typical robust optimization problem (as show in Figure 1.d), if the optimization algorithm (OA) sends n designs for evaluations, n concurrent instances of the robust sampling (RS) process will be started (RS_i , $1 \le i \le$ n). If each one of these instances send m randomly perturbed designs for evaluation, then $n \times m$ concurrent solver (S) instances will be started $S_{ii}, 1 \le i \le n, 1 \le j \le m$). Messages sent back from the S_{ij} instance need to be addressed to the correct RS_i instance, and messages sent back from the RS instances has be addressed to the correct OA instance

BPMN uses a correlation mechanism to associate messages to particular instances involved in a conversation (OMG, 2011). Exchanged messages are correlated through the so-called correlation keys, which are defined as a set of name-value pairs. In simplified terms, when the first message in a conversation is received, the receiver process stores the correlation values for the key, which must match in future interchange of messages. In this way, messages can be routed to the appropriate instance responsible for receiving the message. For the robust optimization pattern (see Figure 5), two correlation keys are required, one to correlate messages between OA and RO, and other to correlate messages between RO and S. The first key can be the design ID, while the second can be a combination of the design ID and the sequence number of the perturbed design.

Note that a process needs to keep information about all keys that are used in order to eventually match future messages. This implies an extra memory requirement to store the keys and additionally, extra processing time to perform the matching process every time a new message is received. These problems can be easily solved by adding an extension element to indicate the time to live (TTL) for messages, representing the number of steps expected in a conversation that uses a particular correlation key. As can be noted from the selected pattern, single request-response means that the key can be discarded as soon as an answer message is received, removing the need to store the keys for checking future matching since there will never be other answer. The following XML code shows an example of the use of the extension TTL added to the conversation element of BPMN:

<conversation id="_11">

Of course, the TTL extension can be used at workflow designer discretion, meaning that he or she should include it only when it is clear from the communication pattern.

5 IMPLEMENTATION

In order to demonstrate practically the effect of efficiency enhancement by using the extension mechanism, this section presents the experimental results of the TTL extension presented in previous section. The pattern considered is the robust optimization flow, which has been presented in Figure 5. In order to make more evident the effect of the TTL enhancement, an unlimited value of m as perturbation for robust optimization was selected. Figure 7 presents the results of the execution in



Figure 7: Memory usage for a robust optimization execution with TTL (continuous line) and without TTL (dotted line).

terms of memory consumption. Memory usage without TTL is plotted with a dotted line, while memory usage with the TTL extension is plotted with a continuous line. As it can be appreciated, memory requested from the heap grows continuously due to the need to store the correlation keys when TTL is not used. The problem arises because the RS process cannot discard a key, even if its associated message has been received, since the standard specifies that other messages with the same key can eventually arrive. The optimizer workflow designer knows by sure that this will never happen, but there is no way in which he or she can specify it. The continuous line plot in Figure 7 shows that with

the TTL extension, the use of memory is stable, updated only at regular intervals by the execution of the garbage collector. This happens because correlation keys are disposed as soon as a message that matches the corresponding key is received, releasing the memory that was occupied by the key.

A similar effect can be appreciated with the processing time. Figure 8 presents the results of the delay in the execution of the solver process over time. Delay without TTL is plotted with a dotted line, while delay with the TTL extension is plotted



Figure 8: Delay to start the solver with the TTL extension (continuous line) and without it (dotted line).

with a continuous line. With the no-TLL approach, every time a message arrives, the matching process has to consider all correlation keys, including the values that have successfully matched a message before. The TTL approach instead presents no delay, since correlation keys are removed as soon as the message has been processed, with no need to include them in the matching process.

6 CONCLUSIONS

Optimization workflows have been used successfully over many years; however, the currently available tools used for their definition and execution are not based on standard technologies. A large number of different graphic and execution formats are currently in use, and there is no clear signs of convergence until to date. This paper has proposed the use of BPMN 2.0, a well-defined standard from the area of business processes, as a formal representation for both the abstract and the execution model for optimization workflows. In particular, it was shown that BPMN 2.0 can support the most widely used optimization patterns required today in industry. An implementation example that

illustrates the use of BPMN 2.0 extensions to solve a representative execution efficiency problem has also been presented.

It is expected that the use of a standard for optimization workflows will facilitate the collaboration between scientists and industrial designers, enhance the interaction between different engineering and scientific fields, providing also a common vocabulary in scientific and engineering publications.

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