

Towards Logic Circuits based on Physarum Polycephalum Machines

The Ladder Diagram Approach

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Abstract: In the paper, we present foundations of logic circuits based on Physarum polycephalum machines. We propose to apply the ladder diagram approach for constructing topological structures of such circuits. Relationships between basic ladder diagram elements and topological constructions present in Physarum polycephalum machines are emphasized. At the beginning, basic logic gates (AND, OR, NOT) are considered. Such a set of gates constitutes a functionally complete system. This fact is important for building computationally universal devices.

1 INTRODUCTION

Physarum polycephalum is a one-cell organism belonging to the species of order *Physarales*, subclass *Myxogastromycetidae*, class *Myxomycetes*, and division *Myxostelida*. In the phase of plasmodium, it looks like an amorphous giant amoeba with networks of protoplasmic tubes. It feeds on bacteria, spores and other microbial creatures (substances with a potentially high nutritional value) by propagating towards sources of food particles and occupying these sources. A network of protoplasmic tubes connects the masses of protoplasm. As a result, the plasmodium develops a planar graph, where the food sources or pheromones are considered as nodes and protoplasmic tubes as edges. The plasmodium may be used for developing a biological architecture of different abstract devices, among others, digital. Plasmodium's ability to perform useful computational tasks, in its propagating and foraging behavior, was firstly emphasized by T. Nakagaki et al. (cf. (Nakagaki et al., 2000)). In *Physarum Chip Project: Growing Computers From Slime Mould* (Adamatzky et al., 2012) supported by FP7, we are going to implement programmable amorphous biological computers in plasmodium of Physarum. This abstract computer we are going to obtain is called *slime mould based computer*. One of the tracks in the project is to develop a new object-oriented programming language for Physarum

polycephalum computing (Schumann and Pancierz, 2013).

The problem of constructing logic gates in chemical media or on biological substrates has been considered earlier in the literature. Different approaches have been proposed. One of them is to constrain the substrate into channels and allow disturbances to propagate along the channels and interact with other disturbances at the junctions between the channels. For example, this approach has been implemented in a geometrically constrained Belousov-Zhabotinsky medium, cf. (Górecki et al., 2009), (Motoike and Yoshikawa, 2003), (Sielewiesiuk and Górecki, 2001), (Steinbock et al., 1996). Also, non-excitable chemical implementation of logic gates has been proposed (Adamatzky and De Lacy Costello, 2002). A wider discussion of Physarum polycephalum gates is included in (Adamatzky, 2010).

Our approach, presented in this paper, is a little different. We propose to construct logic gates through the proper geometrical distribution of stimuli for Physarum polycephalum. This distribution is determined according to ladder diagrams (Rosandich, 1999) representing basic logic gates (AND, OR, NOT). Rungs of the ladder can consist of serial or parallel connected paths of Physarum propagation. A kind of connection depends on the arrangement of regions of influences of individual stimuli. If both stimuli influence Physarum, we obtain alternative paths

for its propagation. It corresponds to a parallel connection (i.e., the OR gate). If the stimuli influence Physarum sequentially, at the beginning only the first one, then the second one, we obtain a serial connection (i.e., the AND gate). The NOT gate is imitated by the repellent avoiding Physarum propagation.

The rest of the paper is organized as follows. In Section 2, we recall basics of Physarum polycephalum machines with a special focus on stimuli. Section 3 mentions a basic idea of ladder diagrams. This idea is used in Section 4 for constructing logic gates based on Physarum propagation. Section 6 summarizes the presented approach and suggests directions for further work.

2 BASICS OF PHYSARUM POLYCEPHALUM MACHINES

In Physarum polycephalum machines, we can distinguish the following stimuli constituting their data nodes:

- Attractants that are sources of nutrients or pheromones, on which the plasmodium feeds. Each attractant A is characterized by its position and intensity.
- Repellents. Plasmodium of Physarum avoids light and some thermo- and salt-based conditions. Thus, domains of high illumination (or high grade of salt) are repellents such that each repellent R is characterized by its position and intensity, or force of repelling.

Plasmodium of Physarum polycephalum functions as a parallel amorphous computer with parallel inputs and parallel outputs. Data are represented by spatial (topological) configurations of attractants and repellents. Plasmodium of Physarum polycephalum is a computing substrate. In (Adamatzky, 2010), Adamatzky underlined that Physarum does not compute. It obeys physical, chemical and biological laws. Its behavior can be translated to the language of computations. At the beginning of computation, data nodes are distributed in a computational space, and plasmodium is placed at given points in the space. Plasmodium proceeds computation even if the solution has been reached and halts only when physical resources are exhausted. Typically, plasmodium spans attractants (sources of nutrients or pheromones) with protoplasmic tubes (veins). Plasmodium builds a planar graph, where nodes are attractants and edges are protoplasmic tubes.

It is a subject of discussion how plasmodium feels attractants. Experiments show that plasmodium can

locate and colonize the nearby sources of nutrients or pheromones (attractants). In our approach, we assume that each attractant (repellent) is characterized by its region of influence (ROI) in the form of a circle surrounding the location point of the attractant (repellent), i.e., its center point. The intensity determining the force of attracting (repelling) decreases as the distance from it increases. A radius of the circle can be set assuming some threshold value of the force.

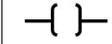
3 BASICS OF LADDER DIAGRAMS

Ladder logic is the most popular programming language used to program Programmable Logic Controllers (PLCs), cf. (Rosandich, 1999). This language was developed from the electromechanical relay system-wiring diagrams. Programs in the ladder logic language are written graphically in the form of the so-called ladder diagrams. Basically, this notation assumes that contacts are controlled by discrete (binary) inputs and coils control discrete (binary) outputs. We can distinguish three main types of elements of ladder diagrams:

- *Normally open contact* (NOC). It passes power (i.e., it is *on*) if the binary input assigned to it has value 1. Otherwise, it does not pass power (i.e., it is *off*).
- *Normally closed contact* (NCC). It passes power (*on*) if the binary input assigned to it has value 0. Otherwise, it does not pass power (*off*).
- *Coil* (C). If it is passing power (i.e., it is *on*), a value of the binary output assigned to it is set to 1. Otherwise (i.e., it is *off*), a value of the binary output assigned to it is set to 0.

The symbols of ladder diagram elements mentioned earlier are collected in Table 1.

Table 1: Symbols of main types of elements in ladder diagrams.

Symbol	Meaning
	Normally open contact
	Normally closed contact
	Coil

Using three main types of elements of ladder diagrams we can build basic logic gates shown in Figures 1 (AND), 2 (OR), and 3 (NOT).

The gates mentioned work as follows:

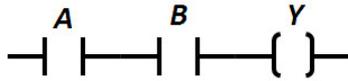


Figure 1: The ladder diagram AND gate.

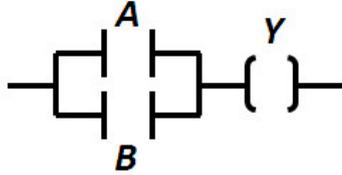


Figure 2: The ladder diagram OR gate.



Figure 3: The ladder diagram NOT gate.

- AND: The coil is *on* ($Y = 1$) if and only if both contacts are *on*. It is satisfied if $A = 1$ and $B = 1$. Otherwise, the coil is *off*.
- OR: The coil is *on* ($Y = 1$) if at least one contact is *on*. It is satisfied if $A = 1$ or $B = 1$. Otherwise, the coil is *off*.
- NOT: The coil is *on* ($Y = 1$) if a contact is *on*. $A = 0$ causes the contact to be switched on. The coil is *off* ($Y = 0$) if a contact is *off*. $A = 1$ causes the contact to be switched off.

Using structures of basic logic gates we can build, in ladder diagrams, more complex digital systems. Now, it is out of scope of this paper. We will consider this problem in the future.

4 LOGIC CIRCUITS BASED ON PHYSARUM POLYCEPHALUM PROPAGATION

Ladder diagrams implement an idea of flowing power from left to right. The output for the rung in the ladder diagram occurs on the extreme right side of the rung and power is assumed to flow from left to right if and only if there exists at least one closed path from left to right making the flow possible. We apply this idea to build logic gates in Physarum polycephalum machines. Flowing power is replaced with propagation of plasmodium of Physarum polycephalum. Plasmodium propagation is stimulated by attractants and repellents (see Section 2). In our approach, stimuli (attractants and repellents) are treated as data nodes. We assume that plasmodium must occur in a proper

region to be influenced by a given stimulus. This region is determined by the radius depending on the intensity of the stimulus. Using the analogy to flowing power in rungs of ladder diagrams, we can build logic gates in Physarum polycephalum machines by the proper geometrical distribution of stimuli (attractants and repellents) on the substrate. Controlling the power flow in rungs by opening/closing contacts is replaced with controlling the plasmodium propagation by activating/deactivating stimuli. Relationships between elements of ladder diagrams and stimuli of Physarum polycephalum computing are collected in Table 2.

Table 2: Relationships between elements of ladder diagrams and stimuli of Physarum polycephalum computing.

Ladder diagram element	Physarum polycephalum computing stimulus
Normally open contact	Attractant controlled by input
Normally closed contact	Repellent controlled by input
Coil	Attractant controlling output

Table 3 shows interpretation of logic values (0 and 1) for inputs in terms of states of stimuli. Input values cause activation/deactivation of stimuli. Value 1 activates the stimuli whereas value 0 deactivates the stimuli. Analogously, Table 4 shows interpretation of logic values (0 and 1) for outputs in terms of states of stimuli. In our approach, the output represented by the coil in ladder diagrams is replaced with the attractant. We assume that the output attractant is always activated. If plasmodium is attracted by it and occupies it, then we interpret this state as 1. Otherwise, if there is no plasmodium occupying the attractant, i.e., plasmodium is not attracted, the state is interpreted as 0.

Table 3: Representation of input logic values.

Boolean value	Representation
0	Attractant/repellent deactivated
1	Attractant/repellent activated

Table 4: Representation of output logic values

Boolean value	Representation
0	Absence of Physarum at the attractant
1	Presence of Physarum at the attractant

Our idea of paths of plasmodium propagation is further presented graphically. In Table 5, we have collected symbols used by us in diagrams.

As it was mentioned earlier, the idea of ladder diagrams has been applied in our logic gates constructed in Physarum polycephalum machines. Figure 4 shows distribution of stimuli for the AND gate. This distribution simulates a serial connection of contacts. Plas-

Table 5: Symbols of elements used in figures.

Symbol	Meaning
●	Physarum
○	Attractant deactivated
⊙	Attractant activated
◻	Repellent deactivated
◻	Repellent activated
○	Region of influence
➔	Direction of plasmodium propagation

modium of Physarum polycephalum P can be propagated to the output attractant A_y if and only if both attractants A_{x1} and A_{x2} are activated. First, plasmodium is attracted to A_{x1} (because it is placed only in its region of influence). After the achievement of this goal, it is in the region of influence of A_{x2} and it is attracted by it. The achievement of A_{x2} causes that plasmodium is in the region of influence of A_y and it is attracted by it. Finally, plasmodium achieves A_y . It is interpreted as a logic output with value 1. Deactivation of either the attractant A_{x1} or A_{x2} causes that the path of propagation becomes broken, i.e., there is a place where plasmodium is not attracted by any attractant. Figure 7 shows paths of plasmodium propagation for all possible combinations of input values for A_{x1} and A_{x2} .

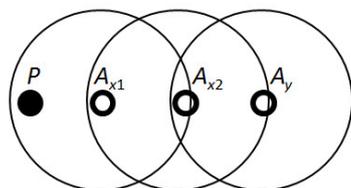


Figure 4: The Physarum AND gate.

Figure 5 shows distribution of stimuli for the OR gate. This distribution simulates a parallel connection of contacts. Plasmodium of Physarum polycephalum P can be propagated to the output attractant A_y if one of the attractants A_{x1} or A_{x2} is activated. First, plasmodium is attracted to A_{x1} or A_{x2} (because it is placed in regions of influences). After the achievement of one or both of them, it is in the region of influence of A_y and it is attracted by it. Finally, plasmodium achieves A_y . It is interpreted as a logic output with value 1. Deactivation of both attractants A_{x1} and A_{x2} causes that the path of propagation becomes broken, i.e., plasmodium is not attracted by any attractant and cannot start from the initial position. Figure 8 shows paths of plasmodium propagation for all pos-

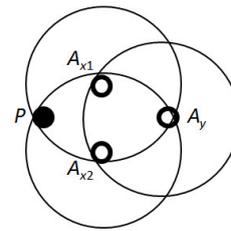


Figure 5: The Physarum OR gate.

sible combinations of input values for A_{x1} and A_{x2} .

The NOT gate behavior is simulated by the repellent as it is shown in Figure 6. If the repellent R_x is activated (i.e., the input value is 1), then it avoids plasmodium to be attracted by the output attractant A_y . Therefore, Physarum is not present at A_y , i.e., the output value is 0. Otherwise, plasmodium is not avoided and achieves A_y . Figure 9 shows paths of plasmodium propagation for all possible combinations of input values for R_x .

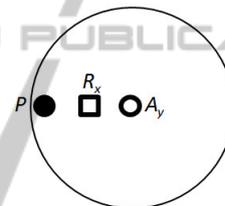


Figure 6: The Physarum NOT gate.

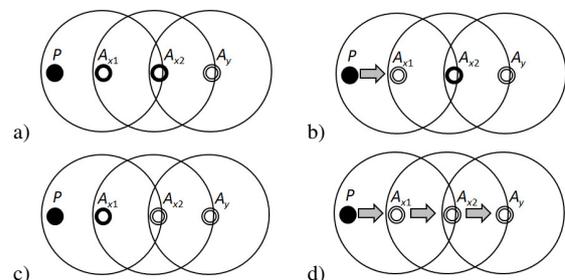


Figure 7: States of the AND gate for all input combinations.

5 EXPERIMENT

In the experiment, we have built a Physarum polycephalum demultiplexer based on the ladder diagram structure. A demultiplexer is a device taking a single input signal and selecting one of many data-output-lines, which is connected to the single input. In Figure 10, a schematic symbol of the 1-to-2 demultiplexer (a) and its implementation (b) using a particle model of Physarum polycephalum (Jones and Adamatzky, 2010) are shown. In the schematic symbol: d is a

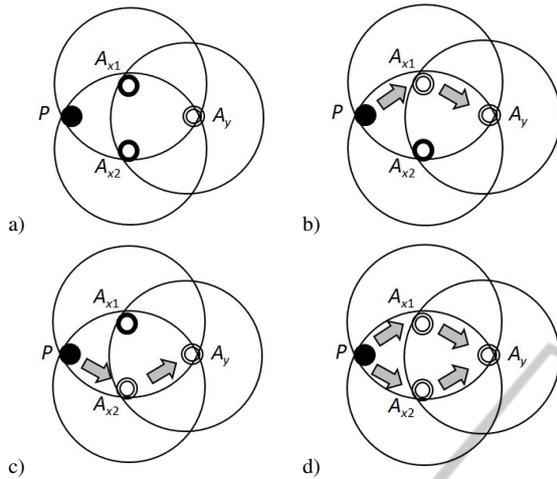


Figure 8: States of the OR gate for all input combinations.

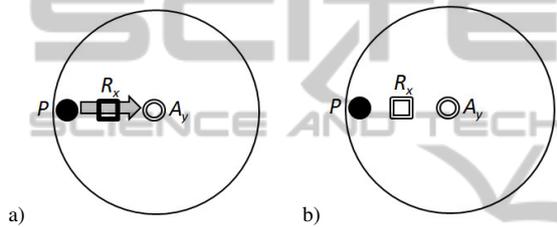


Figure 9: States of the NOT gate for all input combinations.

data input, s is a select input, and y_0, y_1 are outputs. The operation of the demultiplexer can be described as follows:

- if $s = 0$, then $y_0 = d$,
- if $s = 1$, then $y_1 = d$.

The functional specification can be written as $y_0 = \bar{s}d$ and $y_1 = sd$. In the Physarum polycephalum implementation of the demultiplexer, one can see: Physarum polycephalum (P), attractants (A_d, A_s, A_{y0}, A_{y1}), repellent (R_s). Let ROI denote the region of influence. For the topological distribution of Physarum polycephalum, attractants and repellents, we assume that:

- P belongs to $ROI(A_d)$,
- A_d belongs to $ROI(A_{y0}), ROI(R_s)$, and $ROI(A_s)$,
- A_s belongs to $ROI(A_{y1})$.

Logical states are implemented in the following way:

- $s = 0$ means R_s and A_s are deactivated, $s = 1$ means R_s and A_s are activated,
- $d = 0$ means A_d is deactivated, $d = 1$ means A_d is activated.

It is worth noting that A_{y0} and A_{y1} are always activated.

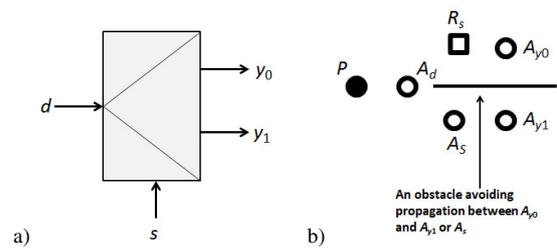


Figure 10: 1-to-2 demultiplexer: (a) a schematic symbol, (b) distribution of stimuli.

In Figure 11, the experimental environment for a particle model of Physarum polycephalum is shown.

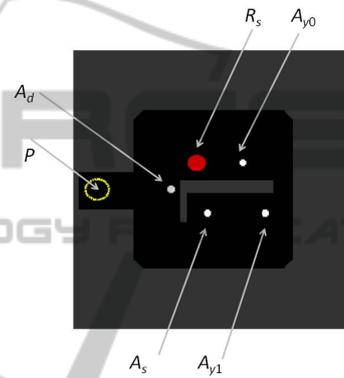


Figure 11: The experimental environment for a particle model of Physarum polycephalum.

In Figure 12, results of experiments are presented. Pictures taken by us show how Physarum polycephalum was propagated in each situation.

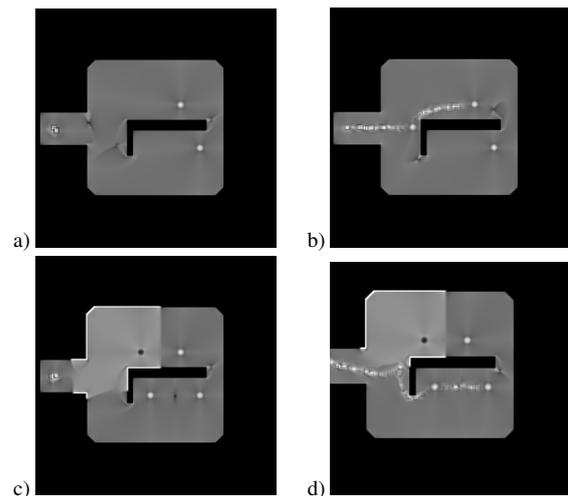


Figure 12: Results of experiments: (a) for $s = 0$ and $d = 0$, (b) for $s = 0$ and $d = 1$, (c) for $s = 1$ and $d = 0$, (d) for $s = 1$ and $d = 1$.

One can see the following cases:

- $s = 0$ and $d = 0$: uneventful, because there is no data regardless of switch position,
- $s = 0$ and $d = 1$: no repellent causes the stream to go to A_{y0} , the model does not grow down because it is outside the region of influence of A_{y1} ,
- $s = 1$ and $d = 0$: uneventful, because there is no data regardless of switch position,
- $s = 1$ and $d = 1$: the repellent causes selection of the lower path to A_{y1} .

It means that the Physarum polycephalum behaves as intended.

6 SUMMATION

In the paper, we have shown how to construct basic logic gates in Physarum polycephalum machines using the idea of ladder diagrams. Proper relationships between ladder diagrams and Physarum polycephalum computing have been pointed out. The paper consists, in the first step, in research connected to developing a biological architecture of different abstract digital devices based on the ladder diagram principle. This principle is very popular in programming Programmable Logic Controllers (PLCs). However, in case of PLCs, the ladder diagram principle is used only at the abstract level as a high-level programming language. The program is executed by silicon microprocessors based on the standard architectures not reflected in the direct flow of power. Our approach could allow a direct hardware implementation of this principle in different controllers. In our case, it is a biological hardware implementation.

The approach presented in this paper may be used in different constructions of logic gates in chemical media or on biological substrates which are based on the flow or propagation of some medium. An important thing is to find the mechanism of controlling the flow or propagation in the restricted regions by some elements which can be activated or deactivated. The main problem for the further work is to search for mechanisms of constructing complex digital systems. For example, in ladder diagrams, negations of complex expressions must be realized using some internal variables enabling us to carry states of coils to states of contacts.

Another task for the further work is to implement the presented idea in the experimental environment for more complex circuits. In this case, an important thing is the proper control over states of stimuli, i.e., their rapid activation or deactivation. Moreover, the

construction requires adjusting proper regions of influences of individual stimuli to model serial or parallel connections.

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