

# Dimensionality Reduction for Supervised Learning in Link Prediction Problems

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**Abstract:** In recent years, a considerable amount of attention has been devoted to research on complex networks and their properties. Collaborative environments, social networks and recommender systems are popular examples of complex networks that emerged recently and are object of interest in academy and industry. Many studies model complex networks as graphs and tackle the link prediction problem, one major open question in network evolution. It consists in predicting the likelihood of an association between two not interconnected nodes in a graph to appear. One of the approaches to such problem is based on binary classification supervised learning. Although the curse of dimensionality is a historical obstacle in machine learning, little effort has been applied to deal with it in the link prediction scenario. So, this paper evaluates the effects of dimensionality reduction as a preprocessing stage to the binary classifier construction in link prediction applications. Two dimensionality reduction strategies are experimented: Principal Component Analysis (PCA) and Forward Feature Selection (FFS). The results of experiments with three different datasets and four traditional machine learning algorithms show that dimensionality reduction with PCA and FFS can improve model precision in this kind of problem.

## 1 INTRODUCTION

For the last years, the constant advances in information technology have significantly contributed to increase the amount of interconnected data around the world. In this scenario, many large, complex and dynamic digital networks have emerged. For example, social networks, collaborative environments and recommender systems, just to name a few, are complex networks provided by Web 2.0 and e-Science. Both scientific and industrial communities have devoted a considerable amount of attention to the investigation of such networks and their properties (Liben-Nowell and Kleinberg, 2003). Many studies model networks as graphs, where a vertex (node) represents an item in the network (e. g. person, web page, product, movie, photo, etc) and an edge represents some sort of association between the corresponding items (e.g. a purchase connects the product and the client).

Complex networks are very dynamic, since new vertices and edges can be added to the graph over the time. Understanding the reasons that make the

networks evolve is a complex question that has not been properly answered yet. One major but comparatively easier problem in the study of network evolution is the link prediction task. It consists in predicting the likelihood of an association between two not interconnected nodes in the graph to appear (Lü and Zhou, 2011). We have noticed that link prediction has been applied for two different tasks: predicting “future” links (Liben-Nowell and Kleinberg, 2003), when the goal is to discover which links will appear in the future, and predicting “missing” links (Lü and Zhou, 2011), used for inferring links that already exist in the network, but are not represented yet.

One of the approaches to the link prediction problem is based on supervised learning (Hasan et al, 2006; Li and Chen, 2009; Pujari and Kanawati, 2012; Sa and Prudencio, 2011; Benchetarra et al., 2010). Such approach converts original data to a binary classification problem. In this problem, each data point corresponds to a pair of vertices with a class label denoting their link status: positive if the association between the two vertices exists,

negative, otherwise. Additional features must be added to the dataset in order to describe its data points and represent some sort of proximity between the pair of vertices. A machine learning algorithm is applied to the enriched dataset in order to generate a classification model.

Many features have been experimented in supervised learning for link prediction problems (Hasan and Zaki, 2011). Typically, these features are classified in three groups: (a) node and edge information (e.g. client's age, job location, etc); (b) aggregated features (e.g. sum of e-mails, sum of contacts, etc); (c) topological measures extracted from the graph (e.g. common neighbors, jaccard's coefficient, etc). Choosing which features to add to the dataset is crucial for the learning process. It is a typical optimization problem where there is a search for a reduced set of features that preserves, as much as possible, the original amount of information available in the dataset.

Although many works have reported promising results with the binary classification approach for link prediction, choosing the set of features to train the classifiers is acknowledged to be a major challenge (Hasan and Zaki, 2011).

The machine learning community has developed many methods to deal with the high-dimensional space problem (Yu and Liu, 2003; Caruana et al., 2008). In general, these methods are based on two approaches (Kohavi and John, 1997): filter and wrapper. The filter approach consists in calculating some evaluation metric (such as correlation or information gain) from the dataset in order to select the features that lead to better evaluations. On the other hand, the wrapper approach is iterative and, for each iteration, selects a subset of features, reduces the original dataset (using the selected features) and uses it to construct and evaluate a predictive model. This process is repeated until a stopping criterion is satisfied.

Dimensionality reduction techniques can also be classified in two groups: feature selection and feature extraction. The main difference between them is that the first group does not change original attributes and the second one transforms original features in new attributes.

Despite its acknowledged importance for supervised learning tasks, few works have investigated the effects of dimensionality reduction in link prediction. Table 1 shows examples of dimension reduction techniques according to the classifications presented above.

Feature Selection for Link Prediction – FESLP (Xu and Rockmore, 2012) and Cross-Temporal Link

Prediction – CTLP (Oyama et al., 2011) have been specifically designed to be used in link prediction applications. FESLP selects features based on their correlation and information gain. CTLP assumes that features useful for link prediction change over time and, thus, searches for sets of features which best describes nodes and their variations as time passes by. Oyama et al., (2011) used CTLP in a dynamic, time evolving environment to determine the identities of real entities represented by data objects observed in different time periods. Xu and Rockmore (2012) ran their experiments with datasets generated from an email network of a large academic university.

Forward Feature Selection – FFS (Freitas, 2002) and Principal Component Analysis – PCA (Jackson, 1991) are methods traditionally used by the machine learning community.

FFS is iterative. In each iteration, FFS searches for a feature that, combined to a set of selected features, builds a reduced dataset that leads to the best predictive model (according to some criterion, such as precision or recall, for example). Its loop will perform until no predictive model built in the current iteration shows improvement. Initially, the set of selected features is empty and FFS builds as many reduced datasets as the number of attributes in the original dataset (each reduced dataset contains exactly one attribute plus the class, target of the problem).

PCA is a statistical technique that uses an orthogonal transformation to convert a dataset of possibly correlated features into a set of linearly uncorrelated attributes called principal components. The number of principal components is less than or equal to the number of original features. Such components are orthogonal because they are the eigenvectors of the covariance matrix, calculated with the attributes of the original dataset.

To the best of our knowledge, both FFS and PCA have never been used to reduce dimension in link prediction applications.

Table 1: Examples of Dimensionality Reduction Methods.

Methods	Approach	Feature Treatment
FESLP	Filter	Selection
CTLP	Filter	Selection
PCA	Filter	Extraction
FFS	Wrapper	Selection

So, this paper evaluates the effects of PCA and FFS as dimensionality reduction preprocessing techniques to the binary classifier construction in link prediction applications. In contrast to FESLP and CTLP, we have run our experiments over three

open and popular datasets (DBLP, Amazon, Flickr). Traditional learning algorithms like SVM, Naïve Bayes, K-NN and CART (Hasan et al, 2006) were tested with both dimensionality reduction methods. The results show that dimensionality reduction with FFS and PCA can improve model precision in this kind of problem when compared to the use of the complete set of features (CS).

This work was organized in four other sections. Section 2 presents details about the experimental setup. Configurations of the classification algorithms and information about the used datasets are also described in Section 2. Section 3 presents and analyses the results obtained. Conclusions and future work are posed in Section 4.

## 2 EXPERIMENTAL SETUP

### 2.1 Datasets

We have selected three different datasets to perform our experiments: DBLP, Amazon and Flickr. All of them are available on the web for download (Ley, 2009; Leskovec and Krevl, 2014). The first one contains data about co-authoring scientific publications and has been used in many works concerning future link prediction (Hasan et al, 2006; Oyama et al., 2011; Benchettara et al., 2010). The idea is to predict future interactions (links) that could occur between the authors (vertices). The second dataset is formed by product co-purchasing (with products as vertices and their relations of being sold together as links). The Flickr dataset contains pictures (vertices) and their associations (links). The link prediction task in DBLP is slightly different from the ones in Amazon and Flickr. While in DBLP dataset the goal is “future” link prediction, the task in both Amazon and Flickr datasets is to predict “missing” links among products (Amazon) and photos (Flickr).

### 2.2 Feature Set

For this work, a feature set with 15 attributes was selected. Most of them were selected due to their use and relevance in many applications of link prediction (Hasan and Zaki, 2011). However, some other features that were not so common in the link prediction task were chosen as well, in order to evaluate their relevance in the datasets used in the experiments. The features are described as follows:

1. Shortest path length (Hasan and Zaki, 2011):

this traditional feature corresponds to the smallest number of edges that forms a path between a pair of vertices;

2. Second shortest path length (Hasan et al, 2006): the length of the shortest path different from the previous one;
3. Common neighbours (Hasan and Zaki, 2011): the number of common neighbours between two given vertices;
4. Sum of neighbours (Hasan et al., 2006): the total of neighbours of each vertex from a pair;
5. Jaccard’s Coefficient (Hasan and Zaki, 2011): the ratio between the number of common neighbours and the number of total neighbours of each vertex;
6. Sum of intermediate elements: taking into account the structure of a bipartite graph, the sum of intermediate elements refers to the total number of elements connected to both vertices that form a pair;
7. Adamic/Adar similarity (Adamic and Adar, 2003): it is the sum of the secondary common neighbors (neighbors of neighbors), with a smaller weight (relevance) than the primary neighbors (direct neighbors).
8. Preferential attachment (Barabasi et al., 2002): product of the number of neighbours of both vertices that form a pair;
9. Katz measure (Katz, 1953): sum of lengths of all paths existing between each pair of vertices, providing higher relevance to paths with smaller lengths.
10. Leicht-Holme-Newman Index (Leicht et al., 2006): ratio between the number of common neighbours of a pair of vertices and their preferential attachment;
11. Clustering coefficient (Hasan and Zaki, 2011): this metric is related to the number of triangles that each vertex is part of;
12. Closeness centrality (Freeman, 1978): the inverse value of the average distance of each vertex of the pair to all other vertices in the graph;
13. Average clustering of the nodes (Saramäki et al., 2007): the mean of the local clustering coefficient of the vertices;
14. Average neighbour degree (Barrat et al., 2004): the average of the degree of the neighbours of the pair of vertices;
15. Square clustering coefficient (Lind et al., 2005): this metric is related to the number of squares that each vertex is part of.

### 2.3 Method

Figure 1 depicts the process performed for each group of experiments.

Conceptually, our experimental process has three major stages: preprocessing, configuration, and evaluation. The first stage prepares the data for the next stages; the second one defines the settings of both dimensionality reduction strategy and classification algorithm, and the last stage trains and evaluates the learning model over the reduced datasets.

All the stages were developed in Python and were based on Scikit-learn (Pedregosa et al, 2011), a well known machine learning library, and on NetworkX (Hagberg et al., 2008) a development environment frequently used to implement and process graph structures.

#### 2.3.1 Pre-processing

This stage is performed only once for each dataset. It randomly selects samples from the original data in order to build a dataset for the classification task. The new dataset is the one used by the other stages. This stage has the following steps:

- a) Binary Class Transformation: this step is responsible for taking a sample from the original dataset modelled as a graph  $G$  and turning it into a dataset formed by the pairs of vertices and their classes. Each of the randomly selected pairs of vertices is classified as positive or negative. The classification process will depend on the kind of task performed: for the future link prediction, the original dataset is divided into two range of years (Hasan et al., 2006) – the training years (which represents the “present” period of time, and is represented by the graph  $G_t$ , originated from the graph  $G$ ), and the test years (which represents the “future” period of time, and is represented by the graph  $G_{t+1}$ , also originated from the graph  $G$ ). A selected pair of vertices cannot have a link between them in the training range, but may or may not have a link in the test range, being classified as positive or negative example, respectively. This process was used with the DBLP dataset. For the missing link prediction task, the sample is selected from the graph  $G$ , and the pairs of vertices are classified as positive or negative if they have a link between them or not. However, once the positive examples are selected, their links are removed from the graph  $G_t$ , which is a copy from the original graph  $G$  (in order to simulate their absence and consider

them the “missing” links). This criterion was applied to Amazon and Flickr datasets.

- b) Feature Set Construction: after building the sample, the features of each selected pair of vertices are calculated. As we have used only topological features for this work, the features are calculated based on the graph structure  $G_t$  (which can represent different versions of the original graph  $G$ , depending on the task performed). We normalized the features values using the standard score (Hasan et al., 2006). After normalized, the calculated features are attached to the tuple corresponding to its pair of vertices in the dataset for classification.

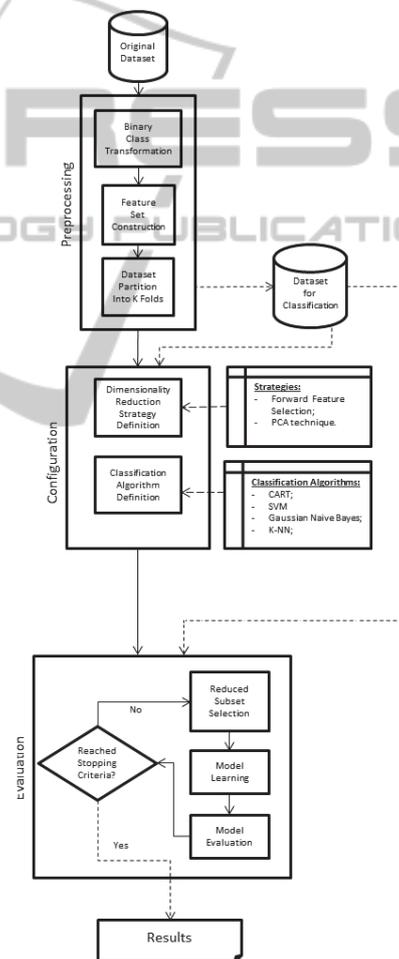


Figure 1: The sequence of stages and their steps performed for each experiment.

- c) Dataset Partition into K-Folds: this step divides the dataset for the classification task into  $K$  different folds, adding the index of the fold of each pair of nodes to its corresponding tuple. The purpose of keeping the folds previously defined

was to consider the same dataset partition for the  $k$ -fold cross-validation process to be executed with every classification algorithm.

### 2.3.2 Configuration

The data analyst uses this stage to select both the dimensionality reduction strategy and the classification algorithm (and its parameters to be employed in the evaluation stage). This stage has the following steps:

- a) Dimensionality Reduction Strategy Definition: in this step, the dimensionality reduction strategy that will be used for future evaluation is chosen. There are two available strategies: FFS and PCA. The former has no parameter. For the latter, the maximum number of principal components that will be generated from the dataset must be defined by the user.
- b) Classification Algorithm Definition: this step is responsible for defining the classification algorithm and its configuration to be used in the supervised learning process. The tested algorithms and their configurations are listed in section 2.4.

### 2.3.3 Evaluation

The supervised learning process and dimensionality reduction strategy evaluation effectively happen in this stage. As depicted in the figure 1, the evaluation stage is iterative, executing its steps in a loop. If the PCA technique is chosen as dimensionality reduction strategy, this loop will perform until the maximum number of principal components are evaluated. Otherwise, the FFS will be used, and as it is an incremental strategy, its loop will perform until there is no improvement of precision of the built predictive models. The results of this stage are the precision of the most accurate predictive model and the number of principal components or features (depending on the strategy) used to build this model. This stage has the following steps:

- a) Reduced Dataset Selection: this step applies the dimensionality reduction strategy in the pre-processed dataset, creating the reduced datasets. If the FFS strategy is selected, at its first iteration, a reduced dataset with each attribute of the original feature set will be generated. However, if the PCA technique is selected, there will be as many reduced datasets as the previously defined maximum number of principal components.
- b) Model Learning: In order to obtain a predictive

model, this step applies the classification algorithm to the reduced dataset produced by the previous step. The predefined configuration of the algorithm is always used during the process. As we are using the  $k$ -fold cross validation, we build  $k$  different predictive models for each reduced dataset. We have parallelized this process, building these predictive models simultaneously.

- c) Model Evaluation: the predictive model is evaluated in this step. All the  $k$  predictive models are evaluated using the traditional  $k$ -fold cross validation. We have used the precision of the classification model to evaluate the reduced dataset. As mentioned before, the validation was parallelized, so the evaluation of each predictive model happens simultaneously, and the final precision is the average precision of these predictive models.

## 2.4 Classification Algorithms

Although there are many classification algorithms for supervised learning, we had to choose some of them to perform our experiments. Summarized in Table 1, our choices followed the ones reported in (Hasan et al., 2006).

We performed some preliminary experiments with each dataset, in order to set the parameter values depicted in Table 2. For example, we ranged  $k$  of  $k$ -NN from 3 to 9 in order to choose the one ( $k=5$ ) with the best classification results in the evaluated datasets. Once set, such configurations were used in all experiments.

Table 2: Classification algorithms used in this work.

Algorithm	Comment
SVM	'RBF' Kernel; penalty = 100; kernel coeff. = 0.1
K-NN	K=5
Naïve Bayes (NB)	Gaussian Distribution
CART	Random State = 10

## 3 RESULTS AND DISCUSSIONS

We performed three groups of experiments. Each group considered one of the three datasets. For the future link prediction task in the DBLP dataset, we have used a period of time from 1990 to 2000 as the training years, and from 2001 to 2005 as test years. As we have used the Amazon and Flickr datasets for the missing link prediction task, we did not have to define a period of time for them. We preprocessed

each dataset only once, at the beginning of the experiments of its group. Then, we have applied PCA, FFS and CS strategies with each classification algorithm in each dataset using the 10-fold cross validation process. The CS (Complete Set) “strategy” was considered our baseline. It always used the complete set of attributes (15 features). In fact, no dimensionality reduction was performed with it. With PCA, we have used 14 as the maximum number of principal components for each dataset. The FFS strategy demanded no parameter.

We have built a total of 5280 predictive models. Table 3 summarizes our results. Each triple (dataset, dimensionality reduction strategy, classification algorithm) defines a cell that contains two numbers. The first one is the average precision (%) of the classification models produced by the subset of experiments that applied the corresponding dimensionality reduction strategy to the respective classification algorithm and dataset during the 10-fold cross validation process. The second one (presented between brackets) indicates the number of features (or principal components) of the most precise classification model produced in such subset of experiments.

The FFS strategy outperformed CS in eight of twelve cases (66.6%). Only in the subset of experiments with the Amazon dataset and SVM algorithm, FFS presented the same average precision of CS, but with a smaller feature subset. The PCA outperformed CS in half of the cases (50%), having the same average precision in three of them.

FFS overcame PCA in nine of twelve cases (75%), while PCA only overcame FS in two of all cases (16.6%).

It is worth to mention the improvement of the Gaussian Naïve Bayes (NB) algorithm when evaluated with a reduced dimension space. Not surprisingly, for all datasets, this algorithm performed much better with less correlated attributes or principal components than with the complete original feature set.

#### 4 CONCLUSIONS

Link prediction is an important task in the scenario of complex networks and supervised learning is an approach to deal with it. High dimensionality is one major problem in machine learning applications. And so it is in the supervised learning link prediction task. In spite of the importance of this problem, just a few works related to dimensionality reduction in link prediction have been developed. However, none

of them have used classical techniques from the machine learning literature, such as principal components analysis (PCA) and forward feature selection (FFS).

Table 3: Summary of results obtained with the three groups of experiments.

Dataset	Algorithm	Dimensionality Reduction Strategy		
		CS (%)	FFS (%)	PCA (%)
DBLP	CART	73.7 [15]	79.9 [02]	73.6 [10]
	SVM	81.3 [15]	81.2 [07]	81.3 [11]
	K-NN	80.0 [15]	79.2 [04]	80.1 [10]
	NB	64.2 [15]	80.5 [05]	78.0 [01]
Amazon	CART	96.4 [15]	97.3 [03]	95.8 [04]
	SVM	97.5 [15]	97.5 [07]	97.5 [11]
	K-NN	97.2 [15]	97.5 [04]	97.3 [09]
	NB	91.8 [15]	97.0 [03]	92.9 [03]
Flickr	CART	89.5 [15]	89.2 [02]	77.3 [07]
	SVM	82.6 [15]	83.7 [03]	82.6 [10]
	K-NN	79.2 [15]	86.4 [06]	79.8 [08]
	NB	65.5 [15]	79.3 [01]	71.0 [04]

In this paper, we have explored the effects of dimensionality reduction in the link prediction task, by applying the traditional techniques of PCA and FFS. The main contributions of our experiments include: (a) results that showed that traditional dimensionality reduction techniques can lead to more precise and compact models in link prediction; (b) the use of open datasets (which makes it easier for other researchers to reproduce the experiments) that cover “future” (DBLP) as well as “missing” (Amazon and Flickr) link prediction applications; (c) insertion of some topological measures (the last three ones described in subsection 2.2) not usually employed in link prediction state of art to describe the datasets.

As future work, we consider the use and evaluation of other classical feature selection techniques in link prediction, including optimization meta-heuristics, such as genetic algorithms. It would be also interesting to use other datasets that include not only the topological information, but information from the graph nodes as well, in order to consider a wider range of features. Experiments with other classification algorithms for those link prediction tasks and the use of other evaluation measures such as recall, F-measure and AUC are also desirable.

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