Detect the Unexpected: Novelty Detection in Large Astrophysical Surveys using Fisher Vectors

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Abstract: Finding novelties in an untagged high dimensional dataset poses an open question. In this work, we present an innovative method for detecting such novelties using Fisher Vectors. Our dataset distribution is modeled using a Gaussian Mixture Model. An anomaly score that stems from the theory of Fisher Vector is computed for each of the samples. We compute the anomaly score on the SDSS galaxies spectra dataset and present the different types of novelties found. We compare our findings with other outlier detection algorithms from the literature, and demonstrate the ability of our method to distinguish between samples taken from intersecting probability distributions.

1 INTRODUCTION

The detection of outliers in real-world datasets is a key component in the analysis of unfamiliar processes. Historically, many discoveries in astronomy were made serendipitously by encountering unique unexpected observations while examining the skies. Two famous examples of this exhausting search are the Cosmic Microwave Background and Uranus. Today, when large amounts of astronomical information are available, visual inspection of data is a daunting task. Current astronomical surveys datasets may contain millions of instances each, from a variety of different sources, and are usually categorized by fitting physical models. The emergence of new objects throughout astronomical surveys, without a clear physical understanding of their origins, may not be explained by any of these models.

The Sloan Digital Sky Survey (SDSS; Eisenstein et al., 2011) is one of the most successful astronomical surveys. The SDSS spectroscopic dataset consists 3 million optical spectra. These include ~ 2 million galaxy spectra, with which we will work, and an additional ~ 1 million spectra of quasars and stars. The SDSS also contains imaging data covering 14,055 square degrees of sky, which is about one third of the sky. Despite its size, large fractions of the SDSS were in fact visually inspected. Hall et al. (2013), for example, visually inspected 100,000 quasar spectra, covering all objects in the relevant redshift range with good signal to noise ratio, in the search of a specific phenomena. Another large scale visual inspection campaign, in this case targeting imaging data, is the Galaxy Zoo (Lintott et al., 2008). Citizen scientists inspected various SDSS catalogs and detected a broad range of objects. It is worthwhile noting that this initiative led to the detection of a previously unknown category of galaxies, named the green pea galaxies (Cardamone et al., 2009).

Upcoming surveys lead us to a new era where a complete visual analysis of the data would not be feasible. For example, the Dark Energy Spectroscopic Instrument (DESI, Levi et al., 2013) will include spectra of 25 million galaxies. This is about an order of magnitude more objects than in SDSS. The DESI dataset will contain unique galaxies with occurrence rate of one in tens of millions. Detecting such galaxies would require the employment of anomaly detection algorithms.

A desirable outcome of processing a large scale survey would be to separate the wheat from the chaff, by dividing the instances into two or more sets. One set should contain the frequent instances and the outliers that obey an extreme behaviour of a commonly known pattern. The other sets should contain only the proposed novelties, instances without a clear physical model that describes them. The sorting of instances to these sets may be achieved by assigning each an

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anomaly score. Many solutions to this task have been proposed. Each solution usually falls into one of the following three approaches: Reconstructionbased anomaly detection, distance-based anomaly detection, and probabilistic-based anomaly detection. For further reading, refer to Pimentel et al. (2014).

Similar anomaly detection techniques are commonly applied in many research areas. However, each area may possess distinct motivations. As a consequence, measuring the success a proposed algorithm may vary between different fields. When searching for bank frauds, the criteria for success could be the fraction of detected frauds. In scientific application, however, our ultimate goal is to detect previously unseen phenomena. Such phenomena might manifest only once in the entire dataset. It is reasonable to think that in order to increase our chances of detecting such objects, the applied methods should be sensitive to a wide range of unusual behaviours. For this reason, in scientific applications the criteria for success could be the range of different types of detected anomalies. In physics, most of the unusual objects detected by any method had previously been known and discussed in the literature. The detection of an object whose properties are unknown is an extremely rare event that has a considerable element of luck, making it an unreasonable measure of success.

In this paper we present an anomaly detection method that can also be refined for novelty detection. Our proposed approach first estimates a model of the galaxy's spectra distribution by utilizing a Gaussian Mixture Model (GMM). Next, we show that by using Fisher Vectors as a basic building block, an appropriate anomaly score emerges. We show our results on a 1D and 2D toy problems, and present unique findings of our method on the SDSS dataset.

2 RELATED WORK

Applications of anomaly detection in astronomy include Boroson and Lauer (2010) who detected anomalies in SDSS quasar spectra using Principal component Analysis (PCA). After applying PCA to their dataset they detected anomalies using three different scores; PCA reconstruction error, PCA coefficients magnitude, and isolation in the PCA coeffcients space. They noted that all three scores were able to detect interesting anomalies, and did not find a strong distinction between the types of anomalies detected by the different methods.

Distance-based anomaly detection was applied to SDSS galaxy spectra in Baron and Poznanski (2017), using the unsupervised Random Forest distance (Shi and Horvath, 2006). Notably, Baron and Poznanski (2017) were able to detect many types of interesting galaxies, most notably a post starburst galaxy with evidence for outflows, which were followed up on in Baron et al. (2018). A similar method was applied in Reis et al. (2018) to infrared stellar spectra. Distance based anomaly detection was also used for light-curve data in Protopapas et al. (2006) and Richards et al. (2012). In order to work with raw light-curve data, a translational invariant distance measure is required, and indeed, Protopapas et al. (2006) used the cross correlation distance. Another popular approach for handling light-curve data is representing them with a set of extracted features. Richards et al. (2012) used extracted features for a distance-based anomaly detection. Similarly to Baron et al. (2018); Reis et al. (2018), they used Random Forest distance, with the difference that Richards et al. (2012) used a supervised Random Forest, pre-trained on labeled data.

Meusinger et al. (2012) used self-organizing maps (Kohonen, 1982, SOM,) for anomaly detection in SDSS quasar spectra. Their unusual quasars were found by visually inspecting the spectra of objects residing in low density regions of the SOM. This is an example of anomaly detection by dimensionality reduction in which the anomalies are detected in the low dimensional embedding of the data. The advantage of such a method is that in the low dimension it is easy to detect the anomalies. In Meusinger et al. (2012) this was done by simple visual inspection.

Supervised anomaly detection was performed in Nun et al. (2014), where a Random Forest was trained on labeled data consisting of variable objects lightcurve features. Using the Random Forest to predict the class of unlabeled objects, anomalies are detected according to their obtained Random Forest voting distribution. This algorithm was applied to 20 million light-curves from the MACHO survey, in two iterations aimed at reducing the fraction of detected observational artifacts. Artifacts detected as anomalies in the first iteration were added to the labeled data of the second iteration.

Nun et al. (2016) detected anomalies in astronomical light-curves using an ensemble of anomaly detection methods. Their ensemble included 5 methods. Two k-Nearest Neighbors approaches, Random Forest and Joint Probability (Nun et al., 2014), Local Correlation Integral, and Learned Probability Distribution. They have also created an online tool for the inspection of the detected anomalies by the community¹.

In this paper, we compare our results on SDSS galaxy spectra with the following methods: (i) un-

¹Catalog of astronomical outliers

supervised Random Forest as applied in Baron and Poznanski (2017); Reis et al. (2018), (ii) PCAreconstruction similarly to Boroson and Lauer (2010) (we only use the reconstruction error score), and (iii) isolation forest (Liu et al., 2008), a baseline method often used in anomaly detection. Isolation forest detects anomalies directly without modeling the entire dataset. This is done by detecting objects that are most frequently isolated by randomly partitioning the data. We used scikit learn Pedregosa et al. (2011) in the implementation of all three methods.

3 BACKGROUND

This work presents an anomaly detection method that is based on Fisher Vectors. Before delving into the method itself, we review the relevant mathematical foundations.

Gaussian Mixture Model. The first step of our method is creating a generative statistical model of the dataset. The chosen model for this task is the Gaussian Mixture Model (GMM) for its simplicity and its ability to perform well on a variety of tasks.

GMM is a parametric probability density function represented as a weighted sum of multivariate Gaussians. The multivariate Gaussian itself represents a distribution over vectors in $x \in \mathbb{R}^D$. The probability density function of a mixture of *K* multivariate Gaussian is:

$$p(x|\pi_{k},\mu_{k},\Sigma_{k}) = \sum_{k=1}^{K} \frac{\pi_{k}}{\sqrt{(2\pi)^{D} \det |\Sigma_{k}|}} e^{-\frac{1}{2}(x-\mu_{k})^{T}\Sigma_{k}^{-1}(x-\mu_{k})}.$$
 (1)

The model parameters, $\pi_k, \mu_k \in \mathbb{R}^D, \Sigma_k \in \mathbb{R}^D \times \mathbb{R}^D$, for a given dataset $X = \{x_1, x_2, \dots, x_n\}$ are learned by maximizing the log-likelihood, \mathcal{L} , of the data:

$$\mathcal{L}(\pi_k,\mu_k,\Sigma_k;X) = \frac{1}{n} \sum_{i=1}^n \log \sum_{k=1}^K p(x_i | \pi_k,\mu_k,\Sigma_k) \quad (2)$$

using the Expectation Maximization (EM) algorithm (Dempster et al., 1977).

Fisher Information Matrix. The Fisher Information Matrix is a measurement for the amount of information present for the model's parameters, $\lambda_{\alpha} \in \Theta$, that is available in the data (Cover and Thomas, 2012). It is defined as

$$F_{\lambda_{\alpha}\lambda_{\beta}} = \mathbb{E}_{x \sim p(x|\theta)} \left[\partial_{\lambda_{\alpha}} \log p(x|\theta) \partial_{\lambda_{\beta}} \log p(x|\theta) \right].$$
(3)

For the case where $p(x|\theta)$ is GMM distribution, and under the assumption that there is no correlation between the different parameters of the mixture, Σ_k is diagonal, and can be expressed as a one-dimension vector, $\sigma_k \in \mathbb{R}^D$. Under this assumption, *F* is also diagonal and can be written as a vector (Perronnin et al., 2010),

$$F_{\mu_{kj}} = \frac{\pi_k}{\sigma_{kj}^2} \quad F_{\sigma_{kj}} = \frac{\pi_k}{2\sigma_{kj}^4} \quad . \tag{4}$$

The contribution of a sample to each of the components of F is

$$\Delta F_{\lambda_{\alpha}} = p\left(x|\theta\right) \left(\partial_{\lambda_{\alpha}} \log p\left(x|\theta\right)\right)^{2}.$$
 (5)

Fisher Vectors. Fisher Vectors (FV) were first introduced by Perronnin and Dance (2007) as an efficient way to classify images. The FV is proportional to the derivatives of the GMM's log-likelihood w.r.t its parameters, $\lambda = \{\pi_k, \mu_k, \sigma_k\}$, for a given vector, $x_i \in \mathbb{R}^D$. The derivatives of the log-likelihood is

$$\left. \frac{\partial \mathcal{L}}{\partial \mu_k} \right|_{x_i} = \frac{p(x|\lambda_k)}{\sum\limits_{k'=1}^{K} p(x|\lambda_{k'})} \frac{x_i - \mu_k}{\sigma_k^2}, \tag{6}$$

$$\frac{\partial \mathcal{L}}{\partial \sigma_k}\Big|_{x_i} = \frac{p(x|\lambda_k)}{\sum\limits_{k'=1}^{N} p(x|\lambda'_k)} \left(\frac{(x_i - \mu_k)^2}{\sigma_k^2} - \sigma_k^2\right).$$
(7)

The derivatives w.r.t the priors, π_k , are ignored as they usually bring very little information (Perronnin et al., 2010). Whitening the different dimensions is accomplished by normalizing the derivatives by using the diagonal Fisher Information Matrix. The normalized gradients are

$$\left\lfloor \frac{\partial \mathcal{L}}{\partial \mu_k} \right|_{x_i} \right\rfloor_N = \frac{p(x|\lambda_k)}{\sum\limits_{k'=1}^K p(x|\lambda'_k)} \frac{1}{\sqrt{\pi_k}} \frac{x_i - \mu_k}{\sigma_k}, \quad (8)$$

$$\begin{bmatrix} \frac{\partial \mathcal{L}}{\partial \sigma_k} \Big|_{x_i} \end{bmatrix}_N = \frac{p(x|\lambda_k)}{\sum\limits_{k'=1}^N p(x|\lambda'_k)} \frac{1}{\sqrt{2\pi_k}} \left(\left(\frac{x_i - \mu_k}{\sigma_k^2} \right)^2 - 1 \right). \quad (9)$$

The Fisher Vector, $\mathcal{FV}_{\vec{\lambda}_k}(x_i) \in \mathbb{R}^D$, is the vector obtained by a concatenation of all the normalized gradients. An empirical observation by Perronnin et al. (2010) was that the FV become sparse as the number of Gaussians in the mixture increases.

4 FV-BASED ANOMALY DETECTION

In this section, we utilize the FVs derived from a diagonal covariance GMM and present a prescription for creating an anomaly scores. Let $X = \{x_1, x_2, ..., x_n\}$, $x_i \in \mathbb{R}^D$ be a set of samples from an unknown distribution. A set of GMM parameters, $\theta = \{\pi_k, \mu_k, \sigma_k\}_{k=1}^K$ is estimated from a fit to *X*.

To establish an anomaly score, we need to identify samples that are unlikely to be generated by our probability distribution. Anomalies can be described by a probability distribution function, which is a sum of two or more components, broad and narrow ones. In such case, the regions of low probability consist of extreme samples from the class of regular objects and do not include any samples from the anomaly class. Given a shift, ε , to the Gaussian parameters, λ , the difference in the log-likelihood of generating a given sample $x_i \in \mathbb{R}^D$ is

$$\Delta_p = \log p(x_i, \lambda + \varepsilon) - \log p(x_i, \lambda). \quad (10)$$

When $\varepsilon \ll 1$, Eq. (10) can be expanded to first order in ε ,

$$\Delta_p = \epsilon \partial_{\lambda} \log p(x,\lambda) + O(\epsilon^2). \quad (11)$$

As the probability of each Gaussian to generate x_i decays exponentially with the distance from x_i , most samples rely only on a small number of Gaussians. Up to a scaling, Eq. (11) is equal to $\mathcal{FV}(x_i)$. The contribution for each single sample, x_i to the estimation of the distribution's parameters is apparent in Eq. (3). The higher the estimated probability is to generate x_i , the more it contributed to information content of the model. By assuming that the different features of x_i , $x_{i,j}$ are independent, we can reduce the dependency of the probability only on the *j*th feature.

Denote by $p_j(x_i|\lambda)$ the probability density function over the estimated GMM after integrating out all the features $\{m\}_{m=1}^{D}$ in x_i besides for the *j*th feature,

$$p_{j}(x_{i}|\lambda_{k}) = \int_{-\infty}^{\infty} p(x_{i,j}|\lambda) dx_{i,j} \cdots dx_{i,j-1} dx_{i,j+1} \cdots dx^{i,D}$$
$$= \frac{1}{\sqrt{2\pi\sigma_{k}^{2}}} e^{-\frac{(x_{i,j}-\mu_{k,j})^{2}}{2\sigma_{k,j}^{2}}}.$$
 (12)

Eq. (5) presents the contribution of each sample x_i to Eq. (3). Our proposed anomaly score is the one-

dimensional contribution of each sample x_i to Eq. (3),

$$\mathcal{A}_{sc}(x_{i}) = \max_{k} \left[\sum_{j} p_{j}\left(x_{i} | \vec{\lambda}_{k}\right) \mathcal{FV}_{\lambda_{kj}}(x_{i}) \mathcal{FV}_{\lambda_{kj}}(x_{i}) \right]. \quad (13)$$

This score achieves two competing criteria. It awards a low score for samples with a low probability of appearing, thus focusing on the higher probability regions of the estimated distribution, $p(x|\lambda)$, as the integrated probability decays with the distance of the features from the estimated Gaussian means. On the other hand it awards a higher score to samples that contain a large FV component.

The proposed anomaly score can also be normalized before searching for the maximum FV component,

$$\bar{\mathcal{A}}_{sc}(x_{i}) = \max_{k} \left[\frac{\sum_{j} p_{j}\left(x_{i} | \vec{\lambda}_{k}\right) \mathcal{F} \mathcal{V}_{\lambda_{kj}}(x_{i}) \mathcal{F} \mathcal{V}_{\lambda_{kj}}(x_{i})}{\sigma_{\mathcal{A}_{sc}^{k}}^{2}} - \frac{\mu_{\mathcal{A}_{sc}^{k}}}{\sigma_{\mathcal{A}_{sc}^{k}}^{2}} \right]$$
(14)

Where $\mu_{\mathcal{A}_{sc}^{k}}, \sigma_{\mathcal{A}_{sc}^{k}}$ are the expectation value and standard deviation,

$$\mu_{\mathcal{A}_{sc}^{k}} = \underbrace{\mathbb{E}}_{x_{i} \sim p(x|\lambda)} \left[\sum_{j} p_{j} \left(x_{i} | \vec{\lambda}_{k} \right) \mathcal{F} \mathcal{V}_{\lambda_{kj}} \left(x_{i} \right) \mathcal{F} \mathcal{V}_{\lambda_{kj}} \left(x_{i} \right) \right],$$
(15)

$$\sigma_{\mathcal{A}_{sc}^{k}}^{\mathcal{Z}} = \underbrace{\mathbb{E}}_{x_{i} \sim p(x|\lambda)} \left[\left(\sum_{j} p_{j} \left(x_{i} | \vec{\lambda}_{k} \right) \mathcal{F} \mathcal{V}_{\lambda_{kj}} \left(x_{i} \right) \mathcal{F} \mathcal{V}_{\lambda_{kj}} \left(x_{i} \right) \right)^{2} \right] - \mu_{\mathcal{A}_{sc}^{k}}^{2} \cdot (16)$$

This adaptation to the score enhances the contribution of FV originated from low probability clusters, and thus, enables the detection of outliers in low probability clusters.

The use of FV assists with detecting anomalies generated by localized probabilities of small clusters of objects that may exist in the dataset.

5 RESULTS

We present our results on two sets of problems. We first show how our method performs on a toy-problem

in section 5.1, and then compare various anomaly detection methods on the SDSS dataset in section 5.2. In both cases we found out that using the FVs of the σ parameters Eq. (9) performed better.

The VLFeat (Vedaldi and Fulkerson, 2008) package was employed for GMM estimation and for the FVs extraction.

5.1 Toy Problem

In this section we evaluate our method under a setting of randomly generated 1D and 2D samples as seen in Fig. 1. The 1D toy dataset contains 10000 points sampled from an 1D gaussian, $\mathcal{N}(0,1)$, and a set of 100 novelties sampled from another 1D gaussian, $\mathcal{N}(2.5, 10^{-5})$. The 2D toy dataset is composed of 100000 points sampled from a 2D Gaussian, $\mathcal{N}(0,1) \times \mathcal{N}(0,1)$ and a set of 5000 novelties sampled from another 2D gaussian, $\mathcal{N}(2.5, 10^{-5}) \times$ $\mathcal{N}(1.4, 10^{-5})$.

In order to show that our method is able to detect non-trivial outliers, we compare the given anomaly score to the associated log-likelihood of each sample in Fig. 1. As expected, the log-likelihood is highly correlated with the distance to the to the nonanomalous gaussian center. Unlike the log-likelihood, our anomaly score is able to overcome this, and grants samples near the anomalous gaussian higher scores.

As a quantitative measurement for comparison to other algorithms, we use the Point-biserial correlation coefficient r_{pb} (Which is mathematically equivalent to the Pearson coefficient for the cases of a continuous and a binary variable). Figures 2 and 3 show r_{pb} as a function of the number of Gaussians in the mixture utilized by our method. Clearly, as this number rises, our method classifies samples from the anomalous gaussian better. We further tested the *k*th-nearest-neighbours (*k*-NN), Isolation Forest (IF), Local Outlier Factor (LOF) and Unsupervised Random Forest (U-RF) algorithms, and report their appropriate correlation coefficient on the toy problems in Table 1.

5.2 SDSS Galaxies

The galaxy spectra were obtained from the publicly available SDSS DR14 (Abolfathi et al., 2017) dataset. We filter samples that do not contain the *Class* = *GALAXY* from the *SpecObj* table. This criterion removes objects that were not classified as galaxies via SDSS spectral fitting pipeline. We take only galaxies for which the rest frame spectrum contains flux values in the wavelength range: $3700\text{\AA} < \lambda < 8000\text{\AA}$. Out of these galaxy objects we select the 150,000 with the highest signal to noise ratio (according to the *SN*-



Figure 1: The distribution of samples in the 1D toy problem. The blue points represent the log-probability of each sample when fitted using 1000 Gaussians in the mixture. The red points represent the 100 highest ranking data points with respect to the log p of the sample. The green points represent the 100 highest ranking data points with respect to our score.



Figure 2: The correlation coefficient, r_{pb} , for the different number of clusters in the GMM for the toy problems in 1D. As the number of gaussians in the mixture increases, and the underlying model overfits the data distribution, the score increases as well. On the other hand, the log-probability's coefficient is mostly uncorrelated and does not depend on the underlying model.

Table 1: The correlation coefficient, r_{pb} , of the 1D and 2D toy problem of various anomaly detection algorithms. U-RF refers to Unsupervised Random Forest. $r_{pb} = 1$, represents the case where the true anomalies are have the highest anomaly scores, while $r_{pb} = -1$ represents the case were the true anomalies are have the lowest anomaly scores. $r_{pb} = 0$ represents the case were the true anomalies have random anomaly scores. The results of our method in this table were produced using a mixture of 100 Gaussians.

Method	Toy Problem 1D	Toy Problem 2D
LOF	-0.0004	-0.0006
<i>k</i> -NN	-0.0140	-0.1517
IF	0.3478	0.3365
U-RF	0.0193	-0.9392
\mathcal{A}_{sc} (ours)	0.9835	0.9684



Figure 3: The correlation coefficient, r_{pb} , for the different number of clusters in the GMM for the toy problems in 2D. As the number of gaussians in the mixture increases, and the underlying model overfits the data distribution, the score increases as well. On the other hand, the log-probability's coefficient is mostly uncorrelated and does not depend on the underlying model.

Median field in the *SpecObj* table). The prominent spectral features are well above the noise for virtually all galaxies in this sample. The data is publicly available, see sdss.org/dr14 for more details. The SDSS module of Astroquery can also be used to obtain the data.

Preprocessing stage consists of removing flux values marked as bad by the SDSS pipeline (i.e., flux values with inverse variance of 0), normalizing the spectra to have a median of one, shifting the spectra to the rest frame, as well as linearly interpolating the spectra to the same wavelength grid.

The objects in the SDSS galaxy spectra are ranked using both our scores, \mathcal{A}_{sc} and $\bar{\mathcal{A}}_{sc}$, using K = 30-200gaussians in the mixture. A visual inspection was performed in order to characterize the top-ranked galaxies in each of the experiments.

The anomaly score, \mathcal{A}_{sc} , orders the objects in large groups of uncommon galaxies. Most of the objects in the top-175 ranked objects by our method are exclusively starburst galaxies, galaxies that are currently undergoing significant star formation. This phenomenon is present in a low fraction of the galaxies, and is associated by the existence of prominent emission lines (emission lines are created by hot gas in the galaxy emitting radiation at specific wavelengths, where locations of the lines are determined by the atomic levels of the atoms composing the gas, and relative strength and profiles of the lines are determined from the kinetic properties and ionization status of the gas). The following 40 objects contain a large fraction of bad spectra (mainly due to sky lines). The next group of galaxies contains two additional populations, one of post-starburst galaxies, galaxies of high recent interest (Goto, 2007, e.g.), and an additional population of galaxies with old stellar population and some Active Galactic Nuclei (AGN) signatures.

Unlike \mathcal{A}_{sc} , the top-ranked objects by normalized anomaly score, $\bar{\mathcal{A}}_{sc}$, are a variety of unique galaxies. Empirically this happens when K > 100. Unfortunately, the set of top-ranked objects in this case is not robust; the group of detected anomalies may vary greatly when using a different K.

A qualitative illustration the top-ranked objects by the two methods together with the the complete distribution is presented on a two-dimensional embedding of the dataset constructed using the UMAP algorithm (McInnes et al., 2018). Table 2 contains some examples of the detected anomalies. The full list of detected anomalies is available online. For completeness, we also present the manifestation of some of the detected anomalies on the galaxy spectra in Figures 5, 6, 7, 8 and 9.

We compared our proposed method to the following approaches: k-Nearest Neighbours, minimum log-probability, Isolation Forest, Unsupervised Random Forest, and PCA reconstruction. The 100 topranked objects' spectra proposed by each of the methods were visually inspected. Only the last three approaches detected a diverse set of objects that were true anomalies, whereas the first two methods detected only an homogeneous set of objects which had no scientific merit. The top-ranked anomalies from each of the methods rarely intersects, see Fig. 10. While all three methods are successful in their designated task, they show a general disagreement as the top-ranked anomalies sets rarely intersect, see Fig. 10. Like our normalized anomaly score, most of the methods are not robust, and produce different candidates for anomalies for different hyperparameters. Examples of the different types of objects found by all of these methods is available in the appendix 6).

6 DISCUSSION

Novelty detection is an essential step in discovering new phenomena in scientific datasets. In astronomy, algorithms designed for this task are in a high demand due to the large amount of information to be collected in upcoming surveys.

Scientific discoveries can come in forms of outliers or slight deviations from a known model. Many approaches succeed in detecting outliers, both in a low- and a high-dimension setting, but fail at the detection of a slight deviation from a known model, even in a simple setting.

Our method is aimed at the detection of these



Figure 4: The top-ranked objects proposed by our method on a 2D projection of the SDSS galaxy spectra dataset constructed using the UMAP algorithm. The top, and bottom left panels show the top-ranked 175, 175-215 and 215-300 objects detected by our method. Most of the objects detected in these panels are clustered together (top left and bottom left panels), or consist of bad spectra (top right panel). See text for details. The bottom right panel contains the 100 top-ranked object detected by our normalized method. The detected objects are no longer concentrated in the same region.

Table 2: Examples of anomalies detected by having a large anomaly score, \bar{A}_{sc} . The spectra of some of these objects are presented in 6. It can be seen that our method is sensitive to a wide variety of unusual phenomena.

#	SDSS name	Comments
1	SDSS J144104.37+532008.7	Triple peaked OIII emission, rare NI λ 6200 emission (double
		peaked).
2	SDSS J052223.70+005916.4	Unidentified broad features and continuum shape.
3	SDSS J134423.00+193755.4	Features from two distinct galaxies at $z_1 = 0.47$ and $z_2 = 0.11$.
4	SDSS J112655.58+004046.9	Double peaked narrow emission lines.
5	SDSS J150908.75+090220.9	Emission lines with significant red wing.
6	SDSS J084715.85+315510.8	Post starburst galaxy with an active galacit nuclei.
7	SDSS J105918.12+243234.7	Velocity offset between emission and absorption lines.
8	SDSS J115023.57+281907.4	$z \sim 2$ quasar mis-classified by the SDSS.
9	SDSS J095153.06+010605.8	Type Ia supernova.

slight deviations. It exploits known information metrics over an estimated probability distribution and can be simply generalized to cases that contain a set of completely different phenomenons. We give an empirical motivation for this approach using the toy problems which emphasize its underlying mechanics. The true highlight of the method is the ability to extract a rare set of objects from the SDSS galaxy dataset.

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Figure 5: Spectrum of SDSS J144104.37+532008. We show the region of the spectrum containing the H_{β} and O III lines. The O III shows a triple peaked structure. This is the only example of such structure we encountered. The extremely rare N I λ 6200Å line is also present in the spectrum, and is either double peaked or has a blueshifted wing (a wing refers to a non symmetrical line profile).



Figure 6: Spectrum of SDSS J095153.06+010605.8. The spectral features of a type Ia supernova (namely broad absorption lines in specific locations) are clearly seen in this spectrum. Indeed this object was also found by Graur and Maoz (2013) in a dedicated search for type Ia supernova.

knowledges support and resources from the Center for High-Performance Computing at the University of Utah. The SDSS web site is www.sdss.org.

SDSS-IV is managed by the Astrophysical Research Consortium for the Participating Institutions of the SDSS Collaboration including the Brazilian Participation Group, the Carnegie Institution for Science, Carnegie Mellon University, the Chilean Participation Group, the French Participation Group, Harvard-Smithsonian Center for Astrophysics, Instituto de Astrofísica de Canarias, The Johns Hopkins University, Kavli Institute for the Physics and Mathematics of the Universe (IPMU) / University of Tokyo, the Korean Participation Group, Lawrence Berkeley National Laboratory, Leibniz Institut für Astrophysik Potsdam (AIP), Max-Planck-Institut für Astronomie (MPIA Heidelberg), Max-Planck-Institut für Astro-



Figure 7: Spectrum of SDSS J134423.00+193755.4. The spectrum of a galaxy is shifted in wavelength according to the relative velocity between us and the galaxy. This shift is called redshift and marked with z. This spectrum shows features coming an alignment of two different galaxies along the line of sight, one at redshift of z = 0.11 (spectral features colored in red) and the other at redshift of z = 0.47 (spectral features colored in blue). The blue spectral features from left to right are most likely O II H_β and the two O III emission lines, with the rest wavelength of $\lambda 3727\text{Å}$, $\lambda 4686\text{\AA}$, $\lambda 4960\text{\AA}$, and $\lambda 5007\text{\AA}$, respectively. The spectrum is shown in the rest frame of the z = 0.11 galaxy.



Figure 8: Spectrum of SDSS J115023.57+281907.4. This is an example of a mis-classified object: This object is a high redshift quasar mistakenly classified as a galaxy by the SDSS pipeline. That is, this object should not have been included in the SDSS galaxy dataset. The most prominent line in this spectrum is the Ly_{\alpha} λ 1206Å mis-classified as an emission line at ~ λ 5000Å.

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Figure 10: The 100 top-ranked objects proposed by different anomaly detection methods on a 2D projection of SDSS galaxy spectra dataset constructed using the UMAP algorithm. Different populations of galaxies reside in different regions of this embedding. A visual inspection of all the proposed objects has revealed a high fraction of true anomalies. This plot shows that different methods can be sensitive to different populations of galaxies. Note how one method can have a high concentration of detected anomalies in a specific region, while another method can have zero detections in the same region. From our experiments it appears that the difference between results obtained by a single method with different hyper parameters is similar to the difference between completely different methods.



Figure 9: Spectrum of SDSS J150908.75+090220. The unusual phenomena observed in this spectra are the redshifted wings present in all emission lines. Unlike the redshifted wings, blueshifted wings usually represent outflowing material. This is material that is moving towards the observer. Redshifted wings are harder to explain, and further investigation is required to determine their source. This is an example of the strongest redshifted wings we detected.

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APPENDIX

DSS Galaxies Anomalies

This section contains examples of the anomalies detected in the SDSS galaxy dataset by the Isolation Forest, Unsupervised Random Forest, and PCA reconstruction. These three methods were able to detect diverse types of true anomalies, similarly to our Fisher Vector based method. Examples of anomalies detected by isolation forest are shown in Table 3, Table 3: Examples of anomalies detected with the Isolation Forest algorithm. About 15 of the top 100 anomalies detected by this method were chance alignments.

#	SDSS name	Comments
1	SDSS J001850.89-102236.6	NI λ 6200 emission, unique continuum shape.
2	SDSS J153904.33+114241.6	Chance alignment with M-dwarf.
3	SDSS J052223.70+005916.4	Very unusual continuum.
4	SDSS J031248.68-010020.6	Broad unidentified features.
5	SDSS J113219.79+255012.9	Zig-zag continuum (most likely bad spectra).
6	SDSS J113219.79+255012.9	Features from two distinct redshifts.
7	SDSS J105918.12+243234.7	N I λ 6200 emission with blueshifted wing.
8	SDSS J013404.10+095703.3	Strong, blueshifted Na I λ 5895, 5889 doublet absorption.

Table 4: Examples of anomalies detected using PCA-reconstruction. 6 additional high redshift quasars are included in the top 100 anomalies detected by this method.

#	SDSS name	Comments
1	SDSS J235047.12+143617.5	Sodium absorption blueshifted by 850 $[km/s]$, ionized outflows.
2	SDSS J022113.54-030539.6	high redshift quasar (mis-classified).
3	SDSS J095153.06+010605.8	Type Ia supernova.

Table 5: Examples of anomalies detected with the Unsupervised Random Forest algorithm.

#	SDSS name	Comments
1	SDSS J164732.08+220456.5	Unique continuum shape.
2	SDSS J115023.57+281907.4	High redshift quasar (mis-classified).
3	SDSS J154024.75+325157.2	Type Ia supernova.
4	SDSS J120432.29+220400.7	Two galaxies chance alignment.
5	SDSS J115927.68+485858.8	Multiple component emission, absorption lines redshifted from
		systematic.

anomalies detected by PCA reconstruction are shown in Table 4, and anomalies detected by Random Forest are shown in Table 5.