A Novel Cuff-Less and Calibration-Free Blood Pressure Estimation Framework Using Single Photoplethysmogram

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Abstract: Blood pressure (BP) is one of the four main vital signs and is a key indicator of cardiovascular health. However, monitoring of BP is not regularly done in most of the population until health problems arise. Continuous and convenient monitoring of blood pressure is thus needed to address this issue. We propose a novel BP estimation algorithm *without* calibration to estimate BP from a cuff-less photoplethysmogram (PPG) system. Data from a total of 219 subjects, which underwent only simple preprocessing steps, was used to train and evaluate a hybrid Convolutional Long Short-Term Memory Neural Network (CNN-LSTM) model. The model was trained using the preprocessed PPG signal as the only input. The model had two neurons in the last layer to output systolic blood pressure (SBP) and diastolic blood pressure (DBP) values. The model was optimized by conducting a random search on its hyperparameters for better performance. The model resulted in a comparable performance to those in the literature, with mean absolute errors (MAEs) of 14.13 mmHg and 8.80 mmHg for SBP and DBP, respectively. To assess generalizability, we also tested the trained model on a second dataset collected from 20 subjects using a custom wearable system, which was again resulted in MAEs of 10.71 mmHg and 10.09 mmHg, respectively. Overall, our results show that such a pipeline could potentially be leveraged in the design of wearable systems to achieve cuff-less and calibration-free BP monitoring in ambulatory settings.

1 INTRODUCTION

Blood pressure (BP) is one of the four main vital signs along with pulse rate, respiration rate, and temperature, serving as a critical parameter in assessing cardiovascular health (Sapra et al., 2020). Accurate evaluation of BP levels contributes substantially to the early detection and management of hypertension. Hypertension is a major cause of premature death around the world and is a major risk factor for conditions and diseases such as stroke, heart failure, and kidney disease. Only 42% of adults with hypertension are properly diagnosed and treated (Lackland and Weber, 2015). Continuous blood pressure monitoring systems hold the potential to facilitate timely disease detection and intervention, facilitate the formulation of individualized therapeutic regimens, and afford proactive and preemptive healthcare strategies for individuals susceptible to ailments resulting from abnormal blood pressure (Sana et al., 2020).

BP monitoring methods can be classified into two groups: non-invasive and invasive. The gold standard

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for non-invasive blood pressure monitoring involves using the auscultatory technique (Korotkoff sounds) through oscillometric sphygmomanometers and cuffs (MHRA, 2019). This method provides accurate but intermittent readings of BP (Mukherjee et al., 2018). Invasive methods require the cannulation of an artery with a stiff catheter to insert a transducer for BP measurement. This method provides continuous and significantly accurate BP readings; however, it is not preferred unless necessary due to potential harm and high levels of discomfort to the patient. Other BP measurement methods include ultrasound sensing, volume clamping, tactile sensing, pulse transit time (PTT)-based measurement, and photophletysmography (PPG)-based measurement (Mukherjee et al., 2018).

Among all the methods, PPG-based BP measurement is the most promising method for daily, continuous BP monitoring due to its low cost, accessibility, unobtrusive nature, and easy integration into wearable devices such as smartwatches. The PPG signal is a result of the variance in the amount of light absorbed in the arteries due to the changes in arterial blood vol-

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ume during the cardiac cycle. Its working principle is based on optical detection, consisting of a light source and a photosensor. Depending on the working mode of the photosensor, a PPG signal is generated by measuring either the reflected or transmitted light from the relevant region. In the literature, PPG signals have been analyzed to provide crucial information regarding vascular resistance, blood oxygen level, and blood pressure (cheol Jeong et al., 2018).

Studies involving PPG developed different techniques to analyze the signal to estimate blood pressure. Pulse arrival time (PAT)- and PTT-based blood pressure calculations are among the most common methods to estimate the blood pressure from PPG signals since there is an established relationship between the two (Kim et al., 2015). Other commonly used techniques involve extracting several frequency and time domain features and using machine learning algorithms to estimate the blood pressure (Maqsood et al., 2021). Most work in the domain also requires personal calibration over short time intervals, which would necessitate access to information about the subject beforehand, which might not always be available (Elgendi et al., 2019). For PAT- and PTTbased estimation methods, the requirement to use two synchronized sensors to accurately measure these features is their biggest disadvantage. For methods that involve manual feature extraction, a careful and timeconsuming analysis of the signals is required. Additionally, it is difficult to standardize the steps in feature extraction procedures. On the other hand, deep learning-based methods can have feature extraction capabilities embedded in their architecture. They are supposed to generalize over the dataset they are trained on, but training them requires a substantial amount of data. The availability of numerous databases with PPG and BP measurements trivializes this problem.

Considering the points above, we propose a deep learning-based regression model for BP estimation using a single PPG measurement. Although methods to estimate or measure BP from certain physiological markers exist, a vast majority of them require multiple sensor modalities, bulky and inconvenient measurement devices, or exhaustive signal analysis. This work aims to develop a novel, robust, and convenient estimation of BP from a single PPG signal without the use of a cuff or any kind of personal calibration procedure. Our main contributions are that we demonstrate a novel approach to BP estimation, utilizing a Convolutional Long Short-Term Memory Neural Network (CNN-LSTM) hybrid architecture to estimate BP directly from filtered PPG signals with no personal calibration procedure. The proposed model is also sufficiently lightweight and can easily be trained on commercial PCs with a GPU.

This paper is organized as follows: The dataset, the general structure of the preprocessing steps, and selection and evaluation methods of our proposed algorithm are described in Section 2. Section 3 presents a comparative evaluation of our algorithm's performance. Concluding remarks have been presented in Section 4.

2 METHODS

2.1 Dataset

This study primarily uses the PPG-BP dataset published by Liang et al. (Liang et al., 2022) for training and validation. The dataset consists of 657 recordings from 219 subjects. Each subject first had their arterial blood pressure measured using the Omron HEM-7201 (Omron Company, Kyoto, Japan) followed by three, 2.1-second-long PPG recordings in the span of three minutes. The PPG recording quality was evaluated by the authors of the dataset using a skewness signal quality index.

2.2 Preprocessing

The raw PPG values from the dataset had high frequency noise contaminating the signal. Low frequency baseline wander was also present in the recordings. Therefore, we conducted a filtering operation before using the dataset to train our BP estimation algorithm. A 4th order Butterworth filter was used with cut-offs at 0.4 Hz and 20 Hz. The resulting clean signal is shown in Figure 1. In the literature, it has been shown that the PPG signal can be adequately analyzed within these frequency ranges (Reali et al., 2022).

Also, deep learning algorithms greatly benefit from normalization. We normalized the data to limit the scale and reduce the variance according to the equation below, where μ is the mean and σ is the standard deviation (Equation 1).

$$x_{normalized} = \frac{x - \mu}{\sigma} \tag{1}$$

2.3 Machine Learning Algorithms

 CNNs and their application over 1D data is not an unexplored topic. However, due to the popularity and success of 2D CNNs, conventionally, 1D data is transformed into 2D graphs (such as



Figure 1: PPG signal after preprocessing.





spectrograms) for analysis. Recently, the use of 1D CNNs for 1D data has become more common in the literature. This is in part due to 1D CNNs requiring less computational complexity and memory, making them a suitable candidate to use for lightweight, real-time applications without requiring specialized hardware. They are also easier to train than 2D CNNs, often requiring a smaller dataset. They have been used in timeseries data analysis such as speech recognition, ECG monitoring, and stock value forecasting (Kiranyaz et al., 2021).

- 2. LSTMs are proposed as a solution to the exploding/vanishing gradient problem of Recurrent Neural Networks (RNNs). Its ability to remember longer dependencies is a result of its recurrently connected memory blocks that regulate the flow of information via non-linear gating units. For this reason, it's a popular choice for handling time series data (Van Houdt et al., 2020).
- 3. CNN-LSTM hybrid models take advantage of both architectures. CNNs provide LSTMs with extracted features with a reduced dimensionality that adequately represents the input, while LSTMs capture temporal dependencies over long sequences. The hybrid architecture consistently outperformed conventional unmixed CNN and LSTM architectures (Van Houdt et al., 2020). In the literature, the hybrid model has been used for

classification of plant growth status (Xing et al., 2023), forecasting of photovoltaic power production, emotion identification, etc. (Van Houdt et al., 2020; Agga et al., 2022). Bao et al. have successfully demonstrated that a hybrid model can successfully estimate wrist angles from electromyogram (EMG) signals (Bao et al., 2020). They compared their hybrid model with support vector regression (SVR), Random Forest, CNNs, and LSTMs. Their hybrid model outperformed all other models in all trials and protocols.

We propose a CNN-LSTM hybrid network to solve the BP estimation problem. LSTMs and CNNs are highly popular deep learning techniques and have a variety of use cases ranging from natural language processing to image processing. LSTMs' ability to capture dependencies in long temporal sequences makes them a good match for time series estimation applications. CNNs can extract learned features from the raw data. In theory, a hybrid model consisting of both should be able to extract the local features of a signal and capture the long-term dependencies.

2.4 Hyperparameter Selection

The general structure of the model is presented in Figure 2. To tune the hyperparameters for our model, we conducted a random search on the hyperparameters in Table 1, training 100 different models over 30 epochs

Hyperparameters	Hyperparameter Values
1D CNN Layers	1, 3
1D CNN Filters	16, 32, 64
1D CNN Kernel Sizes	5, 15, 63
Lstm Layers	1, 3, 5
Lstm Units	32, 64, 128
Dense Layers	0, 1, 3
Dense Units	16, 64, 128

Table 1: List of selectable hyperparameters.

Hyperparameters	Hyperparameter Values		
1D CNN Layers	3		
1D CNN Filters	Layer 1: 16		
	Layer 2: 32		
	Layer 3: 64		
1D CNN Kernel Sizes	Layer 1: 63		
	Layer 2: 15		
	Layer 3: 15		
Lstm Layers	5		
	Layer 1: 128		
	Layer 2: 128		
Lstm Units	Layer 3: 32		
	Layer 4: 64		
	Layer 5: 128		
Dense Layers	0		
Dense Units			

Table 2: Hyperparameter selection results.

on the dataset.

The resulting architecture with the smallest validation root mean square error was selected as the candidate to be further trained on the dataset. The random search yielded the parameters in Table 2 for the model.

We have two neurons as the last layer of our architecture to output systolic blood pressure (SBP) and diastolic blood pressure (DBP) values.

2.5 Model Evaluation

For a more reliable estimation of our model's performance, we used 10-fold cross-validation. The metrics used to evaluate the algorithm's performance are presented below, where y is the ground truth, x is the prediction, and n is the number of samples.

1. Mean Absolute Error (MAE): The mean of absolute errors (Equation 2).

$$MAE = \frac{1}{n} \sum_{i=1}^{n} |y_i - x_i|$$
(2)

2. Root Mean Square Error (RMSE): The standard deviation of prediction errors. It measures how

spread the residuals are (Equation 3).

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (y_i - x_i)^2}$$
(3)

3. Mean Absolute Error Percentage (MAPE): The percentage mean of absolute errors (Equation 4).

$$MAPE = \frac{1}{n} \sum_{i=1}^{n} |\frac{y_i - x_i}{y_i}|$$
(4)

We used MSE (square of RMSE) to monitor the prediction success of the algorithm during training.

2.6 Experiments to Assess Generalizability

To assess generalizability, we also tested the trained model on the dataset we collected from 20 subjects using a custom wearable system. Data collection was conducted upon approval by the Koc University Institutional Review Board, and all participants provided written consent. Subject demographics were as follows: 8 females and 12 males, Age: 23.8 ± 4.2 , Height: 172.6 ± 9.5 cm, Weight: 70.9 ± 16.1 kg.

Before the experimental protocol, the subjects' SBP and DBP were measured using Omron M2 device. Following that, the subjects were asked to stand still for two minutes while their PPG signals were being collected from their wrist area using a MAX30102 sensor at 50 Hz. The IR signal was pre-processed in a similar manner (detailed in Section 2.2) and used as the test data for the pretrained CNN-LSTM model.

3 RESULTS AND DISCUSSION

In this work, we focused on BP estimation from raw PPG signals without using handcrafted features. Only the filtered PPG recording was fed to the CNN-LSTM hybrid model. Most works in the literature propose a calibration method to improve their results. Slapnivcar et al. used 20% of the test subjects to train their network for personalization (Slapničar et al., 2019). Their MAE improved as much as 5.98 mmHg and 5.5 mmHg, respectively, for their best-performing algorithm. In another work, Xing et al. compared their calibration-free algorithm with the same algorithm with a calibration factor (Xing et al., 2019). Their calibration factor was the median of a person's previous fitting errors. Their calibration factor improved their estimation results by 2.0±4.1 mmHg for SBP, 2.2 \pm 0.5 mmHg for DPB in the young (\leq 50 yo), and 5.5±4.3 mmHg for SBP, 2.4±2.1 mmHg for DPB in



Figure 4: DBP Trend.

the old (>50 yo) population. They argue that the calibration process reduced biases. However, we find this a bit counterintuitive since the population size for the older population was higher than the younger population by 81%. In fact, the estimations should have been more biased towards the older population when the calibration-free algorithm was used; however, this was not the case. Depending on how the calibration is made, calibrations might introduce even more biases to compensate for the errors. Considering the previous point and how personal calibration requires subject-specific information that might not always be available, we decided to go with a calibration-free method in designing our algorithm.

3.1 Model Evaluation Results

We selected two papers using the same dataset as ours; therefore, the evaluation criteria that would normally be dependent on data distribution to draw conclusions, such as MAE, makes sense. Although most BP datasets have a similar range, depending on the subject demographics, the difference in the distribution of BP can be significant enough to skew conclusions drawn from different datasets. Our motivation was to prevent such an occasion from occurring. Table 3 lists some of the best algorithms belonging to the two papers that used the same dataset as ours. Among them, only ours and (González et al., 2023)'s ResNet approach don't use any feature extrac-



Figure 5: SBP Error Histogram.



Figure 6: DBP Error Histogram.

tion prior to training. Our approach and (González et al., 2023)'s ResNet approach show very similar performances, with ours having better mean errors but slightly worse standard deviations. The rest of the machine learning approaches that utilize some kind of feature extraction method prior to training have better results in general. This might be due to deep learningbased approaches requiring a larger dataset to better understand the relationship between the input and output.

Figures 3 - 4 show trends in four folds of the test data. The figures show that our algorithm can properly encapsulate the upward and downward movements in the blood pressure. The data was smoothed with a moving average filter (n = 30) to make the trend clearer in the visualization.

Figures 5 - 6 visualize the histograms of residual errors. The error histograms indicate that the errors are normally distributed around 0. The error histogram of SBP has a higher range. This is because SBP has a higher variance as a result of its larger magnitude in comparison to DBP.

3.2 Experiments to Assess Generalizability

As detailed in Section 2.6, we also tested the trained model on the IR PPG signals we collected from 20 subjects. For the SBP measurements, the MAE and MAPE were calculated to be 10.71 mmHg and 9.45%,

Model	Performance Criteria	Systolic BP	Diastolic BP
RelieF GPR (w/o opt.)	MAE (mmHg)	10.08	7.87
	RMSE (mmHg)	14.80	9.83
	ME+STD (mmHg)	-	-
	MAPE (%)	-	-
CFS GPR (w/o opt.)	MAE	11.91	7.64
	RMSE	16.05	9.16
	ME+STD	-	-
	MAPE	-	-
RelieF GPR (w opt.)	MAE	3.02	1.74
	RMSE	6.74	3.59
	ME+STD	-	-
	MAPE	-	-
LightBGM	MAE	13.06	8.16
	RMSE	-	-
	ME+STD	0.00±16.95	-0.04±10.30
	MAPE	-	-
AdaBoost	MAE	13.22	8.04
	RMSE	-	-
	ME+STD	-0.56±16.95	-0.16±10.25
	MAPE	-	-
	MAE	13.62	8.61
DecNet	RMSE	-	-
ResNet	ME+STD	-1.85±17.45	-2.17±10.81
	MAPE	-	-
Ours	MAE	14.13	8.80
	RMSE	18.13	10.96
	ME+STD	0.71±18.23	-0.79±11.08
	MAPE	11.24%	12.54%

Table 3: Comparison of model performance.

respectively. For the DBP measurements, the MAE and MAPE were 10.09 mmHg and 12.02%, respectively. Obtaining high performance from a different test dataset justified that our pipeline was indeed generalizable regardless of the instrumentation used.

4 CONCLUSION

In this study, we proposed and implemented a calibration-free BP estimation algorithm and demonstrated that it is possible to estimate SBP and DBP from a single PPG without manual feature extraction. The preprocessing steps to prepare the data for training were discussed. The general structure of the proposed CNN-LSTM model and its hyperparameters were described in detail. The performance of the model was evaluated with the metrics indicated in Section 2.5 and compared to similar works in the literature.

Different from the other works, our algorithm does not rely on multiple sensor modalities, nor does

it rely on personal calibration to estimate the BP. Our CNN-LSTM hybrid model is also a novel approach to BP estimation. An advantage of our model is that it is sufficiently lightweight to run on commercial old GPUs such as GTX1070. It completes a 10-fold cross-validation under 10 minutes on the full dataset, and only takes seconds to predict BP given the data.

Single PPG, cuff-less BP monitoring is cheap, accessible, and user-friendly. In the near future, it might be possible to integrate algorithms of this kind into smartwatches or other wearables. Similar to how a fingertip pulse oximeter is able to measure blood oxygen levels, devices of the same kind might be able to provide BP readings. This way, BP-related risk factors could be detected and serve to prevent or diagnose certain conditions and diseases in the general populace, increasing quality of life.

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