# **Retinoblastoma Detection: Leveraging Deep Learning and Residual** Connections for Enhanced Diagnostic Accuracy

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- Keywords: Artificial Intelligence, Convolutional Neural Network, Deep Learning, Deep Neural Networks, Image Classification, Machine Learning, Retinoblastoma.
- Abstract: Retinoblastoma is a rare cancer of the eye that affects children and can be deadly if not diagnosed in time. Detecting this disease early improves the likelihood of curative treatment and makes it possible to preserve the child's vision. Meanwhile, the application of deep learning techniques to pathology holds the promise of revolutionizing cancer detection and treatment early. When it comes to retinoblastoma, the prospect of automating diagnostic processes to work more accurately and efficiently than healthcare workers can detect dangerous cases with better-than-average accuracy should improve survival rates, as well as rates of vision conservation. In this study, we evaluated several convolutional neural network models: MobileNetV2, EfficientNetB0, ResNet101, DenseNet121, VGG16, and an ensemble model providing a quantitive comparison of which of the models performs best. Among the models, the one that performed best and most accurately was ResNet101, which achieved an accuracy of 97.42%(top-1 accuracy). Comparatively, EfficientNetB0 had a lower metric that indicated its accuracy was 53.40% (top-1 accuracy). ResNet101's relatively high accuracy for this study suggests that this model is better suited for this type of feature-based classification problem compared to the other models. Residual connection blocks allow layers in a deep neural network to learn to map the input to the same output. This improves performance and reduces errors. Residual networks (ResNets) with many layers have now become the standard architecture used in the leading vision challenges, which gives more insight to researchers and practitioners in choosing the most suitable diagnostic model.

# **1 INTRODUCTION**

Retinoblastoma is an eye cancer that almost exclusively affects very young children and is usually diagnosed prior to the age of five. While it is a rare form of cancer, it is aggressive in nature; left untreated, it can spread to other parts of the eye and the body. While early detection is vitally important, it is not easily accomplished, especially considering that the disease almost exclusively affects very young children who cannot easily communicate. Current imaging techniques used in the detection of retinoblastoma, such as ultrasounds or MRIs, have limited effectiveness. However, molecular "liquid" tests that look for genes associated with retinoblastoma might hold more promise. Though the current methods of achieving these elusive tests are not very practical, more affordable, and more accessible methods are under development.

In recent years, the integration of computer vi-

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sion and deep learning technologies has ushered in a promising era of retinoblastoma detection. These technologies have the potential to reduce mortality from retinoblastoma, which could lead to improved health outcomes for people in low- and middleincome countries. Additionally, this technology could help reduce the need for costly and time-consuming manual analysis.

In recent years, the integration of computer vision and deep learning technologies has opened up a new era for retinoblastoma detection. These technologies hold immense promise for reducing mortality from retinoblastoma—a rare but deadly eye cancer that predominantly strikes infants and children—by providing timely, accurate, and cost-effective diagnoses. Moreover, they could significantly lessen our reliance on manual analysis, which is not only laborintensive but also prone to error.

In this era of artificial intelligence, several deep learning models have been developed to detect retinoblastoma visually. The architectures of these

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Retinoblastoma Detection: Leveraging Deep Learning and Residual Connections for Enhanced Diagnostic Accuracy. DOI: 10.5220/0013099000003911 Paper published under CC license (CC BY-NC-ND 4.0) In Proceedings of the 18th International Joint Conference on Biomedical Engineering Systems and Technologies (BIOSTEC 2025) - Volume 1, pages 269-279 ISBN: 978-989-758-731-3; ISSN: 2184-4305 Proceedings Copyright © 2025 by SCITEPRESS – Science and Technology Publications, Lda. models have varied, but all of them have achieved high rates of accuracy and precision. When compared to conventional human ocularpathologic analysis, the models are also cheaper and more efficient. The architectures of the deep learning models used in the current study include (DSandler et al., 2018), EfficientNetB0 (Tan and Le, 2019), ResNet101 (He et al., 2016), DenseNet121 (Huang et al., 2017), VGG16 (Simonyan and Zisserman, 2014) and the Ensemble model (Dietterich, 2000).

Models were trained and assessed on a public dataset <sup>1</sup> to determine and compare their estimations of accuracy for pixel-level segmentation tasks on Retinoblastoma. The experiments and evaluations conducted reveal the relative strengths and weaknesses of various learning architectures when applied to the task of classifying Retinoblastoma. The outcomes of this extensive study allow us to understand the most suitable Convolutional Neural Network (CNN) backbone that can be used to propose a innovative architecture that provide an optimal performance in terms of accuracy and efficiency for use in automated intelligent systems tasked with diagnosing Retinoblastoma.

### 2 RELATED WORK

The literature features a number of deep learning models for detecting and classifying retinoblastoma. Earlier work by (Durai et al., 2021) presents an approach to not just diagnosing retinoblastoma but diagnosing it earlier than previous models-this is an important focus since retinoblastoma is a rapidly progressing cancer that can develop within months and most often does so in very young children. Durai's work emphasizes using deep learning for image analysis; they discuss using a CNN model along with preliminary work in using a more traditional image processing approach. The overall work is more of a step in the right direction toward employing automated systems for diagnosing retinoblastoma but unfortunately does not feature results based on clinical tests

A method for improving the accuracy of retinoblastoma diagnoses has been developed by (Duraivenkatesh et al., 2023). This method, intended for use by healthcare professionals, integrates several sophisticated artificial intelligence (AI) technologies, including image processing, and is based on the use of fundus photography for identifying retinoblastoma. The researchers claim that their work could lead to

<sup>1</sup>The dataset is available at: https://github.com/ norton-chris/Retinoblastoma\_detector\_SVM/tree/master significantly improved identification of the disease in its early stages. An international group of researchers, led by (Kaliki et al., 2023), has also applied AI to the problem of detecting retinoblastoma. In their study, they focused on intraocular retinoblastoma and similarly used fundus images for much of their analyses. Kaliki and colleagues also assert that their work could enhance the speed and accuracy of retinoblastoma diagnoses.

Zhang and colleagues (Zhang et al., 2023) developed a deep learning algorithm called the Deep Learning Assistant for Retinoblastoma (DLA-RB). This algorithm identifies active retinoblastoma tumors with a high level of sensitivity and accuracy. The cost of the DLA-RB is far lower than conventional electronic tools. Thus, the DLA-RB is an effective tool for both diagnosis and surveillance, especially in places where resources are limited. The approach taken by Zhang et al. to arrive at the DLA-RB was straightforward. The researchers achieved an extraordinary level of performance without employing overly complicated methods. Still, this work only allows active retinoblastoma tumors to be detected, which is necessary for initial encounters in retinoblastoma diagnosis and for routine follow-up. Using explainable AI techniques, Aaldughayfiq and colleagues (Aldughayfiq et al., 2023) propose an innovative method to detect retinoblastoma. Instead of the usual candidates for explainability, such as LIME and SHAP, they use the InceptionV3 architecture as the foundation for their model. They then finetune the model on a dataset that contains images of retinoblastoma and non-retinoblastoma cases. By doing so, they not only classify the images as either of the two types but also make the process interpretable. They argue that this is essential if the people who read the images are to trust the model and its results.

Advances in automated eye cancer detection using machine learning and image analysis are bringing dramatic shifts to the healthcare field. Mistry and Ramakrishnan (Mistry and Ramakrishnan, 2023) describe how these powerful technologies have the potential to revolutionize eye cancer detection and, with further development, could become life-saving tools. Eye cancer, while rare, can progress rapidly. Automated detection utilizing the latest technologies may prove to be a more efficient and effective method of diagnosis. These technologies can accurately identify ocular tumors at early stages, improving diagnosis and treatment outcomes. The integration of machine learning in medical imaging not only enhances precision but also reduces the burden on healthcare professionals, Recently, (Pol et al., 2024) have concentrated on developing automatic segmentation methods for detecting retinoblastoma in optical coherence tomography (OCT) images. Their proposed methodology accurately employs machine learning to delineate the tumor in the complex 3D structure of the eye and to perform the early diagnosis necessary to carry out effective treatment planning. By automating the segmentation process, the technology significantly reduces the time and effort required from medical professionals, ensuring more consistent and precise results. (Shanthini et al., 2024) proposed a novel approach of detecting eye cancer that uses CNNs. Their work is notable for combining the image analysis power of these CNNs with an advanced optimization algorithm called the Sine Cosine Fitness Gray Wolf Optimizer. The study demonstrates that this integrated approach can significantly enhance diagnostic accuracy, offering a promising tool for early detection and treatment of eye cancer, while also emphasizing the importance of further research to refine and validate the system.

# 3 RETINOBLASTOMA SYMPTOMS-BASED IMAGE

Retinoblastoma is a rare kind of eye cancer that primarily targets infants and young children. When it strikes, it normally presents with a number of symptoms that can be readily detected through imaging. The most common sign is usually leukocoria, an abnormal white reflection from the retina that can be seen under direct examination or in photographs. This is sometimes called a "cat's eye reflex" because of how it looks-the way a cat's eyes might look at night, under certain conditions. Other signs and symptoms may include strabismus (which affects the alignment and positioning of the eyes, making it appear that one or both eyes are "crossed"), swelling, redness, and poor vision in the eye that has the tumor. Advanced imaging techniques, such as ultrasound, MRI, and fundus photography, play a crucial role in diagnosing and assessing the extent of retinoblastoma, enabling timely and effective treatment (Shields and Shields, 2004). Figure 1 illustrates the difference between healthy and unhealthy eyes with Retinoblastoma.

### 4 METHODS

## 4.1 Dataset Used in Evaluation of Methods

We compiled a comprehensive dataset of images consisting of both normal eyes and eyes affected by retinoblastoma. The dataset was carefully curated to include a wide range of cases, ensuring a diverse representation of the condition and its variations. This diversity is crucial for training models that can generalize well to unseen data. The dataset was divided into two subsets: a training set (80%) and a testing set (20%). The training set is used to train the transferlearning models, enabling them to learn patterns and features that differentiate normal eyes from those with retinoblastoma. The testing set, on the other hand, is kept separate during training and is used to evaluate the performance of the trained models on unseen data, thereby measuring their generalizability. A visual sample from this dataset is shown in Figure 2, illustrating the variety of images included and how they are prepared for analysis. This dataset forms the foundation for our transfer-learning experiments, providing both the diversity and quality necessary for robust model development.

#### 4.1.1 Data Preprocessing and Augmentation

The study initially started with a total of 100 images, consisting of 50 images of normal eyes and 50 images of eyes affected by retinoblastoma. This provides a balanced dataset before augmentation, with an equal proportion of true positive (retinoblastoma) and true negative (normal) images. Before augmentation, the dataset was evenly balanced: True positive images (retinoblastoma): 50% and True negative images (normal): 50%. After applying augmentation techniques, the dataset was expanded to a total of 2,132 images. This significant increase was achieved through transformations such as rotation, resizing, and flipping, among other techniques. Since the original dataset was balanced (50 normal and 50 retinoblastoma images), and assuming that augmentation techniques were applied equally to both classes.

To increase the size of our dataset, we utilized a popular deep learning library called Keras, which was developed by François Chollet and is now maintained by Google, named mageDataGenerator (Chollet et al., 2015). Keras is often integrated with TensorFlow, Google's premier deep learning framework, and both are popular among industrial practitioners and academic researchers.These augmentations help prevent overfitting by exposing the model to a wider range of



Figure 1: Difference between healthy and unhealthy eyes affected by retinoblastoma where red box indicate leukocoria abnormal white reflection on unhealthy eye.



Figure 2: Different samples from dataset that have been used to evaluate the models where: (a)-(c) show healthy eyes, and (d)-(f) show unhealthy retinoblastoma eyes with white reflection.

scenarios, thereby improving its generalization capabilities. Additionally, ImageDataGenerator supports scaling pixel values and normalizing data, which are essential preprocessing steps for many models.

The balanced dataset (50% normal and 50% retinoblastoma) ensures fair training and evaluation without class bias. Expanding the dataset from 100 to 2,132 images through augmentation prevents overfitting, improves robustness, and supports better generalization. Maintaining class proportions during augmentation avoids issues with class imbalance that could skew performance metrics.

Moreover, we resize the image to  $64 \times 64$  pixels. This is due to the specific input dimensions of the deep learning models that we are going to use. A steady feed of photos into the model is ensured through resizing.

## 4.2 Deep Learning Models for Classification

A total of six deep learning models are trained in this paper for classification purposes. These models are:

#### 4.2.1 MobileNetV2

The convolutional neural network architecture MobileNetV2 (DSandler et al., 2018) is designed for efficient mobile and embedded vision applications. This architecture is an improvement over its predecessor, MobileNetV1, and it introduces inverted residual structures with linear bottlenecks to enhance performance while reducing computational and memory costs. Compared with not only MobileNetV1 but also some state-of-the-art image classification models, MobileNetV2 achieves a more effective balance between high accuracy and low latency, making it an outstanding candidate for on-device image recognition tasks.

The two main innovations in MobileNetV2 are inverted residual structures and linear bottlenecks. These not only enhance the performance of the deep learning models when they are deployed on mobile devices and edge devices but also improve their efficiency. The way that they improve the performance is by allowing the models to learn in a more effective manner with better gradient flow, and the way they increase the efficiency is by saving memory and computational resources compared to MobileNetV1 and similar architectures. These ideas together enable MobileNetV2 to deliver high accuracy and, at the same time, require much less computing power when both models are deployed on the same device.

#### 4.2.2 EfficientNetB0

The deep learning model EfficientNetB0 (Tan and Le, 2019) introduces a new method for scaling that is called compound scaling. This method uniformly scales the network's depth, width, and resolution to improve performance while maintaining efficiency. Compared to previous architectures, models in the EfficientNet family, which includes EfficientNetB0, achieve a state-of-the-art level of accuracy on image classification tasks while using significantly fewer parameters and much less computational power.

To conclude, the scaling of EfficientNetB0 provides a more comprehensive, effective, and efficient means of scaling CNNs compared to traditional methods like depth, width, or resolution scaling. The scaling of CompoundNet is better in many aspects: It is much more efficient. It avoids the imbalance of width and depth that leads to excessive computation and unfeasible models. It can be easily adapted to different resource constraints, which makes it versatile. And it leads to much better results in a top-1 accuracy with much fewer parameters.

#### 4.2.3 ResNet101

He et al.'s ResNet101 (He et al., 2016), a deep convolutional neural network, is part of the Residual Network (ResNet) family designed to tackle the vanishing gradient problem in exceedingly deep networks. Composed of 101 layers, ResNet101 employs residual learning through shortcut connections that allow the network to bypass one or more layers, which, in effect, lets it learn identity mappings. These residual connections not only facilitate learning in a network with a few layers but also in a much deeper network, since they enable gradients to propagate more easily through the layers. With high classification accuracy, ResNet101 has a modest computational requirement and, therefore, has become a prevalent choice in image classification tasks.

Introduced in ResNet101, residual learning brings a substantial innovation to standard convolutional neural networks. When building CNNs, practitioners usually try to limit network depth because going too deep tends to cause a performance decrease; for example, adding more layers to a traditional CNN usually leads to worse performance. But this degradation doesn't stem from overfitting and isn't ameliorated by regularization or dropout. By substantially overcoming the problem of going too deep, residual learning shows that depth itself can be a key variable for improving performance. Residual learning also leads to better performance per unit depth, as ResNet101 is far more accurate than traditional CNNs of similar depth.

#### 4.2.4 DenseNet121

DenseNet121 (Huang et al., 2017) is a family of neural network architectures that has shaken things up a bit in the image classification world of late. Their design pattern is quite straightforward: At the core of a DenseNet lies a series of convolutional operations (in 2D or 3D depending on the application) interspersed with batch normalization layers and non-linear activation functions. This densely connected approach results in state-of-the-art performance on image classification tasks with fewer parameters compared to traditional convolutional DenseNet121 improves gradient flow, networks. parameter efficiency, feature reuse, and mitigates vanishing gradient problems, leading to a more compact and efficient network that outperforms many traditional CNNs.

#### 4.2.5 VGG16

VGG16 (Simonyan and Zisserman, 2014) is a deep convolutional neural network model with 16 weight layers. This model is impressive for its simplicity and its depth, using small  $3 \times 3$  convolutional filters stacked on top of each other. The architecture of VGG16 is amazing; it trades off the number of parameters for depth and is universally applied. It achieves state-of-the-art results on the ImageNet dataset and is known for its performance. Nevertheless, VGG16's design is inefficient. There are tradeoffs involved in achieving depth versus the number of parameters; however, using more parameters than necessary doesn't make VGG16 more effective. Its deployment on hardware is costly, which limits its scalability. More recent models, like ResNet, DenseNet, and MobileNet, achieve network depth more efficiently and with fewer parameters.

#### 4.2.6 Ensemble Model

An ensemble model (Dietterich, 2000) combines several distinct models to create a single, stronger model that outperforms any individual model. Ensembling takes advantage of the fact that models can have very different strengths and weaknesses and, when combined, can achieve greater accuracy if the individual models do not all make the same mistakes. The easiest way to ensemble models is to average their predictions, which bootstrap aggregating does. A more exciting way to ensemble models is to use them in a sequence, which "boosting" does. When we use the term ensemble model in the context of deep learning, we almost always mean a very large model that has been pretrained on a very large dataset.

Combining the predictions of several basic models through a meta-model produces the final output in stacking. Ensemble methods are especially effective in chopping down variations and biases, and in boosting prediction accuracy. Compared to single models, ensemble models offer several key advantages, mostly due to what might be called their model strength combination and individual model weakness mitigation. These advantages make them a potent machine learning tool for achieving high prediction performance with a reliable model.

## 4.3 Training Hyperparameters and Implementation Details

The parameters for the machine learning model were configured as follows: the input images were down-sampled to  $64 \times 64$ , the batch size was set to 4, and the Adam optimizer was used for a maximum of 500 epochs. The loss function was binary cross-entropy combined with Dice loss. The details of these hyper-parameters are presented in Table 2.

Python, specifically Python 3 (Ketkar and Ketkar, 2017), was used to implement the model training. The Keras deep learning library (Ketkar and Ketkar, 2017) was used to build the neural network models, with TensorFlow (Abadi et al., 2016) being used as the back-end for the actual computations.

### 4.4 Evaluation Metrics

In this study, we assessed our convolutional neural network models for standard classification tasks. We used several standard metrics to do the math. The metrics have simple arithmetic involved, and all rely on a few key numbers that involve the correct classification of positive and negative cases (true positives, TP, and true negatives, TN) and the misclassification of negative and positive cases (false positives, FP, and false negatives, FN) (Goodfellow et al., 2016). These are the metrics we used:

• Accuracy: In deep learning, accuracy is a performance metric that measures the proportion of correctly predicted instances out of the total instances in a dataset. This metric provides a straightforward way to evaluate the effectiveness of a model, especially in balanced datasets. It is calculated using Equation 1:

Accuracy = 
$$\frac{TP + TN}{TP + TN + FP + FN}$$
. (1)

• Precision: precision is a performance metric that measures the proportion of true positive predictions among all positive predictions made by the model. It is particularly useful in scenarios where the cost of false positives is high, providing insight into the model's accuracy in identifying positive instances correctly. It is calculated using Equation 2:

$$Precision = \frac{TP}{TP + FP}.$$
 (2)

• Recall: (also known as sensitivity or true positive rate) measures the proportion of actual positive instances that the model correctly identifies. Recall is crucial in applications where missing positive instances has a high cost, providing insight into the model's ability to capture all relevant positive cases. It is calculated using Equation 3:

Recall (Sensitivity) = 
$$\frac{TP}{TP + FN}$$
. (3)

• Specificity: (also known as the true negative rate) measures the proportion of actual negative instances that the model correctly identifies. Specificity is particularly important in scenarios where it is crucial to minimize false positives, as it provides insight into the model's accuracy in identifying negative instances correctly. It is calculated using Equation 4:

Specificity 
$$= \frac{TN}{TN + FP}$$
. (4)

• F1-score: It is a performance metric that combines precision and recall into a single measure by calculating their harmonic mean. F1-score is particularly useful for evaluating models on datasets

Model	Key Features
MobileNetV2	A cost-effective model known for its quick training and
	execution.
EfficientNetB0	Offers a good balance between accuracy and computa-
	tional efficiency.
ResNet101	Renowned for its ability to effectively learn deep fea-
	tures and degradation problem when training very deep
	networks.
DenseNet121	Provides several key advantages, including efficiency,
	gradient flow, and parameter usage.
VGG16	A popular model used for its ability to capture complex
	details in images.
Ensemble Model	Combines results from several models to enhance overall
	performance and accuracy.

Table 1: The main characteristics of the models evaluated in this study.

Table 2: The training hyperparameters are applied during the training process.

Hyperparameter	Value				
Loss Function	CrossEntropyLoss				
Learning Rate	0.001				
Weight Decay	0.01				
Number of Epochs	50				
Batch Size	16				
Optimizer	Adam				
Learning Rate Sched-	ReduceLROnPlateau				
uler					
Early Stopping	Patience= 25 epochs				

with imbalanced classes, as it balances the tradeoff between precision and recall. It is given by Equation 5:

$$F1\text{-score} = 2 \times \frac{\text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}}.$$
 (5)

• Area Under the Curve (AUC) and Receiver Operating Characteristic (ROC) curve: AUC refers to the area under the ROC curve, which plots the true positive rate (recall) against the false positive rate at various threshold settings.

### **5 RESULTS AND DISCUSSION**

In this section, we will present the results and analyze them using the six models and evaluation matrix discussed in the previous section. We will then discuss the results and draw a conclusion. Finally, we will suggest potential areas for further research.

## 5.1 Performance of Classification Models

In this section, we provide a comprehensive evaluation of various classification models. Table 3 summarizes the performance of comparator models based on RGB color images. Figure 3 illustrates a comparison of these models' performance using ROC curves. This comparison illustrates how different models can offer various balances between sensitivity and specificity, aiding in making informed decisions about the best models to use in specific applications.

In retinoblastoma classification, MobileNetV2 exhibits perfect sensitivity with zero false negatives, making it valuable for initial screening, but its low specificity of 56.78% results in many false positives, necessitating further evaluation to avoid unnecessary stress for patients. EfficientNetB0, despite its perfect sensitivity, is impractical for clinical use due to its 0% specificity, leading to 100% false positives and a low overall accuracy of 53.40%, likely caused by overfitting and dataset imbalance. ResNet101 stands out with the highest accuracy of 97.42%, high sensitivity of 95.18%, and perfect specificity of 100%, attributed to its residual connections that balance complexity and overfitting, though it requires further validation on diverse datasets. DenseNet121 also shows promise with a high accuracy of 93.68%, sensitivity of 96.49%, and specificity of 90.45%, thanks to its dense layer connectivity that aids in feature reuse and extraction, though additional testing and hyperparameter tuning are needed to confirm its reliability for clinical use.

To sum up, ResNet101 excelled with a perfect balance of sensitivity and specificity, ideal for clinical use. DenseNet121 also performed well, maintaining high sensitivity and specificity, suitable for

CNN Classification	Evaluation Matrix						
Model	Accuracy	Precision	Recall	Specificity	F1-Measure	AUC	
MobileNetV2 (DSandler et al., 2018)	79.86%	72.61%	100%	56.78%	84.13%	0.78	
EfficientNetB0 (Tan and Le, 2019)	53.40%	53.40%	100%	0%	69.62%	0.50	
ResNet101 (He et al., 2016)	97.42%	100%	95.18%	100%	97.53%	0.98	
DenseNet121 (Huang et al., 2017)	93.68%	92.05%	96.49%	90.45%	94.22%	0.93	
VGG16 (Simonyan and Zisserman, 2014)	81.26%	76.24%	94.30%	66.33%	84.31%	0.80	
Ensemble Model (Dietterich, 2000)	88.29%	90.09%	87.72%	88.94%	88.89%	0.88	

Table 3: Analyzing the quantitative performance of different CNN modules based on publicly available datasets.

\* Bold font indicates the best value.



(d) DenseNet121 (e) VGG16 (f) Ensemble Model Figure 3: Mean ROC curve for all classification models.



Figure 4: A representation of the k-fold cross-validation method.



Figure 5: Accuracy plots for comparator models across all k-values during the training and validation process.

critical scenarios. MobileNetV2, with the highest sensitivity but lower specificity, is useful for initial screenings. EfficientNetB0 and VGG16 had specificity issues, making them less suitable for clinical settings but potentially valuable in preliminary diagnostics. The Ensemble Model proved effective, combining multiple models to enhance diagnostic accuracy.

### 5.2 K-Fold Cross Validation

This paper examines the impact of data distribution on validation performance using 5-fold cross-validation. In this approach, the dataset was divided into 5 equal subsets (folds), where each fold served as the validation set once while the remaining folds were used for training. This process was repeated five times, and the results were averaged to provide a robust evaluation of model performance. The analysis highlights how the model generalizes across different subsets of the dataset, ensuring reliability and accuracy while reducing the risk of overfitting.

Figure 4 illustrates the 5-fold cross-validation process, while Figure 5 shows accuracy plots for comparator models across the training and validation sets for each fold. Additionally, Table 4 presents a comparative summary of the performance across all five folds, demonstrating the model's ability to generalize effectively and maximize data utility.

# 6 CONCLUSION

This work examines different deep learning classification models and their performance in detecting retinoplostoma from publicly available datasets. We found that MobileNetV2 demonstrates exceptional sensitivity, making it highly effective at detecting cases of retinoblastoma. However, its low specificity may result in a higher number of false positives. In contrast, EfficientNetB0 achieves perfect sensitivity but lacks specificity entirely, rendering it unsuitable for clinical use without substantial adjustments. To improve EfficientNetB0's performance, strategies such as expanding the training dataset with more normal eve images, employing data augmentation methods, implementing regularization techniques like L1/L2 regularization or dropout, and considering simpler model architectures like MobileNetV2 could be used. These approaches aim to balance sensitivity and specificity, leading to a more reliable retinoblastoma classification system.

ResNet101 emerges as the best overall performer, offering an optimal balance between sensitivity and specificity, thereby making it an ideal candidate for practical applications. Similarly, DenseNet121 strikes a commendable balance between sensitivity and specificity, proving to be a robust choice for scenarios where both accuracy and the minimization of false positives are critical. VGG16, while exhibiting

CNN Classification	K	Evaluation Matrix						
Model		Accuracy	Precision	Recall	Specificity	F1-Measure	AUC	
MobileNetV2 (DSandler et al., 2018)	1	<b>79.86</b> %	72.61%	100%	56.78%	84.13%	0.78	
	2	79.70%	72.54%	99.3%	56.50%	83.8%	0.71	
	3	78.80%	71.84%	98.51%	55.70%	82.46%	0.68	
	4	77.64%	70.64%	97.78%	54.85%	72.96%	0.64	
	5	76.46%	69.74%	96.80%	53.93%	62.88%	0.61	
	Mean	78.49%	71.47%	98.48%	55.55%	77.25%	0.68	
	1	52.86%	52.98%	88.40%	12.58%	69.45%	0.63	
	2	53.10%	53.27%	89.85%	12.95%	69.58%	0.64	
EfficientNetB0 (Ten and Le. 2010)	3	52.40%	53.40%	90%	13%	69.62%	0.65	
EfficientivetB0 (Tail and Le, 2019)	4	52.10%	53.33%	89.98%	12.98%	69.48%	0.62	
	5	51.98%	52.94%	89.88%	12.85%	69.34%	0.61	
	Mean	52.49%	53.18%	89.62%	12.87%	69.49%	0.63	
	1	97.42%	100%	95.18%	100%	97.53%	0.98	
	2	97.35%	99.98%	95.12%	99.97%	97.50%	0.97	
$\mathbf{P}_{ac}\mathbf{N}_{ac}1(1)$ (He at al. 2016)	3	97.02%	99.88%	94.98%	99.87%	97.47%	0.96	
ResNet101 (He et al., 2010)	4	96.98%	99.82%	94.87%	99.81%	97.38%	0.95	
	5	96.87%	98.97%	94.82%	98.96%	97.13%	0.94	
	Mean	97.13%	99.73%	94.99%	99.72%	97.40%	0.96	
	1	92.98%	91.63%	96.19%	90.15%	93.86%	0.89	
	2	93.42%	91.76%	96.28%	90.24%	93.91%	0.90	
DancaNat121 (Huang at al. 2017)	3	93.56%	91.94%	96.35%	90.38%	94.13%	0.91	
Denselvet121 (Huang et al., 2017)	4	93.68%	92.05%	96.49%	90.45%	94.22%	0.93	
	5	93.18%	91.96%	96.36%	90.31%	94.11%	0.92	
	Mean	93.36%	91.87%	96.33%	90.31%	94.05%	0.91	
	1	80.89%	75.84%	93.98%	65.83%	83.98%	0.76	
	2	80.96%	75.97%	94.11%	65.95%	84.11%	0.77	
VGG16 (Simonyan and Zisserman, 2014)	3	81.03%	76.04%	94.20%	66.10%	84.22%	0.78	
	4	81.11%	76.13%	94.26%	66.23%	84.27%	0.79	
	5	81.26%	76.24%	94.30%	66.33%	84.31%	0.80	
	Mean	81.05%	76.04%	94.17%	0.66.09%	84.18%	0.78	
Ensemble Model (Dietterich, 2000)	1	87.97%	98.61%	87.30%	88.56%	88.55%	0.84	
	2	88.03%	98.76%	87.42%	88.67%	88.63%	0.85	
	3	88.18%	98.84%	87.55%	88.77%	88.77%	0.86	
	4	88.20%	98.97%	87.61%	88.86%	88.86%	0.87	
	5	88.29%	90.09%	87.72%	88.94%	88.89%	0.88	
	Mean	88.13%	97.05%	87.52%	88.76%	88.74%	0.86	

Table 4: Summary comparing validation metrics across all k-values.

\* Bold font indicates the best fold value for each models.

good sensitivity, falls short in specificity compared to other models, which diminishes its effectiveness in reducing false alarms. Lastly, the ensemble model provides a well-balanced performance across all metrics, suggesting that integrating multiple model outputs can enhance overall performance and reliability.

However, despite our results, some factors should be taken into account. This research was conducted using only one dataset. The conclusions drawn from this dataset may not be representative of the entire population. In order to ensure the accuracy of the results, further research should be conducted with a larger sample size. Future research could consider expanding data collection to multiple sources or collaborating with other research teams to combine data sets. Moreover, implementing more diverse participant selection processes and increasing recruitment efforts will help ensure a representative sample.

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