

# DeepCellCount: Cell Counting Using Two-Step Deep Learning

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**Abstract:** This paper addresses the problem of segmenting and counting cells in fluorescent microscopy images. Accurate identification and counting of cells is crucial for automated cell annotation processes in biomedical laboratories. To address this, we trained two convolutional neural networks using publicly available high-throughput microscopy cell image sets. One network is trained for cell segmentation and the other for cell counting. Both models are then used in a two-step image analysis process to identify and count the cells in a given image. We evaluated the performance of this method on previously unseen cell images, and our experimental results show that the proposed method achieved an average Mean Absolute Percentage Error (MAPE) as low as 6.82 on the test images with sparsely populated cells. This performance is comparable to that obtained with a more complex CellProfiler software on the same dataset.

## 1 INTRODUCTION

Cell-based experiments involve observing and analyzing the shapes, positions, and quantities of cells (Lu et al., 2023). Cell segmentation and counting are particularly useful in biomedical research, as they allow quantifying cultured cells and measuring the effectiveness of experimental drugs by comparing cell concentrations before and after the drugs are administered. The changes are then estimated using time-lapse microscopy images over some time to analyze drug viability for proceeding experiments. The time-lapse images provide critical information about cell mortality or growth, movement, morphology, and interaction over time.

Cell segmentation helps to separate each cell from the background and define cell boundaries. The counting stage quantifies the segmented cells to determine whether the experimental drug effectively eliminates the diseased cells (Aldughayfiq et al., 2023). Cell counting can be done manually (Kataras et al., 2023) or with automated counters and digital image analysis (Vembadi et al., 2019). However, identifying and counting cells has traditionally been laborious in the biomedical field.

Many methods have been developed for medical image analysis, including CellProfiler (McQuin C, 2018) and deep learning (Liu et al., 2019). CellProfiler is an open-source software that allows biologists

without computer vision or programming training to measure and count cells from thousands of cell images. On the other hand, deep learning enables efficient image segmentation by allowing machines to learn and extract informative features for recognizing object shapes and boundaries in an image (Kugelman et al., 2022). Thus enabling the localization and segmentation of objects in images. This development can alleviate the manual and time-consuming process of identifying cells from medical images (Liu et al., 2019).

Inspired by the success of the deep learning-based image analysis method in related applications, we explore the U-Net-like model as an alternative approach to perform pixel-based cell segmentation and count the segmented cells. We train the models for segmenting and counting using a publicly available dataset, and we apply the trained models to perform experimental prediction on an actual fluorescent microscopic image obtained in collaboration with Scott Lab at the Department of Translational Hematology and Oncology Cancer Research, Cleveland, USA. For brevity, we will now refer to our proposed approach as Deep Cell Count (DCC). The rest of this paper is organized as follows, Section 2 reviews the related literature while Section 3 describes the dataset preparation and modeling of the DCC. Section 4 discusses the experiments and results, and Section 5 concludes the paper.

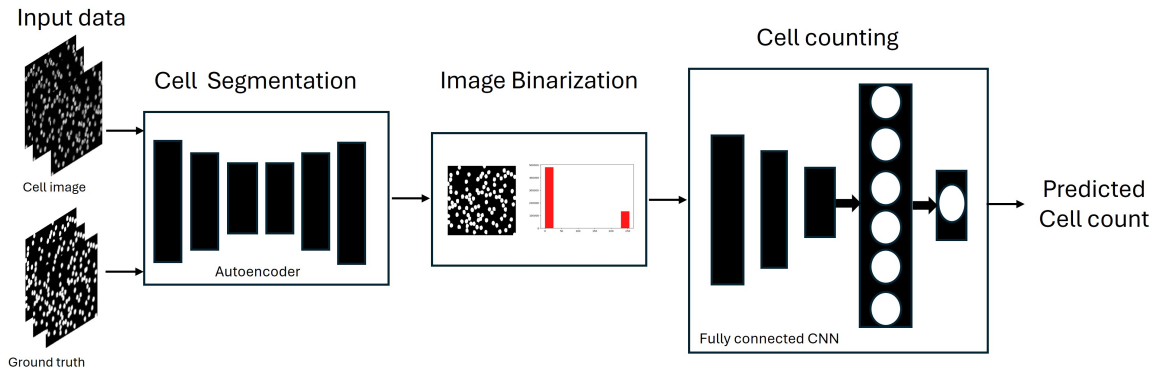


Figure 1: Block diagram of the proposed DCC-based cell counting method.

## 2 RELATED WORK

The following review discusses CNN-based models for cell segmentation and counting. For example, Zhang et al. (2021) created a modified U-Net-like structure to segment malignant brain tumor cells in microscopic images. They utilized distance transform and watershed segmentation for cell counting and confirmed the effectiveness of the U-Net model. Liu et al. (2019) utilized deep CNN models for cell counting using dot density maps and foreground mask methods, demonstrating that the ensemble method for feature extraction produced superior results. Similarly, Hernández et al. (2018) employed Feature Pyramid Networks (FPN) for cell segmentation to capture object structures at various scales within an image. They then used a Visual Geometry Group (VGG) network to count cells and determine aleatoric uncertainty from the segmentation results. Conversely, Li and Shen (2022) argued that deep network layers tend to underperform due to information loss in image segmentation models. The information loss issue in image segmentation when using max-pooling in an autoencoder model was also studied by de Souza Brito et al. (2021).

To address these concerns, our proposed DCC method for cell segmentation employs a lightweight U-Net-like autoencoder CNN model. We use the group normalization method to enhance our model’s generalizability across different image datasets, preventing potential information loss and obtaining a more adaptable model in the segmentation process. We then perform thresholding on the segmented cell images to improve cell identification and develop a fully connected CNN regressor to count the segmented cells. The CNN regressor counting is an experimental technique we explore to test the feasibility of the regression-based method and its performance on cell counting tasks.

## 3 METHODOLOGY

The DCC method described in this paper involves a three-step workflow. First, the cells in the input images are localized through cell segmentation. Next, the quality of the segmented cell images is improved through image thresholding. Finally, a deep regressor model counts the number of observed cells in the thresholded image. Figure 1 shows the schematic diagram of the proposed method. Subsequent sections discuss the preparation of the input cell images, the segmentation, and the counting modeling process.

### 3.1 Cell Image Preparation

To train the DCC cell segmentation and counting model, we utilized the annotated biological image dataset detailed in Section 4.1. We chose this dataset because it is the largest publicly available cell image database for evaluating algorithms in this field. The dataset is valuable as it provides ground truth for validating our proposed method.

We convert the images to grayscale and resize them to 784x784 to ensure symmetry and divide them into training, validation, and test sets in a 70%, 20%, and 10% ratio, respectively. To augment the training data, we implemented a blurring method using OpenCV blur with a 5x5 window and added Gaussian noise to create unique variations of the training data. The purpose of altering the input images is to enhance the model’s ability to extract informative features from images of varying quality and characteristics (Shorten and Khoshgoftaar, 2019). Figure 2 displays a sample of the cell image and its corresponding mask. The following section used these prepared images as input to train the DCC cell segmentation and counting model.

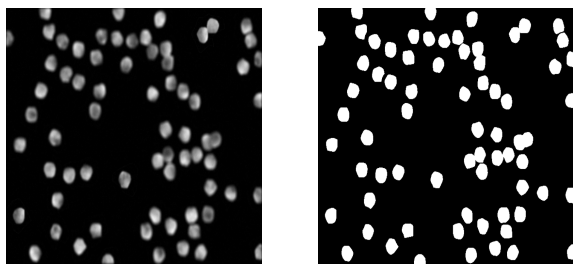


Figure 2: A sample of the dataset used in our work; cell image (left) and corresponding mask (right) image.

### 3.2 DCC Modelling

In the development of the DCC model, we utilized a two-stage approach involving the implementation of a convolutional neural network (CNN). The first stage focused on cell segmentation, where we constructed a CNN to identify and delineate individual cells within an image. Subsequently, in the second stage, we trained a downstream CNN regressor using the segmented image as input to predict the cell counts through regression analysis.

For the segmentation stage, we employed a model architecture following an encoder-decoder paradigm (Oğuz and Ömer Faruk Ertuğrul, 2023). Specifically, we utilized a lightweight U-Net-like model consisting of three encoder and three decoder layers (Ronneberger et al., 2015). The encoder section of the model comprised three convolutional layers with kernel sizes of 64, 128, and 256, each utilizing a (3x3) kernel and rectifying linear unit activation layers. To normalize the output of the convolutional layers, we applied group normalization. This approach was chosen to address potential errors arising from utilizing a small batch size (4 images per batch) in the encoder-decoder model (Wu and He, 2018). The encoded image was then decoded using three expansion convolutional layers with (3x3) kernel size. A sigmoid activation function was employed for the final output to provide the probability of each pixel representing a cell. To classify pixels as cell or non-cell, we utilized different thresholding methods on the outputted probability to compensate for our experimental images' different image quality and cell count density. These thresholding methods include Simple, Adaptive Gaussian, and Otsu techniques. Simple (binary) thresholding uses a global cut-off of 0.5. In contrast, Adaptive Gaussian thresholding computes the cut-off value by taking the Gaussian-weighted average of the probabilities within a block of pixels. Otsu's thresholding method calculates the cut-off value that maximizes the separation of the foreground and the background from the pixels of the image intensity histogram.

In the counting stage, the second CNN model utilized the thresholded mask produced by the encoder-decoder model as input. This model performed two 3x3 convolutions with Rectified Linear Unit (ReLU) activation and max pooling in between. The resultant output was flattened into a vector and fed into a dense layer featuring 512 neurons. The final output of this stage was the regression count of the cells in the input image. The weights of both the encoder-decoder and counting models were optimized using the Adam optimizer with a learning rate of 0.0001, as this is shown to give superior performance in terms of accuracy (Dogo et al., 2022).

## 4 EXPERIMENTATION AND DISCUSSION

### 4.1 Dataset

We utilized two sets of datasets for our experimentation. The first one is the publicly available Broad Institute's Bioimage Benchmark Collection annotated biological image sets (BBBC005Version 1)<sup>1</sup>. The dataset comprises 19200 images and 1200 ground truth masks, with 9600 containing an actual cell count. We worked with the 1200 images with ground truth masks for the segmentation tasks. To train the counting model, we selected 595 images with ground truth masks and actual counts to assess the segmentation and counting performances of the DCC method.

The second dataset was obtained in collaboration with Scott Lab at the Department of Translational Hematology and Oncology Cancer Research, Cleveland, USA. These image samples contain densely populated cells and two distinct cell types labeled with Green Fluorescence Protein (GFP) and mCherry. We only used this dataset to evaluate the proposed DCC model's effectiveness on previously unseen cell images. We used a subset of these images to assess the DCC and compared the counting results with those obtained using CellProfiler software (McQuin C, 2018).

### 4.2 Experimental Setup

We utilized the open-source OpenCV and machine learning libraries to facilitate the image processing and training of the DCC model. These were all hosted on the Google Colaboratory cloud computing platform (Bisong, 2019). We evaluate the proposed DCC

<sup>1</sup><https://bbbc.broadinstitute.org/BBBC005/>

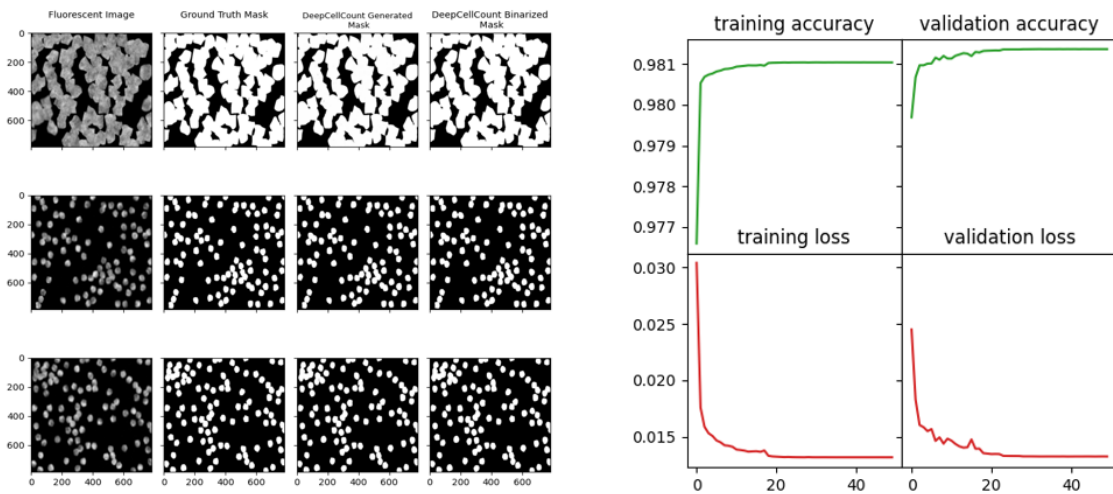


Figure 3: Performances of the DCC model on training and validation data. Left: The outputs of the segmentation model compared with the ground truth. Right: The training and validation accuracy and loss.

using the dataset described in Section 4.1. Throughout the experiments, we employ cross-validation to select the optimal learning rate and batch size for training the CNN. We assess the performance of the DCC on the test data by comparing the actual cell count with the count predicted by the DCC and computing the Mean Absolute Percentage Error (MAPE) of the predictions. We compute the MAPE as follows (Tashman, 2000).

$$MAPE = \frac{\sum_i^K \frac{|y_i - \hat{y}_i|}{y_i}}{K} * 100$$

where  $y_i$  represents the expected cell count value,  $\hat{y}_i$  represents the DCC predicted count value, and  $K$  is the size of the evaluation set. Additionally, we examined how different thresholding processes on the segmented cells impacted the cell count predicted by the DCC. The DCC results were also compared with those of the CellProfiler software. We discuss the results of our experimentation in the next section.

### 4.3 Discussion of Results

Figure 3 displays the accuracy and loss values during the training of the segmentation model and a qualitative comparison of the segmented cells. The segmentation model of the DCC achieved an accuracy of 98% on both the training and validation data.

We used the ground-truth mask from the first dataset discussed in section 4.1 and our DCC-generated segmented cell images as inputs to evaluate the cell counting model’s performance. Figure 4 compares the DCC cell counting model’s performance segmented cell images (with and without

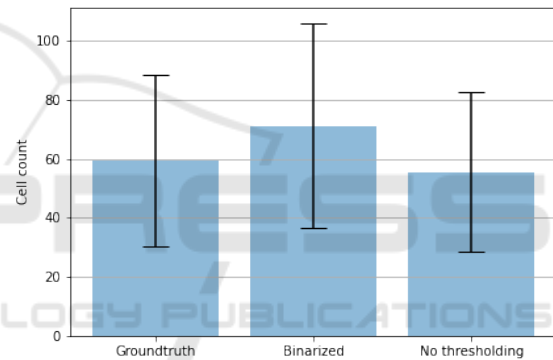


Figure 4: Comparison of the prediction of the DCC model (with and without binary (simple) thresholding of the segmented cell images) with the ground truth. The bars show the average cell count over the entire test dataset.

thresholding) with the original cell counts on the test set. The proposed DCC model achieved MAPE of 6.82 and 19.65, respectively, confirming its comparatively good accuracy for cell segmentation and counting in cell-based biomedical research. The results also show the importance of thresholding the segmented cell images before counting the cells in them.

We experiment with test images obtained from cancer research centers (second dataset in Section 4.1) that are dissimilar to the ones used in the training of our DCC model to assess its robustness. We aimed to evaluate the model’s performance on densely populated cell images and the impact of different thresholding methods, including simple, adaptive, and Otsu, on the cell count. Figure 5 presents a qualitative comparison of the cell segmentation on the test images using the proposed DCC method and CellProfiler software, demonstrating effective segmentation by the



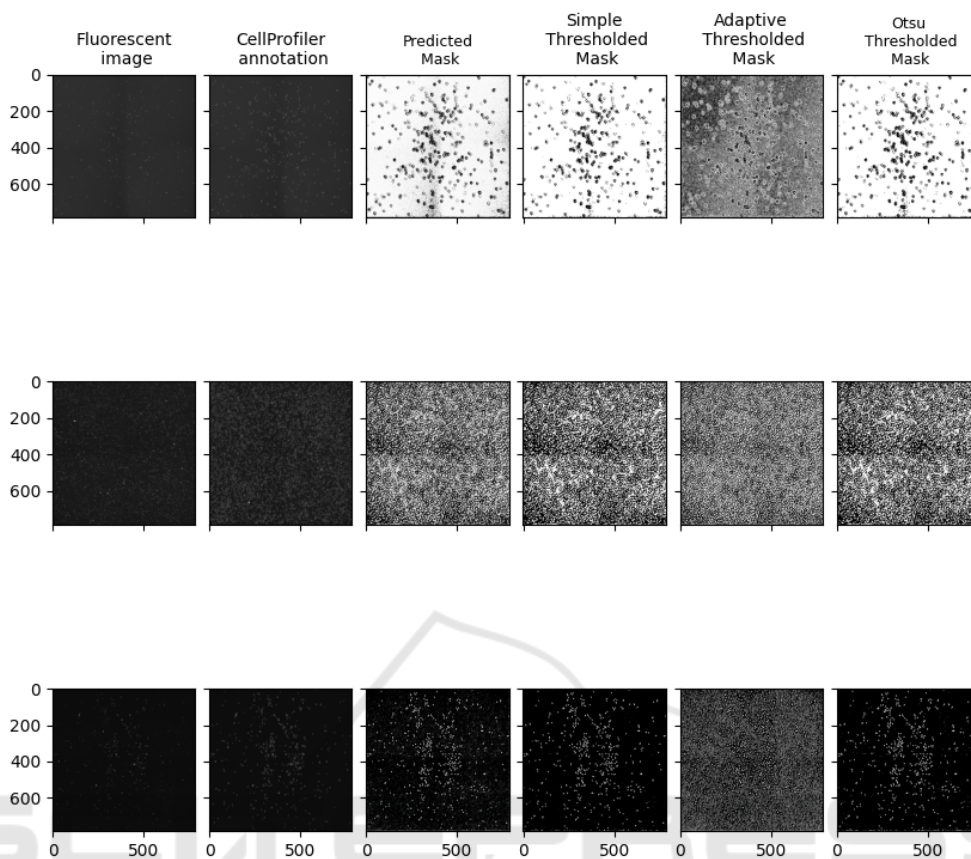


Figure 5: Comparing the performance of the DCC cell image segmentation approach, which utilizes three different thresholding methods, to that of the CellProfiler software. Each row presents the results for a single test fluorescent cell image. The figure shows that the DCC approach, combined with the thresholding methods, achieves clearer cell segmentation than that produced by the CellProfiler software.

DCC approach. Additionally, Figure 6 compares the cell counting performance of the DCC approach on densely populated cell images with the three thresholding methods applied to the segmented cell images before counting. The DCC model with the adaptive thresholding method performed the best, with an average MAPE of 36.29, while the DCC without thresholding gave the worst performance, with an average MAPE of 56.30 on the test set with 600 to 700 cells per image.

The DCC model works well for images with fewer cells (around 600), showing an average MAPE of 6.82. However, it struggles with densely populated images, where the MAPE jumps to 36.29. This drop in performance is partly due to the model being trained mainly on images with sparsely populated cells, making it less effective when faced with more crowded ones. This situation highlights the need for diverse training datasets to ensure models perform well in different scenarios.

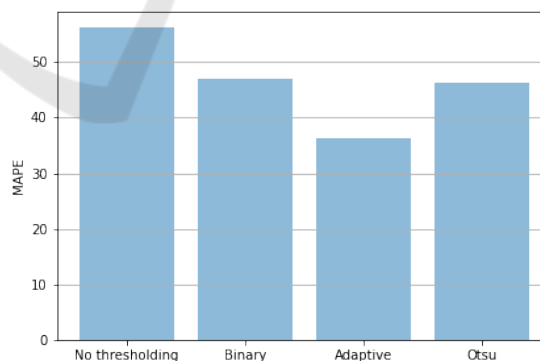


Figure 6: Performance of the DCC on the cell counting using densely populated cell images for different thresholding methods.

## 5 CONCLUSION

Our project aimed to develop models to segment and count cells in fluorescent cell images accurately. We accomplished this by using a two-step process. First,

we employed a simple U-Net-like encoder-decoder model to segment cells from the images. Then, we trained another CNN regressor to count the cells in the segmented images. We experimented with the use of CNN regressor for cell counting and showed that a regression-based counter can perform well. We evaluated the performance of our proposed DCC model on publicly available cell image datasets and found that it achieved an average MAPE of 6.82 on the test set.

Additionally, we tested the DCC model on cell images with densely populated cells acquired from a cancer research laboratory. We show that the DCC model achieved an average MAPE of 36.29 with adaptive thresholding techniques applied to the segmented cell images. Visual results comparing the output of our proposed DCC model with that of CellProfiler software demonstrated that the DCC model can effectively segment cells compared to the more complex tool. We observed that the DCC model performs best when the segmented cell image mask is thresholded using the adaptive thresholding method and when the mask contains sparsely distributed cells.

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